**Instruction Manual**
PN 51-5081C/rev.E
November 2012

# Model 5081-C

## Two-Wire Conductivity Transmitter



ROSEMOUNT®
Analytical

EMERSON™
Process Management

# ESSENTIAL INSTRUCTIONS

## READ THIS PAGE BEFORE PROCEEDING!

Rosemount Analytical designs, manufactures, and tests its products to meet many national and international standards. Because these instruments are sophisticated technical products, you must properly install, use, and maintain them to ensure they continue to operate within their normal specifications. The following instructions must be adhered to and integrated into your safety program when installing, using, and maintaining Rosemount Analytical products. Failure to follow the proper instructions may cause any one of the following situations to occur: Loss of life; personal injury; property damage; damage to this instrument; and warranty invalidation.

- Read all instructions prior to installing, operating, and servicing the product. if this instruction Manual is not the correct manual, telephone 1-800-654-7768 and the requested manual will be provided. Save this instruction Manual for future reference.
- if you do not understand any of the instructions, contact your Rosemount representative for clarification.
- Follow all warnings, cautions, and instructions marked on and supplied with the product.
- inform and educate your personnel in the proper installation, operation, and maintenance of the product.
- install your equipment as specified in the installation instructions of the appropriate instruction Manual and per applicable local and national codes. Connect all products to the proper electrical and pressure sources.
- To ensure proper performance, use qualified personnel to install, operate, update, program, and maintain the product.
- When replacement parts are required, ensure that qualified people use replacement parts specified by Rosemount. u nauthorized parts and procedures can affect the product's performance and place the safe operation of your process at risk. Look alike substitutions may result in fire, electrical hazards, or improper operation.
- Ensure that all equipment doors are closed and protective covers are in place, except when maintenance is being performed by qualified persons, to prevent electrical shock and personal injury.

## CAUTION

if a 375 or 475 u niversal Hart® Communicator is used with these transmitters, the software within the 375 or 475 may require modification. if a software modification is required, please contact your local Emerson Process Management Service Group or National Response Center at 1-800-654-7768.

# About This Document

This manual contains instructions for installation and operation of the Model 5081-C Two-Wire Conductivity Transmitter. The following list provides notes concerning all revisions of this document.

| Rev. Level | Date | Notes |
|---|---|---|
| A | 10/04 | This is the initial release of the product manual. The manual has been reformatted to reflect the Emerson documentation style and updated to reflect any changes in the product offering. This manual contains information on HART Smart and Fo u Nd ATio N Fieldbus versions of 5081-C. |
| B | 2/05 | Revised dwg 1400204 on page 29. |
| C | 5/05 | Fixed LEd font problems on pages 4, 34, 38, 39, 43. |
| d | 1/11 | u pdated enclosure specifications pg 2, dnv logo and © info. |
| E | 11/12 | Added Fieldbus specifications, updated iTK revision and CE certifications |

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EMERSON Process Management

# MODEL 5081-C
# TwO-wIRE TRANSMITTER

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# SECTION 1.0
# DESCRIPTION AND SPECIFICATIONS

- CHo iCE o F Co MMu NiCATio N PRo To Co L: HART® or Fo u Nd ATio N Fieldbus.
- LARGE, EASY-To -REAd two-line display shows the process measurement and temperature.
- SiMPLE MENu STRu CTu RE.
- Ro Bu ST NEMA 4X ENCLo Su RE.
- iNTRiNSiCALLY SAFE d ESiGN allows the transmitter to be used in hazardous environments (with appropriate safety barriers).
- No N-Vo LATiLE MEMo RY retains program settings and calibration data during power failures.
- MEASu RES Co Nd u CTiViTY, RESiSTiViTY, o R Cu STo M Cu RVE VARiABLE.
- Au To MATiC TC RECo GNiTio N simplifies start up.
- Au To MATiC/MANu AL TEMPERATu RE Co MPENSATio N ensures accurate monitoring and control.
- Au To MATiC Co MPENSATio N Fo R SENSo R CABLE RESiSTANCE improves accuracy of high conductivity/ low resistivity measurements.
- Bu iLT-iN TEMPERATu RE Co MPENSATio N ALGo RiTHMS include straight slope, ultra-pure water, cation conductivity, and no compensation.

## 1.1 FEATURES AND APPLICATIONS

The Model 5081-C can be used to measure conductivity in a variety of process liquids. The 5081 is compatible with most Rosemount Analytical sensors. See the Specifications section for details.

The transmitter has a rugged, weatherproof, corrosion-resistant enclosure (NEMA 4X and iP65) of epoxy-painted aluminum. The enclosure also meets explosion-proof standards.

The transmitter has a two-line seven-segment display. The main measurement appears in 0.8-inch (20 mm) high numerals. The secondary measurement, temperature (and pH if free chlorine is being measured), appears in 0.3-inch (7 mm) high digits.

Two digital communication protocols are available: HART (model option -HT) and Fo u Nd ATio N Fieldbus (model option -FF). d igital communications allows access to AMS (Asset Management Solutions). u se AMS to set up and configure the transmitter, read process variables, and troubleshoot problems from a personal computer or host anywhere in the plant.

A handheld infrared remote controller or the HART and Fo u Nd ATio N Fieldbus Model 375 communicator can also be used for programming and calibrating the transmitter. The remote controller works from as far away as six feet.

Housed in a rugged NEMA 4X case, the 5081C measures conductivity or resistivity in the harshest environments. Transmitter can also be configured, using the "Custom Curve" feature, to measure ppm, %, or a no unit variable according to a programmable conductivity vs. variable curve. The transmitter will automatically recognize the type of RTd (Pt100 or Pt1000) being used. Measurements are automatically corrected for the resistance of the sensor cable to improve accuracy of high conductivity readings. The 5081C provides several temperature compensation algorithms to ensure optimal performance: linear slope, ultra-pure water (neutral salt), or cation conductivity. Alternatively, temperature compensation feature can be turned off to provide display of raw conductivity.

## 1.2 SPECIFICATIONS

### 1.2.1 GENERAL SPECIFICATIONS

**Housing:** Cast aluminum with epoxy coating. NEMA 4X (iP65). Neoprene o-ring cover seals.

**Dimensions:** 160.5 mm x 175.3 mm x 161.3 mm (6.3 in. x 6.9 in. x 6.4 in.) See drawing.

**Conduit Openings:** ¾-in. FNPT

**Ambient Temperature:** -4 to 149°F (-20 to 65°C)

**Storage Temperature:** -22 to 176°F (-30 to 80°C)

**Relative Humidity:** 0 to 95% (non-condensing)

**weight/Shipping weight:** 10 lb/10 lb (4.5/5.0 kg)

**Display:** Two-line LCd; first line shows process variable (pH, oRP, conductivity, % concentration, oxygen, ozone, or chlorine), second line shows process temperature and output current. For pH/chlorine combination, the second line can be toggled to show pH. Fault and warning messages, when triggered, alternate with temperature and output readings.

First line: 7 segment LCd, 0.8 in. (20 mm) high.

Second line: 7 segment LCd, 0.3 in. (7mm) high.

display board can be rotated 90 degrees clockwise or counterclockwise.

during calibration and programming, messages and prompts appear in the second line.

**Temperature resolution:** 0.1°C

**Hazardous Location Approval:** For details, see specifications for the measurement of interest.

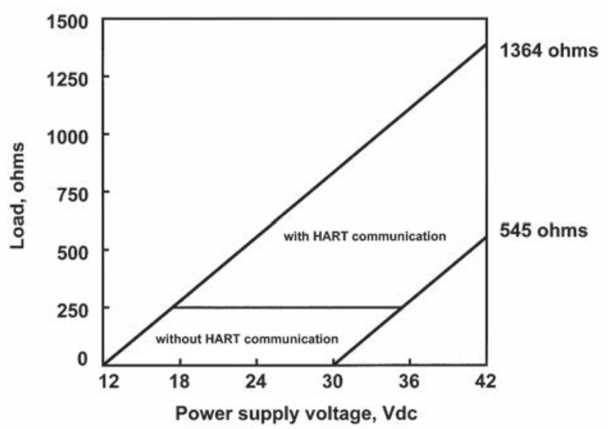
**RFI/EMI:** EN-61326 CE

**Digital Communications:**

**HART —**
**Power & Load Requirements:**
Supply voltage at the transmitter terminals should be at least 12 Vdc. Power supply voltage should cover the voltage drop on the cable plus the external load resistor required for HART communications (250 Ω minimum). Minimum power supply voltage is 12 Vdc. Maximum power supply voltage is 42.4 Vdc (30 Vdc for intrinsically safe operation). The graph shows the supply voltage required to maintain 12 Vdc (upper line) and 30 Vdc (lower line) at the transmitter terminals when the current is 22 mA.

**Analog Output:** Two-wire, 4-20 mA output with superimposed HART digital signal. Fully scalable over the operating range of the sensor.

**Output accuracy:** ±0.05 mA



HART option

**FOUNDATION FIELDBUS —**

**Power & Load Requirements:** A power supply voltage of 9-32 Vdc at 22 mA is required.

### 1.2.2 FUNCTIONAL SPECIFICATIONS

**Calibration:** Calibration is easily accomplished by immersing the sensor in a known solution and entering its value or entering the cell constant for ultra pure applications.

**Automatic Temperature Compensation:**
3-wire Pt 100 or Pt 1000 RTd
Conductivity: 0 to 200°C (32 to 392°F)
Resistivity: 0 to 100°C (32 to 212°F)
Low Conductivity: 0 to 100°C (32 to 212°F)

**Diagnostics:** The internal diagnostics can detect:

| | |
|---|---|
| Calibration Error | Zero Error |
| Temperature Slope Error | Low Temperature Error |
| High Temperature Error | Sensor Failure |
| Line Failure | CPu Failure |
| RoM Failure | input Warning |

once one of the above is diagnosed, the LCd will display a message describing the failure/default detected.

**Digital Communications:**

**HART:** PV, SV, and TV assignable to measurement (conductivity, resistivity, or concentration), temperature, and raw conductivity. Raw conductivity is measured conductivity before temperature correction.

**Fieldbus:** Three Ai blocks assignable to measurement (conductivity, resistivity, or concentration), temperature, and raw conductivity. Raw conductivity is measured conductivity before temperature correction.

### 1.2.3 TRANSMITTER SPECIFICATIONS @ 25°C

**Measured Range:** 0-20,000 µS/cm

**Accuracy:** ± 0.5% of reading and ± 0.001 µS/cm

**Repeatability:** ± 0.25% of reading

**Stability:** 0.25% of output range/month, non-cumulative

**Ambient Temperature Coefficient:**
± 0.05% of reading/°C

**Temperature Slope Adjustment:** 0-5%/°C

o ther temperature compensation algorithms: ultra-pure water compensation, cation conductivity, or raw (uncompensated) conductivity.

**Compatible RTD:** 100Ω or 1000Ω with Automatic Recognition

### 1.2.4 LOOP SPECIFICATIONS

**Accuracy:** under controlled laboratory conditions at 25°C (77°F) with perfectly calibrated ENd u RANCE sensor of appropriate cell constant:

**up to 5,000 µS/cm:** ± 1.0% and ± 2 least significant digit

**from 5,000 to 20,000:** ± 2% of reading and ± 2 least significant digit

### 1.2.5 SENSOR SELECTION GUIDELINES

| Cell Constant | Suggested Conductivity Range |
|---|---|
| 0.01/cm | up to 50 µS/cm |
| 0.1/cm | 1.0 to 500 µS/cm |
| 1.0/cm | 10 to 20,000 µS/cm |

***Note:*** *The conductivity values shown in the above chart are for UNCOMPENSATED (or RAW) conductivity at 25°C. Maximum range values will vary due to temperature compensation selection, process temperature, and other process conditions.*

**RECOMMENDED SENSORS:**

| | |
|---|---|
| Model 140 | Retractable Conductivity |
| Model 141 | insertion High Conductivity |
| Model 142 | insertion Low Conductivity |
| Model 150 | insertion/Submersion Conductivity |
| Model 400 | Screw-in Low Conductivity |
| Model 400VP | Screw-in Low Conductivity |
| Model 401 | Screw-in High Conductivity |
| Model 402 | Retractable Conductivity |
| Model 402VP | Retractable Conductivity |
| Model 403 | Sanitary Conductivity |
| Model 403VP | Sanitary Conductivity |
| Model 404 | Low Flow Conductivity |

## 1.3 HAzARDOUS LOCATION APPROvAL

**Intrinsic Safety:**

APPROVED

Class i, ii, iii, d iv. 1
Groups A-G
T4 Tamb = 70°C

Exia Entity
Class i, Groups A-d
Class ii, Groups E-G
Class iii
T4 Tamb = 70°C

iECEx BAS 09.0159X
Ex ia iiC T4 Ga

**ATEx**

CE 1180
ii 1 G
Baseefa03ATEX0099
EEx ia iiC T4
Tamb = -20°C to +65°C

**ATEx and IECEx Special Conditions for Use:** The model 5081 enclosure is made of aluminum alloy and is given a protective polyurethane paint finish. However, care should be taken to protect it from impact or abrasion if located in a zone 0 hazardous area.

**Non-Incendive:**

APPROVED

Class i, d iv. 2, Groups A-d
d ust ignition Proof
Class ii & iii, d iv. 1, Groups E-G
NEMA 4X Enclosure

Class i, d iv. 2, Groups A-d
Suitable for
Class ii, d iv. 2, Groups E-G
T4 Tamb = 70°C

**Explosion-Proof:**

APPROVED

Class i, d iv. 1, Groups B-d
Class ii, d iv. 1, Groups E-G
Class iii, d iv. 1

Class i, Groups B-d
Class ii, Groups E-G
Class iii
Tamb = 65°C max

## 1.4 TRANSMITTER DISPLAy DURING CALIBRATION AND PROGRAMMING (FIGURE 1-1)

1. Continuous display of conductivity or resistivity readings.
2. u nits: µS/cm, mS/cm, ppm, or %.
3. Current menu section appears here.
4. Submenus, prompts, and diagnostic readings appear hear.
5. Commands available in each submenu or at each prompt appear here.
6. Hold appears when the transmitter is in hold.
7. Fault appears when the transmitter detects a sensor or instrument fault.
8. © flashes during digital communication.

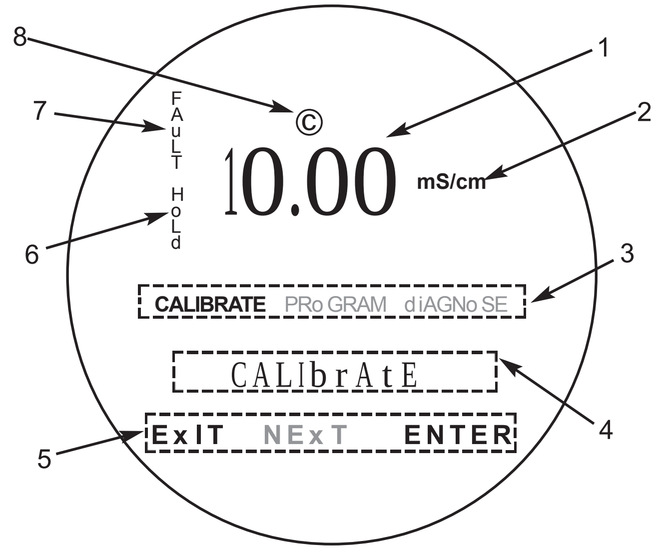



**FIGURE 1-1. TRANSMITTER DISPLAy DURING CALIBRATION AND PROGRAMMING**
The program display screen allows access to calibration and programming menus.

## 1.5 INFRARED REMOTE CONTROLLER (FIGURE 1-2)

1. Pressing a menu key allows the user access to calibrate, program, or diagnostic menus.
2. Press ENTER to store data and settings. Press NEXT to move from one submenu to the next. Press EXiT to leave without storing changes.
3. u se the editing arrow keys to scroll through lists of allowed settings or to change a numerical setting to the desired value.
4. Pressing Ho Ld puts the transmitter in hold and sends the output current to a pre-programmed value. Pressing RESET causes the transmitter to abandon the present menu operation and return to the main display.

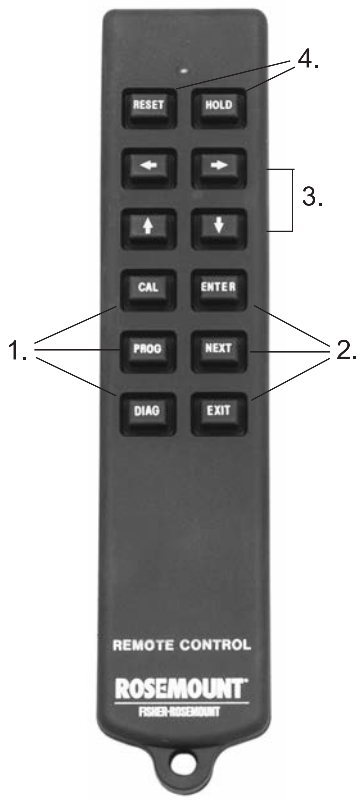



**FIGURE 1-2. INFRARED REMOTE CONTROLLER**

## 1.6 HART COMMUNICATIONS

### 1.6.1 OvERvIEw OF HART COMMUNICATION

HART (highway addressable remote transducer) is a digital communication system in which two frequencies are superimposed on the 4 to 20 mA output signal from the transmitter. A 1200 Hz sine wave represents the digit 1, and a 2400 Hz sine wave represents the digit 0. Because the average value of a sine wave is zero, the digital signal adds no dc component to the analog signal. HART permits digital communication while retaining the analog signal for process control.

The HART protocol, originally developed by Fisher-Rosemount, is now overseen by the independent HART Communication Foundation. The Foundation ensures that all HART devices can communicate with one another. For more information about HART communications, call the HART Communication Foundation at (512) 794-0369. The internet address is *http://www.hartcomm.org*.

### 1.6.2 HART INTERFACE DEvICES

HART communicators allow the user to view measurement data (pH, oRP and temperature), program the transmitter, and download information from the transmitter for transfer to a computer for analysis. downloaded information can also be sent to another HART transmitter. Either a hand-held communicator, such as the Rosemount Model 375, or a computer can be used. HART interface devices operate from any wiring termination point in the 4 - 20 mA loop. A minimum load of 250 ohms must be present between the transmitter and the power supply. See Figure 1-3.

if your communicator does not recognize the Model 5081-C transmitter, the device description library may need updating. Call the manufacturer of your HART communication device for updates.

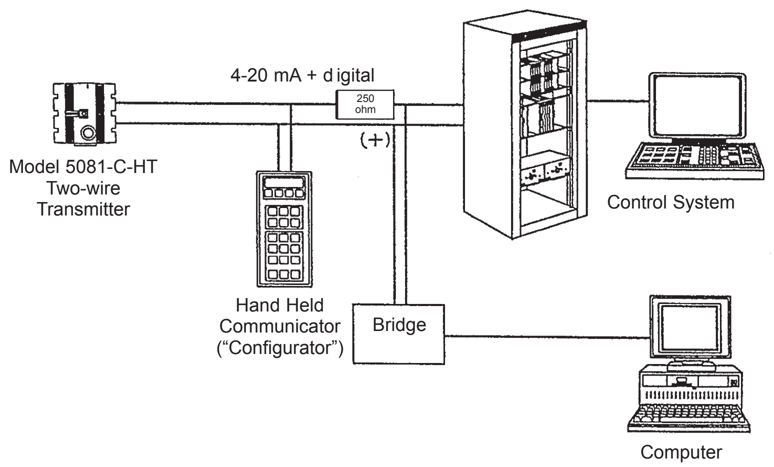



**FIGURE 1-3. HART Communicators.**

Both the Rosemount Model 375 (or 475) and a computer can be used to communicate with a HART transmitter. The 250 ohm load (minimum) must be present between the transmitter and the power supply.

## 1.7 FOUNDATION FIELDBUS

Figure 1-4 shows a 5081-C-FF being used to measure conductivity. The figure also shows three ways in which Fieldbus communication can be used to read process variables and configure the transmitter.

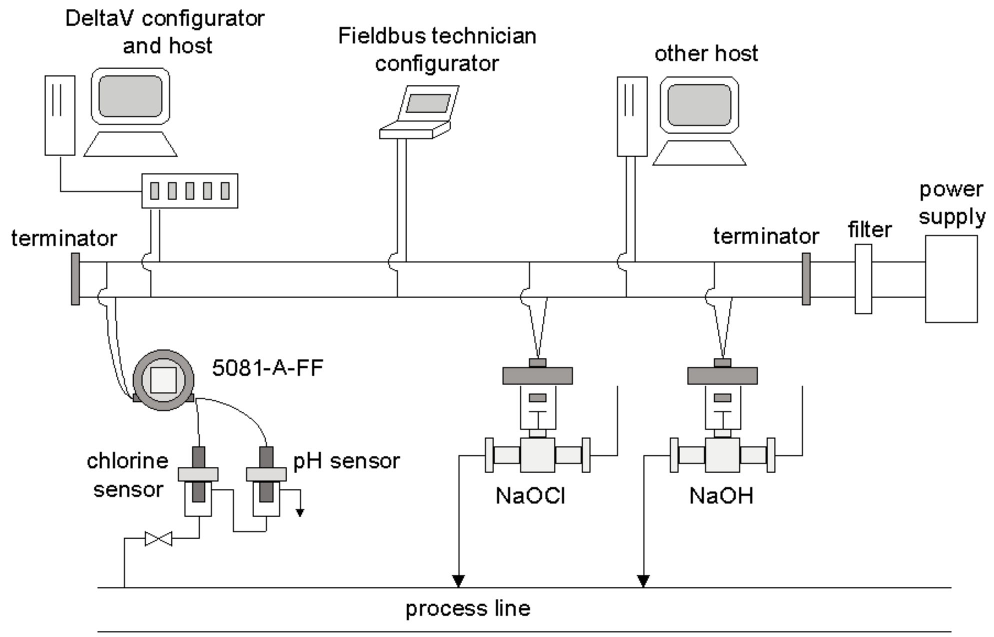



**FIGURE 1-4. CONFIGURING MODEL 5081-C TRANSMITTER wITH FOUNDATION FIELDBUS**

## 1.8 GENERAL SPECIFICATIONS

**Model:** 5081-C-FF Fieldbus Transmitter

**Type:** Contacting Conductivity Transmitter

**Device ITK Profile:** 6 (Released for iTK 6.0.0 / 6.0.1)

**Manufacturer Identification (MANUFAC_ID):** 0x524149

**Device Type (DEv_TyPE):** 0x4084

**Device Revision (DEv_REv):** 0x03

**Linkmaster:** Yes

**Number of Link Objects:** 20

**vCR's supported:** 20

**Mandatory Features:**

- Resource Block
- Alarm and Events
- Function Block Linking
- Trending
- Multi-Bit Alert Reporting
- Field d iagnostics

**Additional Features:**

- Common Software d ownload
- Block instantiation
- Supports d eltaV Auto Commissioning
- Supports d eltaV Auto Replacement
- Supports d eltaV Firmware Live d ownload
- PlantWeb Alerts with re-annunciation / multibit
- Supports Easy Configuration Assistant

**Function Blocks (Execution Time):**

- 4 – Analog input Blocks (15 mseconds)
- Ai Block Channels:
  - Channel 1: Conductivity, Resistivity, Concentration
  - Channel 2: Temperature
  - Channel 3: Raw Conductivity
- Proportional integral d erivative (25 mseconds)

**Power:**

- Two Wire d evice; Fieldbus Polarity insensitive
- Current d raw: 21 mA
- d evice Certifications: iS / FiSCo
- Maximum certified input Voltage for iS: 30V
- Maximum certified input current for iS: 300mA
- Maximum certified input power for iS: 1.3W
- internal Capacitance (Ci): 0 nF
- internal inductance (Li): 0 µH

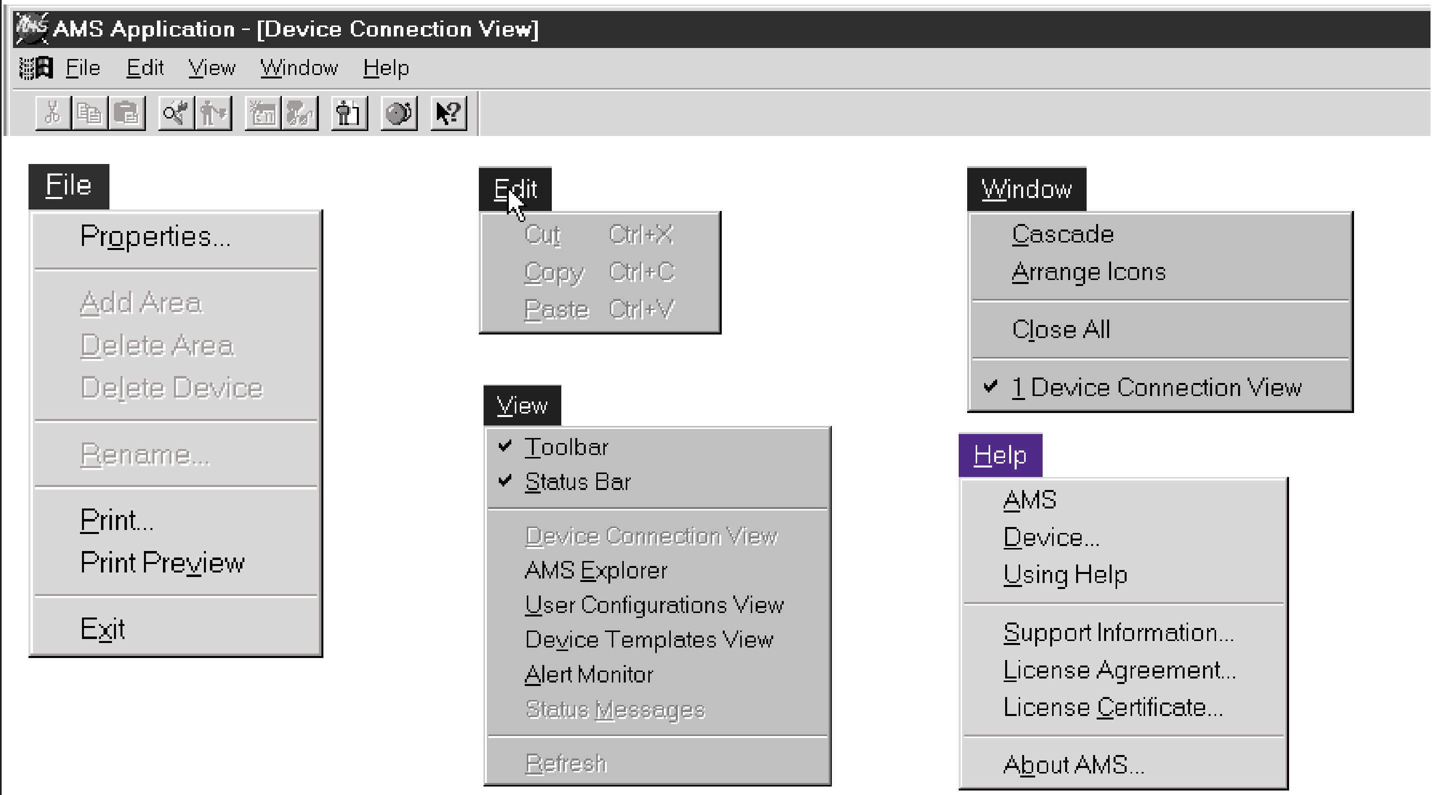



**FIGURE 1-5. AMS MAIN MENU TOOLS**

## 1.9 ASSET MANAGEMENT SOLUTIONS

Asset Management Solutions (AMS) is software that helps plant personnel better monitor the performance of analytical instruments, pressure and temperature transmitters, and control valves. Continuous monitoring means maintenance personnel can anticipate equipment failures and plan preventative measures before costly breakdown maintenance is required.

AMS uses remote monitoring. The operator, sitting at a computer, can view measurement data, change program settings, read diagnostic and warning messages, and retrieve historical data from any HART-compatible device, including the Model 5081-C transmitter. Although AMS allows access to the basic functions of any HART compatible device, Rosemount Analytical has developed additional software for that allows access to all features of the Model 5081-C transmitter.

AMS can play a central role in plant quality assurance and quality control. u sing AMS Audit Trail, plant operators can track calibration frequency and results as well as warnings and diagnostic messages. The information is available to Audit Trail whether calibrations were done using the infrared remote controller, the Model 375 HART communicator, or AMS software.

AMS operates in Windows 95. See Figure 1-5 for a sample screen. AMS communicates through a HART-compatible modem with any HART transmitters, including those from other manufacturers. AMS is also compatible with Fo u Nd ATio N| Fieldbus, which allows future upgrades to Fieldbus instruments.

Rosemount Analytical AMS windows provide access to all transmitter measurement and configuration variables. The user can read raw data, final data, and program settings and can reconfigure the transmitter from anywhere in the plant. Figures 1-6 and 1-7 show two of the many configuration and measurement screens available using HART AMS. Figure 1-8 shows a configuration screen available through AMS inside using Fo u Nd ATio N Fieldbus.

# SECTION 2.0
# INSTALLATION



## 2.1 UNPACKING AND INSPECTION

inspect the shipping container. if it is damaged, contact the shipper immediately for instructions. Save the box. if there is no apparent damage, remove the transmitter. Be sure all items shown on the packing list are present. if items are missing, immediately notify Rosemount Analytical.

Save the shipping container and packaging. They can be reused if it is later necessary to return the transmitter to the factory.

## 2.2 ORIENTING THE DISPLAy BOARD

The display board can be rotated 90 degrees, clockwise or counterclockwise, from the original position. To reposition the display:

1. Loosen the cover lock nut until the tab disengages from the circuit end cap. u nscrew the cap.
2. Remove the three bolts holding the circuit board stack.
3. Lift and rotate the display board 90 degrees, clockwise or counterclockwise, into the desired position.
4. Position the display board on the stand offs. Replace and tighten the bolts.
5. Replace the circuit end cap.

## 2.3 MECHANICAL INSTALLATION

### 2.3.1 General information

1. The transmitter tolerates harsh environments. For best results, install the transmitter in an area where temperature extremes, vibrations, and electromagnetic and radio frequency interference are minimized or absent.
2. To prevent unintentional exposure of the transmitter circuitry to the plant environment, keep the security lock in place over the circuit end cap. To remove the circuit end cap, loosen the lock nut until the tab disengages from the end cap, then unscrew the cover.
3. The transmitter has two 3/4-inch conduit openings, one on each side of the housing. Run sensor cable through the left side opening (as viewed from the wiring terminal end of the transmitter) and run power wiring through the right side opening.
4. u se weathertight cable glands to keep moisture out of the transmitter.
5. if conduit is used, plug and seal the connections at the transmitter housing to prevent moisture from getting inside the transmitter.

**NOTE**

Moisture accumulating in the transmitter housing can affect the performance of the transmitter and may void the warranty.

6. if the transmitter is installed some distance from the sensor, a remote junction box with preamplifier in the junction box or in the sensor may be necessary. Consult the sensor instruction manual for maximum cable lengths.

### 2.3.2 Mounting on a Flat Surface.

See Figure 2-1.

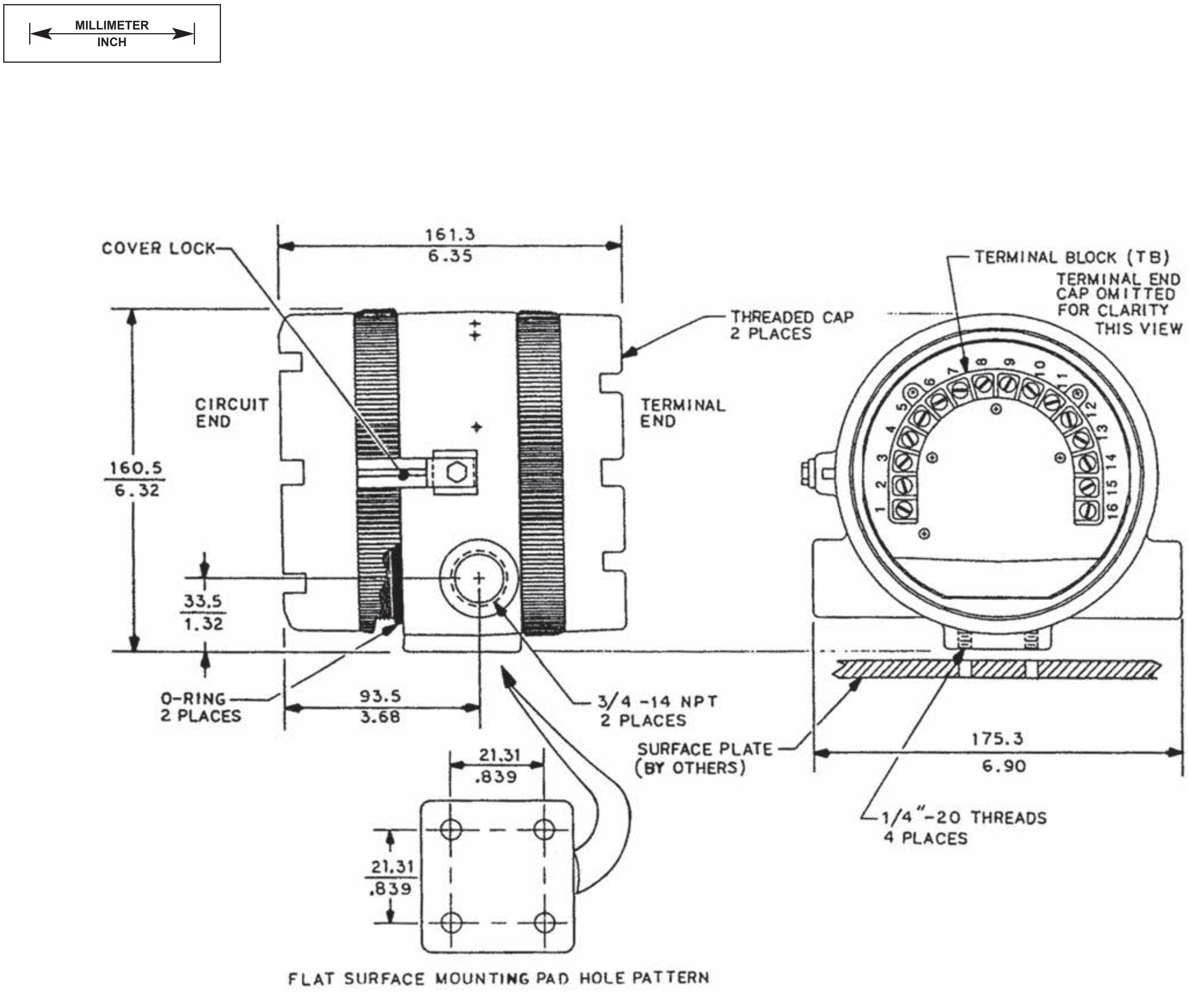



**FIGURE 2-1. Mounting the Model 5081-C Conductivity Transmitter on a Flat Surface**

### 2.3.3 Pipe Mounting.

See Figure 2-2. The pipe mounting kit (PN 2002577) accommodates 1-1/2 to 2 in. pipe.

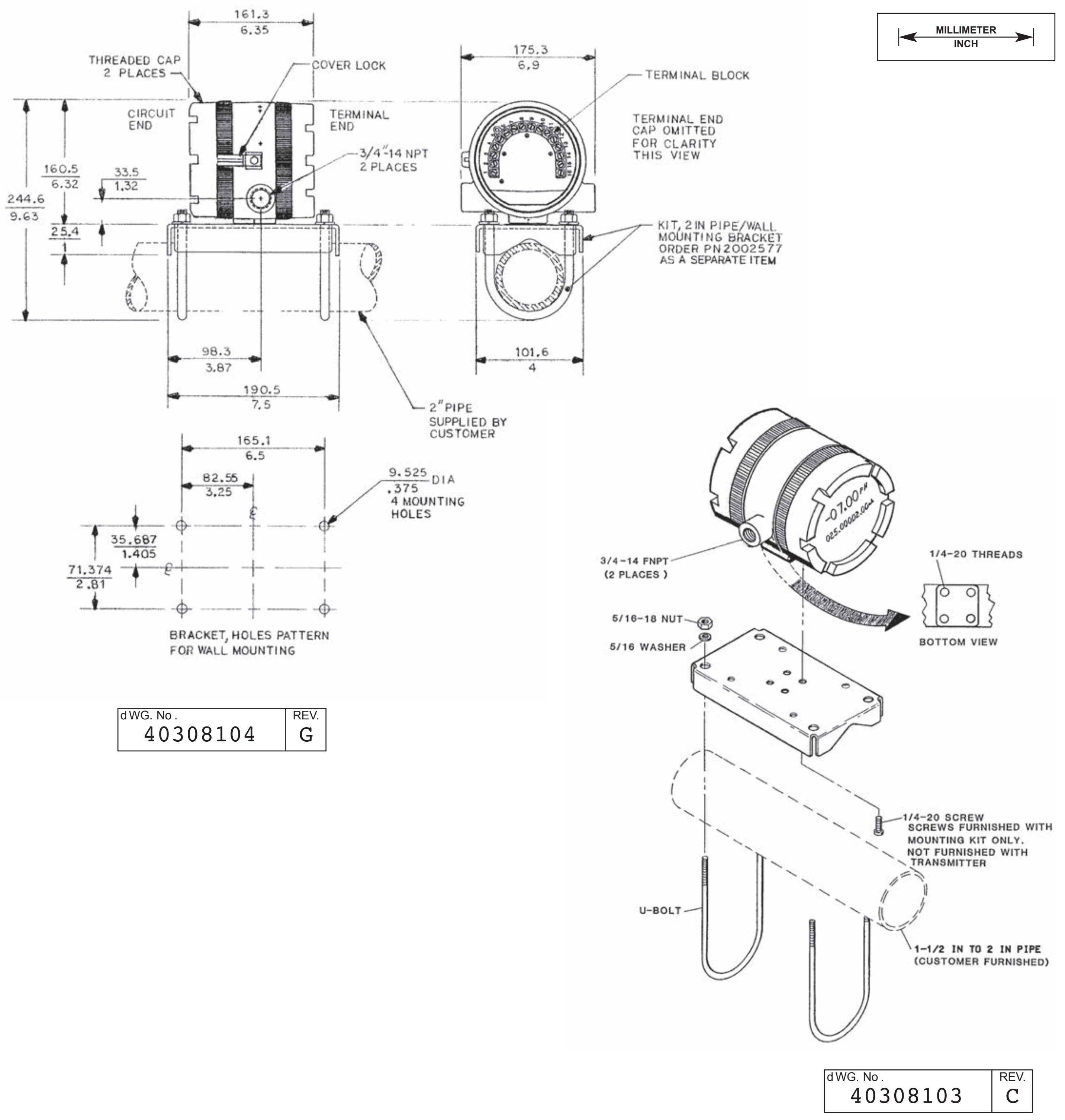



**FIGURE 2-2. Using the Pipe Mounting Kit to Attach the Model 5081-C Conductivity Transmitter to a Pipe**

### 2.3.4 Contacting Loops.

The Model 5081-C conductivity transmitter is designed to make accurate measurements while in contact with the process stream. Measurements can also be tailored to high temperature and/or high pressure streams.

### 2.3.5 Sensor Selection.

All Rosemount Analytical contacting conductivity sensors with PT100 RTd or PT1000 RTd are compatible with the Model 5081-C transmitter. Please refer to Figures 3-5 thru 3-9 for appropriate sensor to transmitter wiring. The sensor cable should be routed through the left inlet closest to the connector.

Choose a contacting conductivity sensor that is appropriate for your process conditions and range of conductivity measurement.

**TABLE 2-1. Model 5081-C Sensor Selection**

| Cell Constant | Range |
|---|---|
| 0.01 | 0 to 200 μS/cm |
| 0.1 | 0 to 2,000 μS/cm |
| 1.0 | 0 to 20,000 μS/cm |

## 2.4 POwER SUPPLy/CURRENT LOOP — MODEL 5081-C-HT

**2.4.1 Power Supply and Load Requirements.** Refer to Figure 2-3.

The minimum power supply voltage is 12.5 Vdc and the maximum is 42.4 Vdc. The top line on the graph gives the voltage required to maintain at least 12.5 Vdc at the transmitter terminals when the output signal is 22 mA. The lower line is the supply voltage required to maintain a 30 Vdc terminal voltage when the output signal is 22 mA.

The power supply must provide a surge current during the first 80 milliseconds of start-up. For a 24 Vdc power supply and a 250 ohm load resistor the surge current is 40 mA. For all other supply voltage and resistance combinations the surge current is not expected to exceed 70 mA.

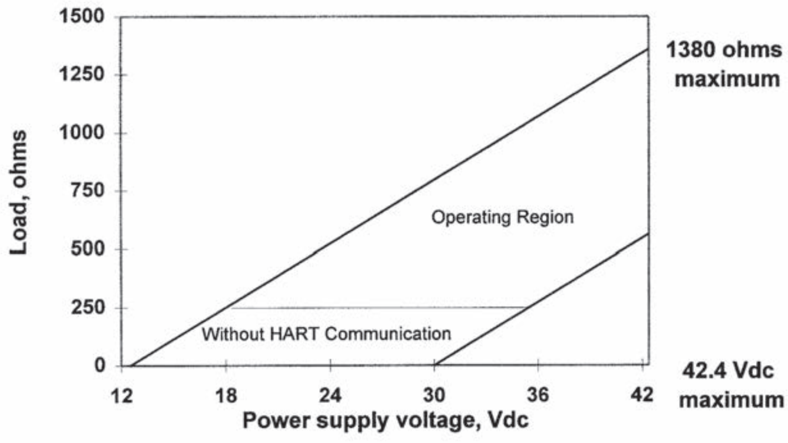



FIGURE 2-3. Load/Power Supply Requirements

For digital (HART or AMS) communications, the load must be at least 250 ohms. To supply the 12.5 Vdc lift off voltage at the transmitter, the power supply voltage must be at least 18 Vdc.

For intrinsically safe operation the supply voltage should not exceed 30.0 Vdc.

**2.4.2 Power Supply-Current Loop wiring.** Refer to Figure 2-4.

Run the power/signal wiring through the opening nearest terminals 15 and 16. use shielded cable and ground the shield at the power supply. To ground the transmitter, attach the shield to the grounding screw on the inside of the transmitter case. A third wire can also be used to connect the transmitter case to earth ground.

**NOTE**

For optimum EMi/RFi immunity, the power supply/output cable should be shielded and enclosed in an earth-grounded metal conduit.

do not run power supply/signal wiring in the same conduit or cable tray with AC power lines or with relay actuated signal cables. Keep power supply/ signal wiring at least 6 ft (2 m) away from heavy electrical equipment.

An additional 0-1 mA current loop is available between TB-14 and TB-15. A 1 mA current in this loop signifies a sensor fault. See Figure 4-3 for wiring instructions. See Section 8.4 or 10.6 and Section 12.0 for more information about sensor faults.

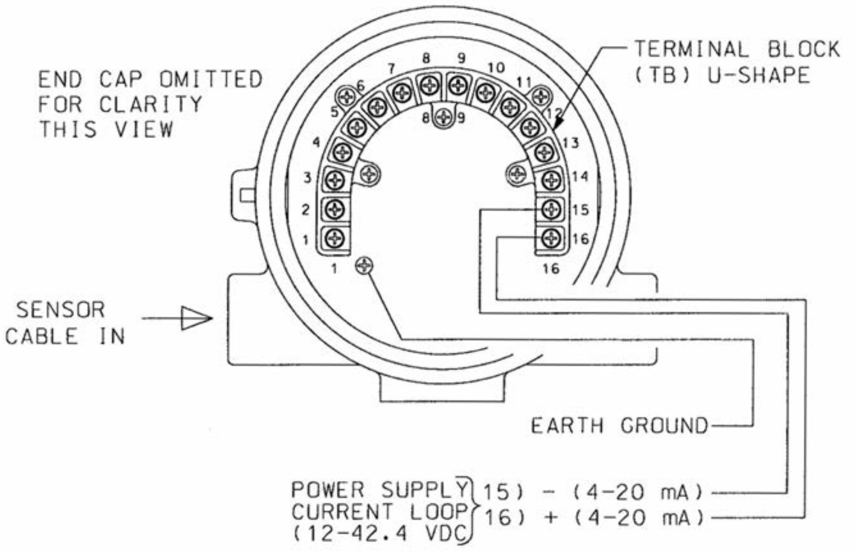



FIGURE 2-4. Model 5081-C-HT Power wiring Details

## 2.5 POwER SUPPLy wIRING FOR MODEL 5081-C-FF

**2.5.1 Power Supply wiring.** Refer to Figure 2-5 and Figure 2-6.

Run the power/signal wiring through the opening nearest terminals 15 and 16. use shielded cable and ground the shield at the power supply. To ground the transmitter, attach the shield to the grounding screw on the inside of the transmitter case. A third wire can also be used to connect the transmitter case to earth ground.

**NOTE**

For optimum EMi/RFi immunity, the power supply/output cable should be shielded and enclosed in an earth-grounded metal conduit.

do not run power supply/signal wiring in the same conduit or cable tray with AC power lines or with relay actuated signal cables. Keep power supply/signal wiring at least 6 ft (2 m) away from heavy electrical equipment.

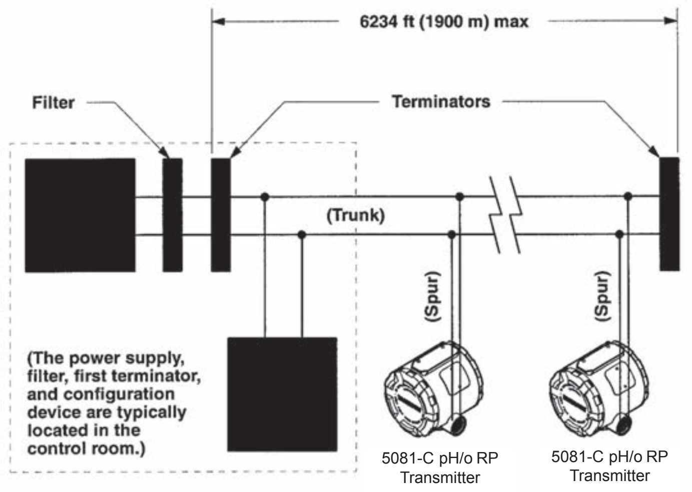



**FIGURE 2-5. Typical Fieldbus Network Electrical wiring Configuration**

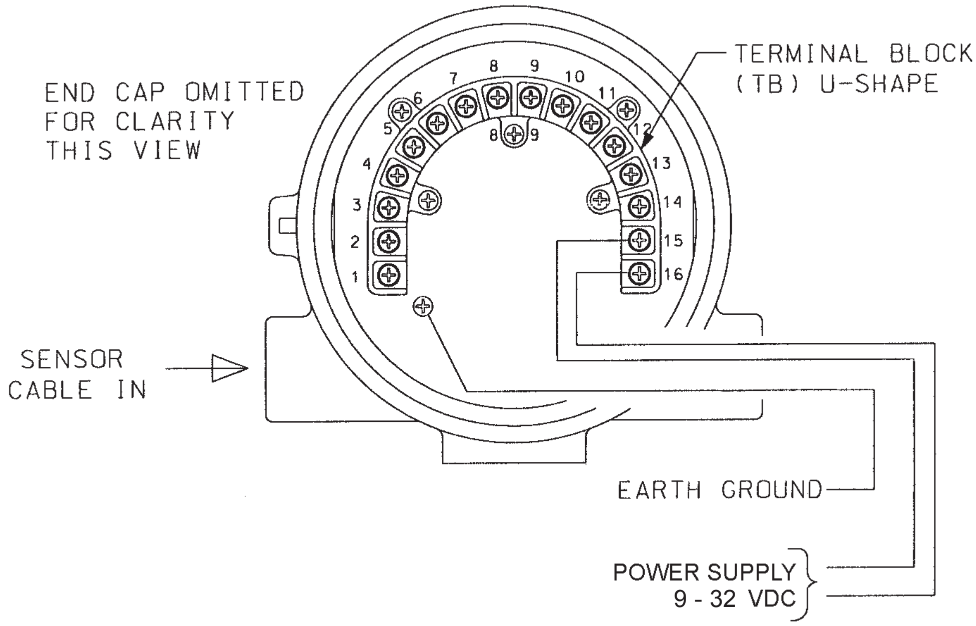



**FIGURE 2-6. Model 5081-C-FF Power wiring Details**

# SECTION 3.0
# w IRING

3.1 Sensor w iring
3.2 Electrical Installation

## 3.1 SENSOR w IRING

Wire sensor as shown below in Figure 3-1. Keep sensor wiring separate from power wiring. For best EMi/RFi protection, use shielded output signal cable in an earth-grounded metal conduit. Refer to the sensor instruction manual for more details.

**Recommended Transmitter Settings***

| Process Stream | Software Settings Type |
|---|---|
| Contacting Conductivity in the range 20 to 20,000 µS/cm (default) | LinEAr |
| u ltrapure water up to 20µS/cm | n SALt |
| Cation Water | CAtio n |

* Assumes 1.0 cell constant.

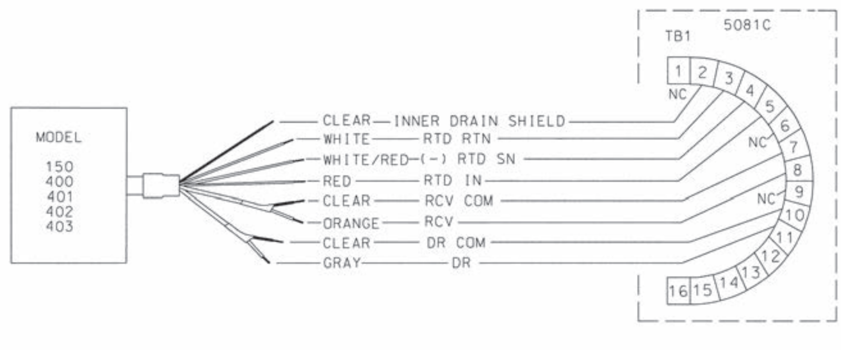



**FIGURE 3-1. w iring Model 5081C-HT**

### 3.1.1 w IRING THROUGH A j UNCTION BOx

The sensor can be wired to the analyzer through a remote junction box (PN 23550-00). Wire the extension cable and sensor cable point-to-point. Refer to the sensor instruction manual for more details.

Factory-terminated (PN 23747-00) and unterminated (PN 9200275) connecting cable are available. The use of factory-terminated cable is strongly recommended. To prepare unterminated cable for use, follow the instructions in the sensor instruction manual.

For maximum EMi/RFi protection, the outer braid of the sensor cable should be connected to the outer braided shield of the extension cable. At the instrument, connect the outer braid of the extension cable to earth ground.

### 3.1.2 POWER WIRING MODEL 5081-C-HT

For general purpose areas, wire power as shown in Figure 3-2. For hazardous areas, please see hazardous area installation drawings.

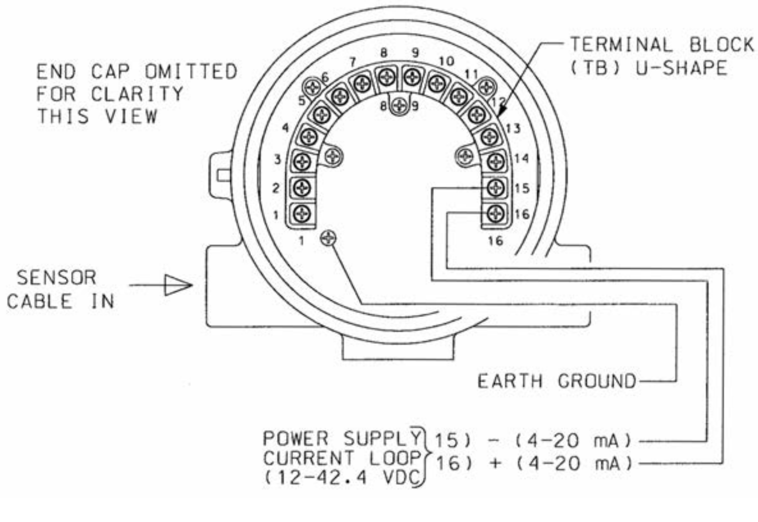



FIGURE 3-2. Power Supply/Current Loop Wiring for Model 5081-C-HT

### 3.1.3 POWER WIRING MODEL 5081-C-FF

For general purpose areas, wire power as shown in Figure 3-3. For hazardous areas, please see hazardous area installation drawings.

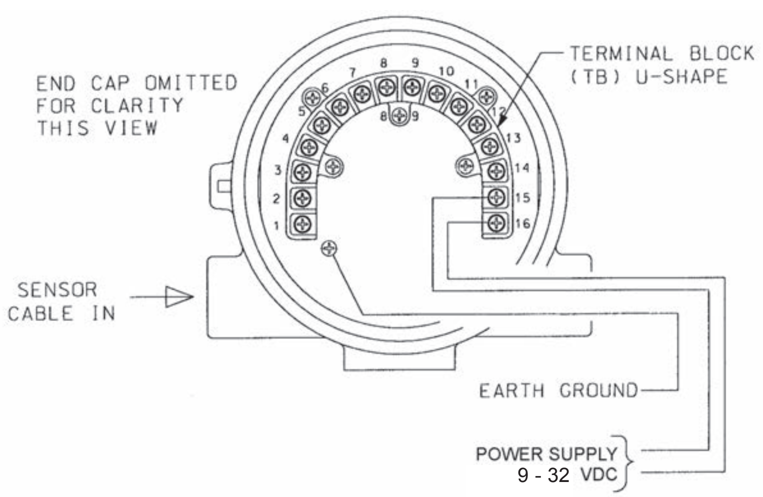



FIGURE 3-3. Power Supply/Current Loop Wiring for Model 5081-C-FF

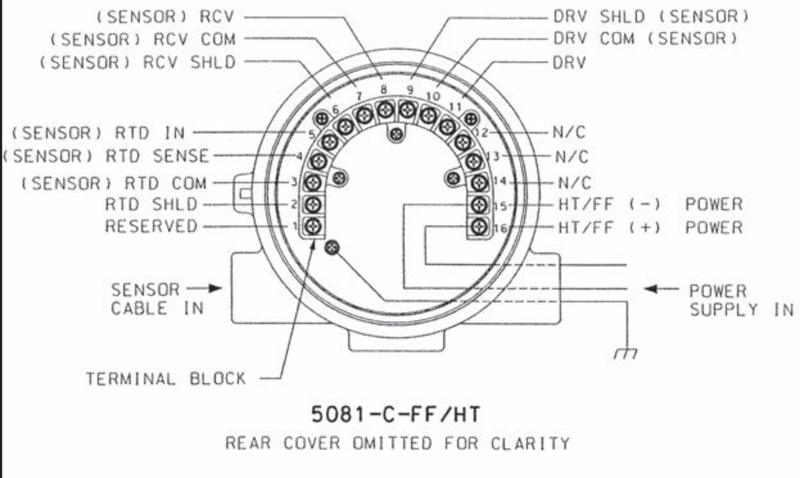



FIGURE 3-4. Power Supply and Sensor Wiring for Model 5081-C

## 3.2 ELECTRICAL INSTALLATION

All Rosemount Analytical contacting conductivity sensors with PT100 RTd or PT1000 RTd are compatible with the Model 5081-C transmitter. Please refer to Figures 3-5 thru 3-9 for appropriate sensor to transmitter wiring. The sensor cable should be routed through the left inlet closest to the connector.

**NOTE**

o ptimum EMi/RFi immunity may be achieved on sensors whose interconnecting cable has an outer braided shield by utilizing a cable gland fitting that provides for continuity between the braided shield and the transmitter enclosure. An equivalent conduit connector may also be used if the sensor cable is to be enclosed in conduit.

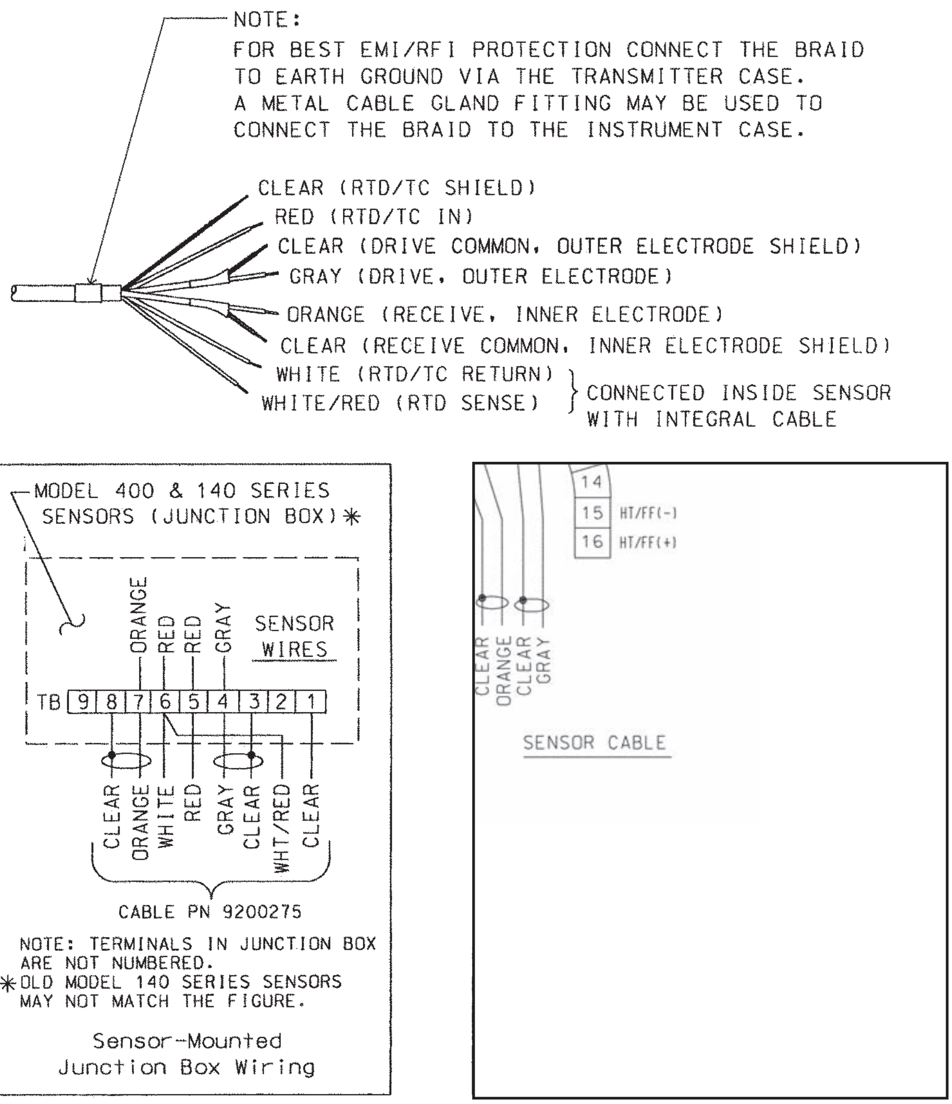



**FIGURE 3-5. Contacting Conductivity Sensor to Transmitter 5081-C**

*Note: Connect gray wire of sensor to terminal 11 for high conductivity ranges or to terminal 12 for low conductivity ranges. See Table 2-1 for range selection.

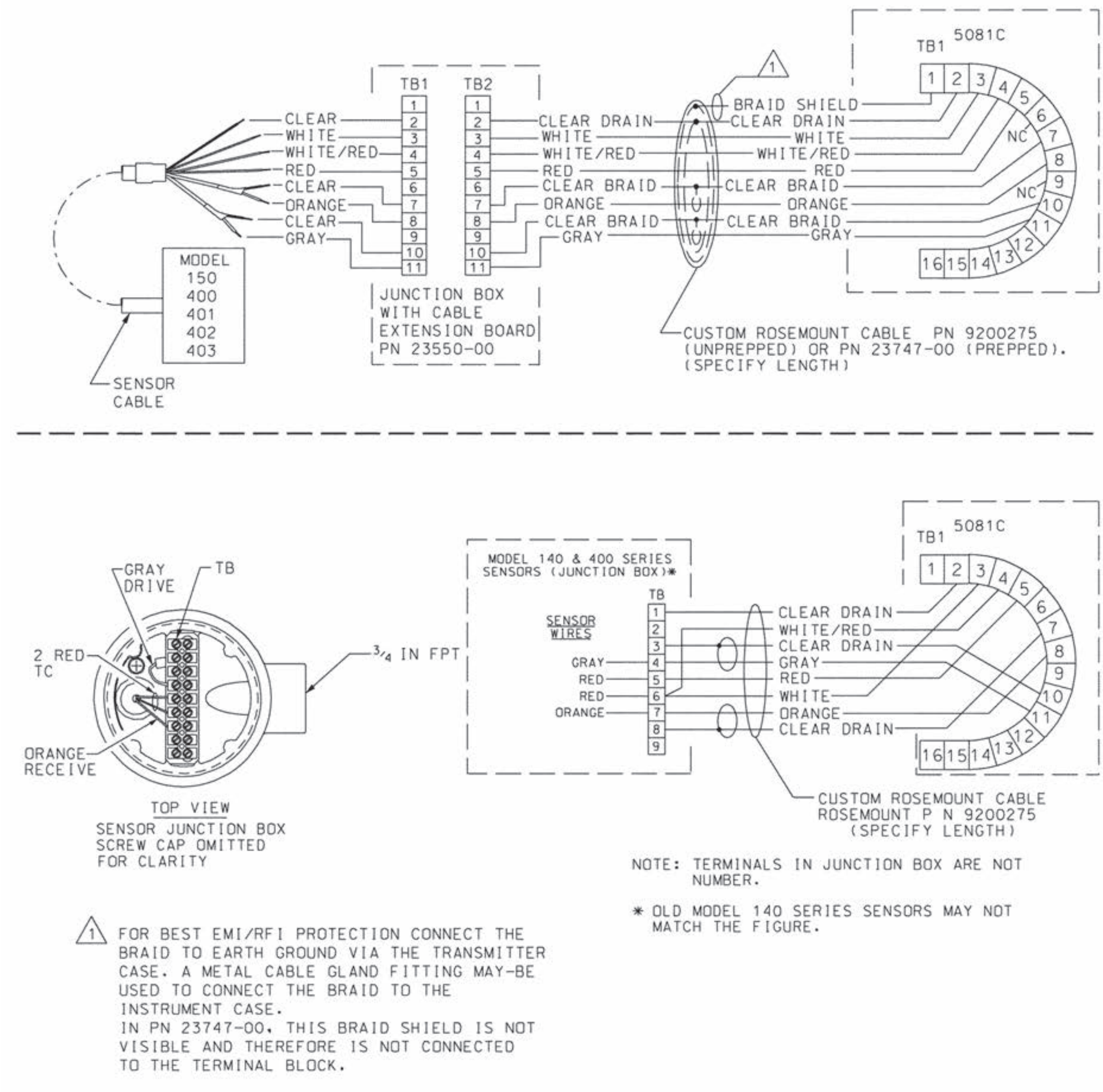



**FIGURE 3-6. Model 5081-C with J-Box — 140 Series Sensor Wiring Details**

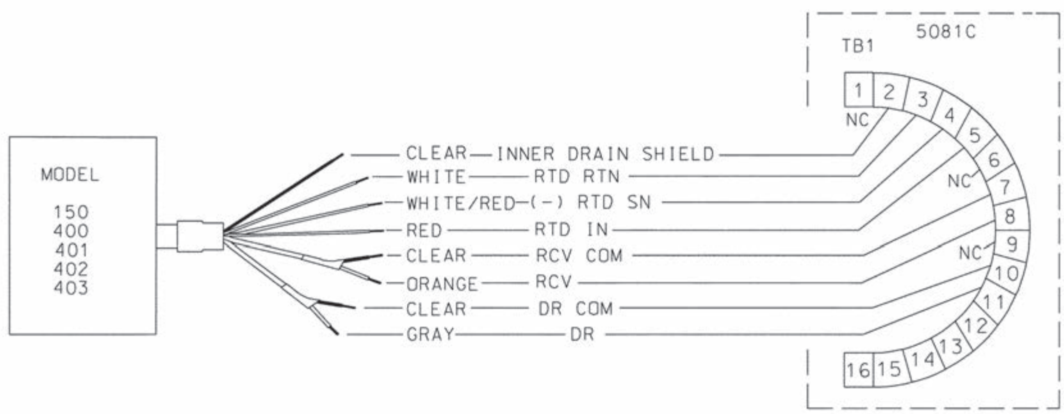



**FIGURE 3-7. Model 5081-C — 150 and 400 Series Sensor Wiring Details**

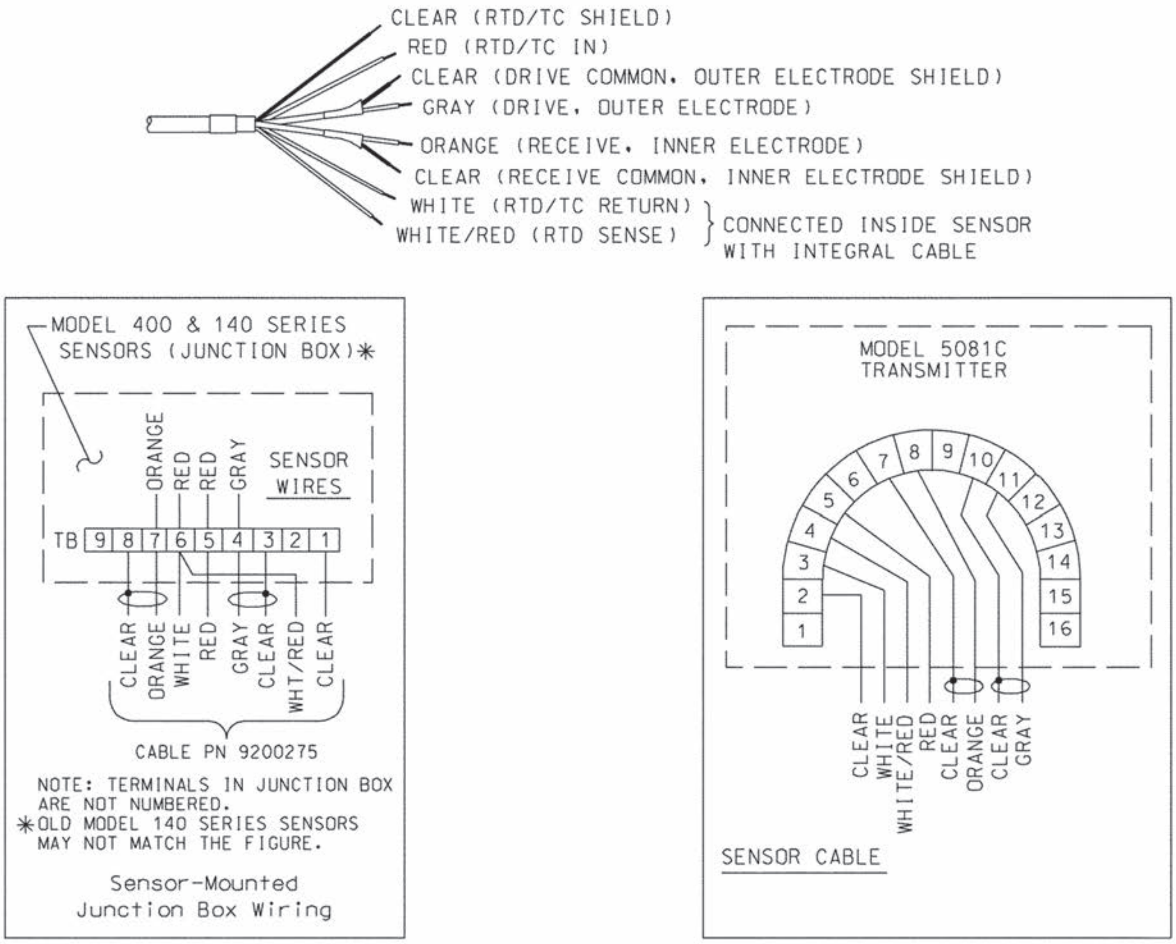



**FIGURE 3-8. Model 5081-C with Contacting Conductivity Sensor**

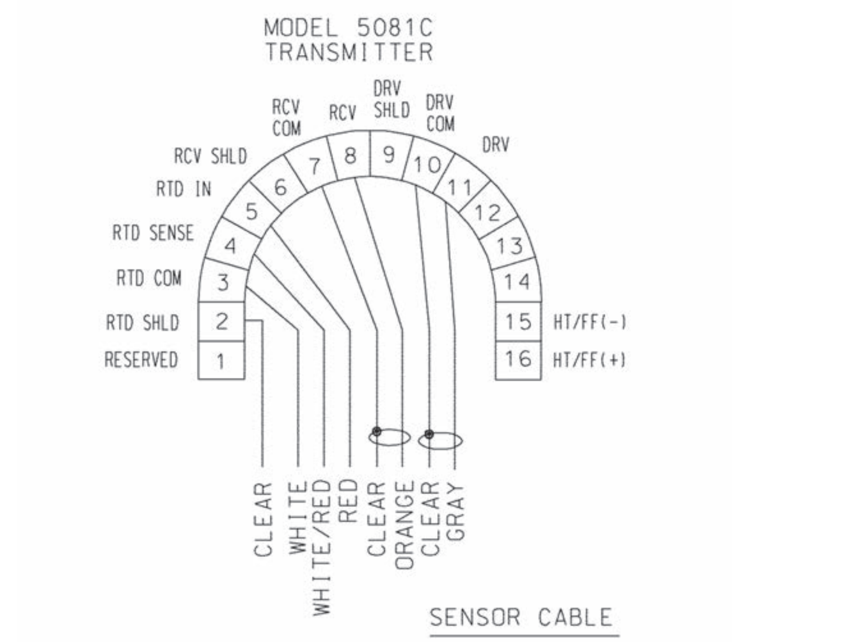



**FIGURE 3-9. Model 5081-C — WIRING to Model 400 ENDURANCE Sensors**

# SECTION 4.0
# INTRINSICALLy SAFE & ExPLOSION PROOF

## 4.1 INTRINSICALLy SAFE AND ExPLOSION-PROOF INSTALLATIONS FOR MODEL 5081-C-HT

For CSA, FM, & Baseefa/ATEX approvals for the infrared Remote Control, see Figure 4-1 (below).

For FMRC Explosion-Proof installation, see Figure 4-3.

For FM intrinsically Safe Label, see Figure 4-4.

For FM intrinsically Safe installation, see Figure 4-5.

For CSA instrinsically Safe Label, see Figure 4-6.

For CSA instrinsically Safe installation, see Figure 4-7.

For ATEX instrinsically Safe Label, see Figure 4-8.

For ATEX instrinsically Safe installation, see Figure 4-9.

## 4.2 INTRINSICALLy SAFE AND ExPLOSION-PROOF INSTALLATIONS FOR MODEL 5081-C-FF

For CSA, FM, & Baseefa/ATEX approvals for the infrared Remote Control, see Figure 4-2 (below).

For FMRC Explosion-Proof installation, see Figure 4-10.

For FM intrinsically Safe Label, see Figure 4-11.

For FM intrinsically Safe installation, see Figure 4-12.

For CSA instrinsically Safe Label, see Figure 4-13.

For CSA instrinsically Safe installation, see Figure 4-14.

For ATEX instrinsically Safe Label, see Figure 4-15.

For ATEX instrinsically Safe installation, see Figure 4-16.

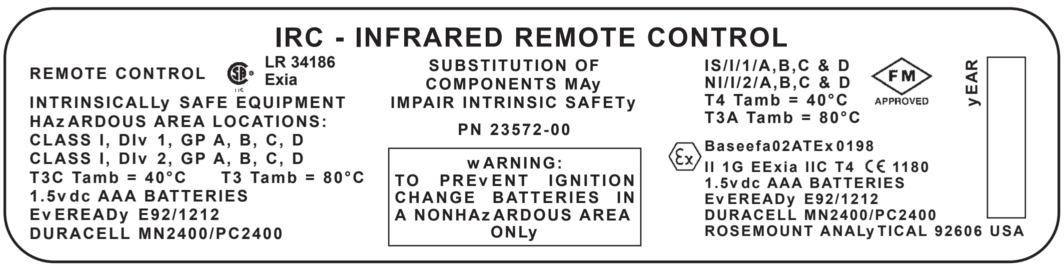



FIGURE 4-1. Model 5081-C-HT Infrared Remote Control — CSA, FM, & Baseefa/ATEx approvals

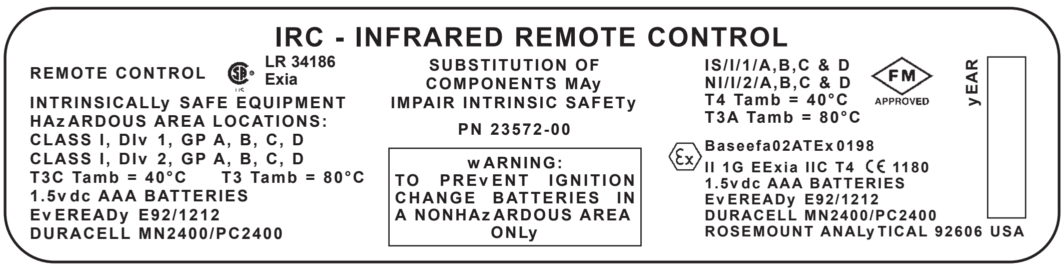



FIGURE 4-2. Model 5081-C-FF Infrared Remote Control — CSA, FM, & Baseefa/ATEx approvals

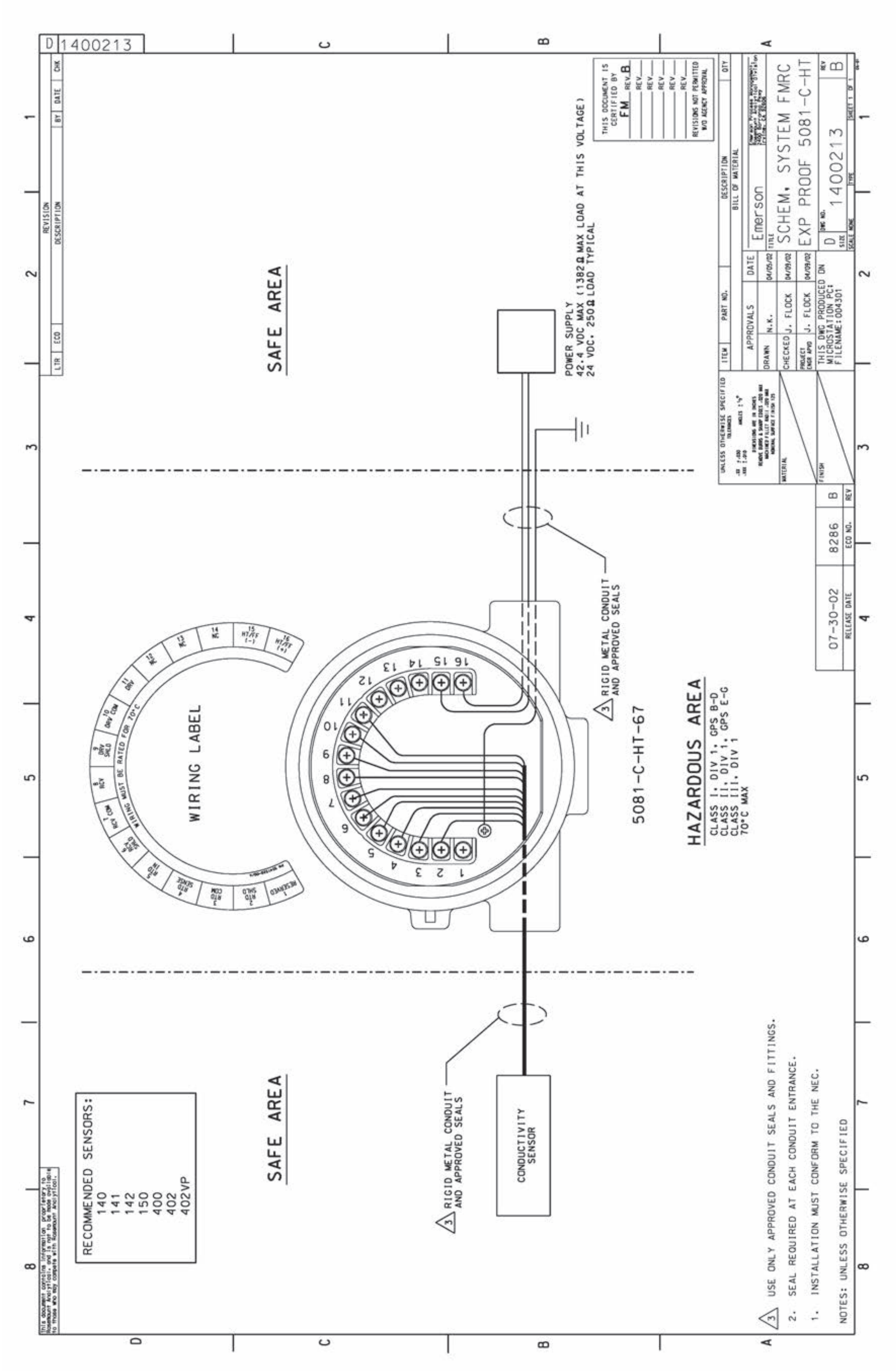



FIGURE 4-3. FMRC Explosion-Proof Installation for Model 5081-C-HT

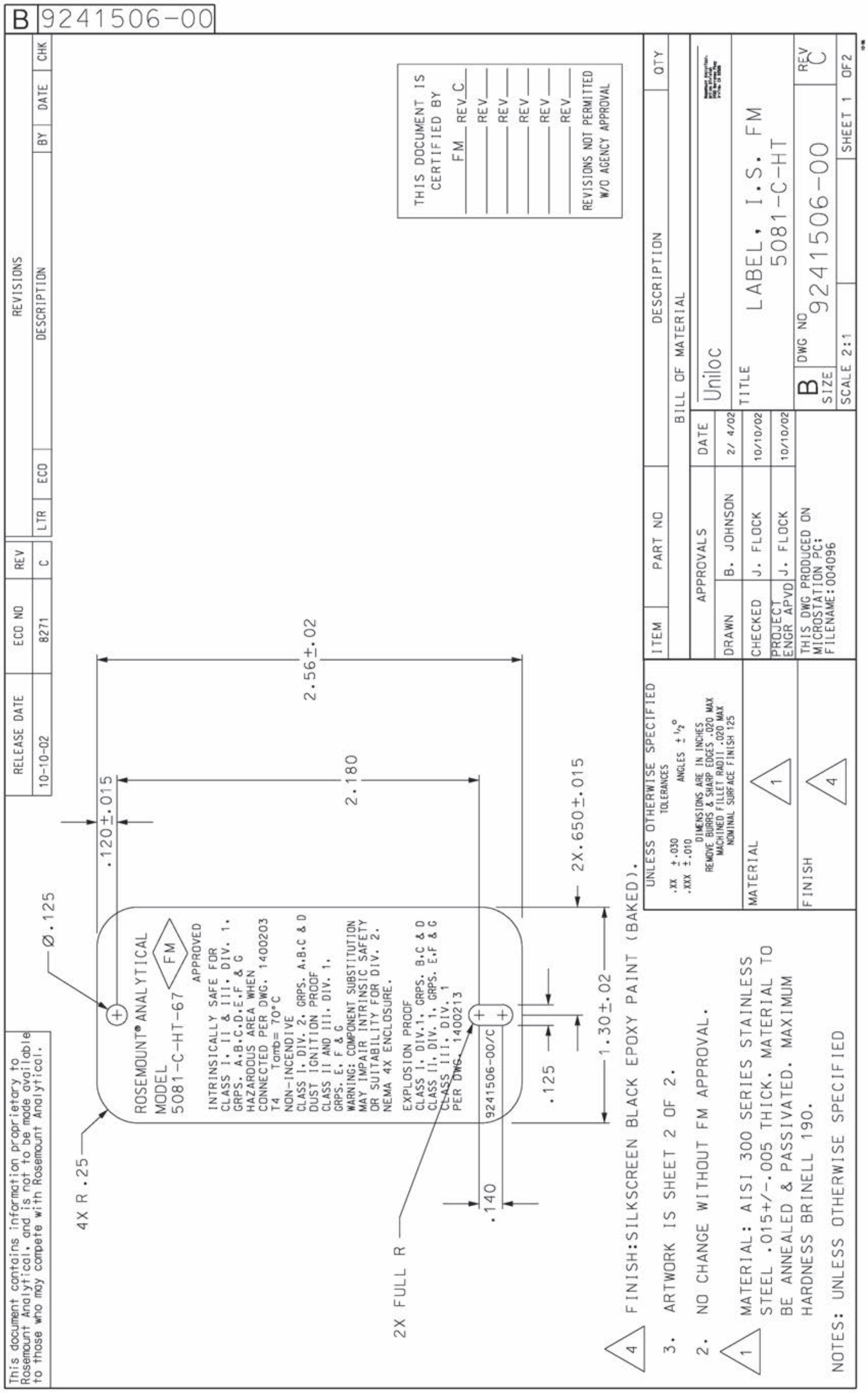
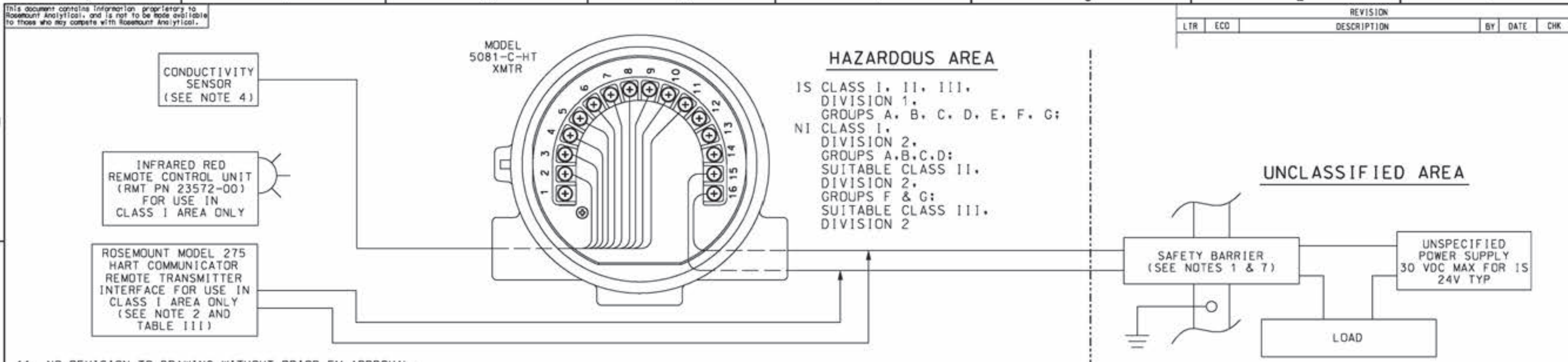



FIGURE 4-4. FM Intrinsically Safe Label for Model 5081-C-HT




WARNING— SUBSTITUTION OF COMPONENTS MAY IMPAIR INTRINSIC SAFETY OR SUITABILITY FOR DIVISION 2.

WARNING— TO PREVENT IGNITION OF FLAMMABLE OR COMBUSTIBLE ATMOSPHERES. DISCONNECT POWER BEFORE SERVICING.

11. NO REVISION TO DRAWING WITHOUT PRIOR FM APPROVAL.

10. THE ASSOCIATED APPARATUS MUST BE FM APPROVED.

9. CONTROL EQUIPMENT CONNECTED TO ASSOCIATED APPARATUS MUST NOT USE OR GENERATE MORE THAN 250 Vrms OR Vdc.

8. ASSOCIATED APPARATUS MANUFACTURER'S INSTALLATION DRAWING MUST BE FOLLOWED WHEN INSTALLING THIS EQUIPMENT.

7. THE ENTITY CONCEPT ALLOWS INTERCONNECTION OF INTRINSICALLY SAFE APPARATUS WITH ASSOCIATED APPARATUS WHEN THE FOLLOWING IS TRUE:

| FIELD DEVICE INPUT | | ASSOCIATED APPARATUS OUTPUT |
|---|---|---|
| Vmax OR Ui | ≥ | Voc, Vt OR Uo; |
| Imax OR Ii | ≥ | Isc, It OR Io; |
| Pmax OR Pi | ≥ | Po; |
| Ci+ Ccable; | ≤ | Ca, Ct OR Co |
| Li+ Lcable. | ≤ | La, Lt OR Lo |

6. RESISTANCE BETWEEN INTRINSICALLY SAFE GROUND AND EARTH GROUND MUST BE LESS THAN 1.0 Ohm.

5. DUST-TIGHT CONDUIT SEAL MUST BE USED WHEN INSTALLED IN CLASS II AND CLASS III ENVIRONMENTS.

4. SENSORS SHALL MEET THE REQUIREMENTS OF SIMPLE APPARATUS AS DEFINED IN ANSI/ISA RP12.6 AND THE NEC, ANSI/NFPA 70. THEY CAN NOT GENERATE NOR STORE MORE THAN 1.2V, 0.1A, 25mW, AND 20uJ. SEE TABLES I AND II.

3. INSTALLATION SHOULD BE IN ACCORDANCE WITH ANSI/ISA RP12.06.01 "INSTALLATION OF INTRINSICALLY SAFE SYSTEMS FOR HAZARDOUS (CLASSIFIED) LOCATIONS" AND THE NATIONAL ELECTRICAL CODE (ANSI/NFPA 70).

2. INTRINSICALLY SAFE APPARATUS (MODEL 5081-C-HT, IRC TRANSMITTER AND MODEL 275) AND ASSOCIATED APPARATUS (SAFETY BARRIER) SHALL MEET THE FOLLOWING REQUIREMENTS: THE VOLTAGE (Vmax) AND CURRENT (Imax) OF THE INTRINSICALLY SAFE APPARATUS MUST BE EQUAL TO OR GREATER THAN THE VOLTAGE (Voc OR Vt) AND CURRENT (Isc OR It) WHICH CAN BE DELIVERED BY THE ASSOCIATED APPARATUS (SAFETY BARRIER). IN ADDITION, THE MAXIMUM UNPROTECTED CAPACITANCE (Ci) AND INDUCTANCE (Li) OF THE INTRINSICALLY SAFE APPARATUS, INCLUDING INTERCONNECTING WIRING, MUST BE EQUAL OR LESS THAN THE CAPACITANCE (Ca) AND INDUCTANCE (La) WHICH CAN BE SAFELY CONNECTED TO THE APPARATUS. (REF. TABLES I, II AND III).
THE CAPACITANCE AND INDUCTANCE OF THE LOAD CONNECTED TO THE SENSOR TERMINALS MUST NOT EXCEED THE VALUES SPECIFIED IN TABLE I.

1. ANY SHUNT ZENER DIODE SAFETY BARRIER APPROVED BY FM HAVING THE FOLLOWING OUTPUT PARAMETERS: SUPPLY/SIGNAL TERMINALS TB1-15, 16

Voc OR Vt NOT GREATER THAN 30 V
Isc OR It NOT GREATER THAN 200 mA
Pmax NOT GREATER THAN 0.9 W

NOTES: UNLESS OTHERWISE SPECIFIED

TABLE I

| GAS GROUPS | OUTPUT PARAMETERS Co (uF) | Lo (mH) |
|---|---|---|
| A, B | 12.05 | 0.5 |
| C | 490.05 | 2.0 |
| D | 9990.05 | 3.7 |

TABLE II

| OUTPUT PARAMETERS | MODEL 5081-A-HT TB1-1 THRU 12 |
|---|---|
| V+ | 6.51 Vdc |
| I+ | 280 mA |
| P+ | 442 mW |

TABLE III

5081-C-HT ENTITY PARAMETERS
SUPPLY / SIGNAL TERMINALS TB 1-15, 16

| MODEL NO. | Vmax (Vdc) | Imax (mA) | Pmax (W) | Ci (nF) | Li (mH) |
|---|---|---|---|---|---|
| 5081-C-HT | 30 | 200 | 0.9 | 27.8 | 0 |

ENTITY PARAMETERS: REMOTE TRANSMITTER INTERFACE

| MODEL NO. | Vmax IN: Vdc | Imax IN:mA | Wamx IN: W | Ci (uF) | Li (mH) | Voc max OUT: Vdc | Isc max OUT:mA |
|---|---|---|---|---|---|---|---|
| 275 | 30 | 300 | 1.0 | .07 | 0.0 | 1.7 | 32 |

THIS DOCUMENT IS CERTIFIED BY FM REV C
REVISIONS NOT PERMITTED W/O AGENCY APPROVAL

| RELEASE DATE | ECO NO. | REV |
|---|---|---|
| 10-11-02 | 8286 | C |

| APPROVALS | | DATE |
|---|---|---|
| DRAWN | N. KOUMBIS | 03/26/02 |
| CHECKED | J. FLOCK | 10/11/02 |
| PROJECT ENGR APVD | J. FLOCK | 10/11/02 |

THIS DWG PRODUCED ON MICROSTATION PC: FILENAME:004155

Uniloc

TITLE: SCHEMATIC, INSTALLATION MOD 5081-C-HT XMTR FM APPROVALS

SIZE D DWG NO. 1400203 REV C SHEET 1 OF 1

FIGURE 4-5. FM Intrinsically Safe Installation for Model 5081-C-HT

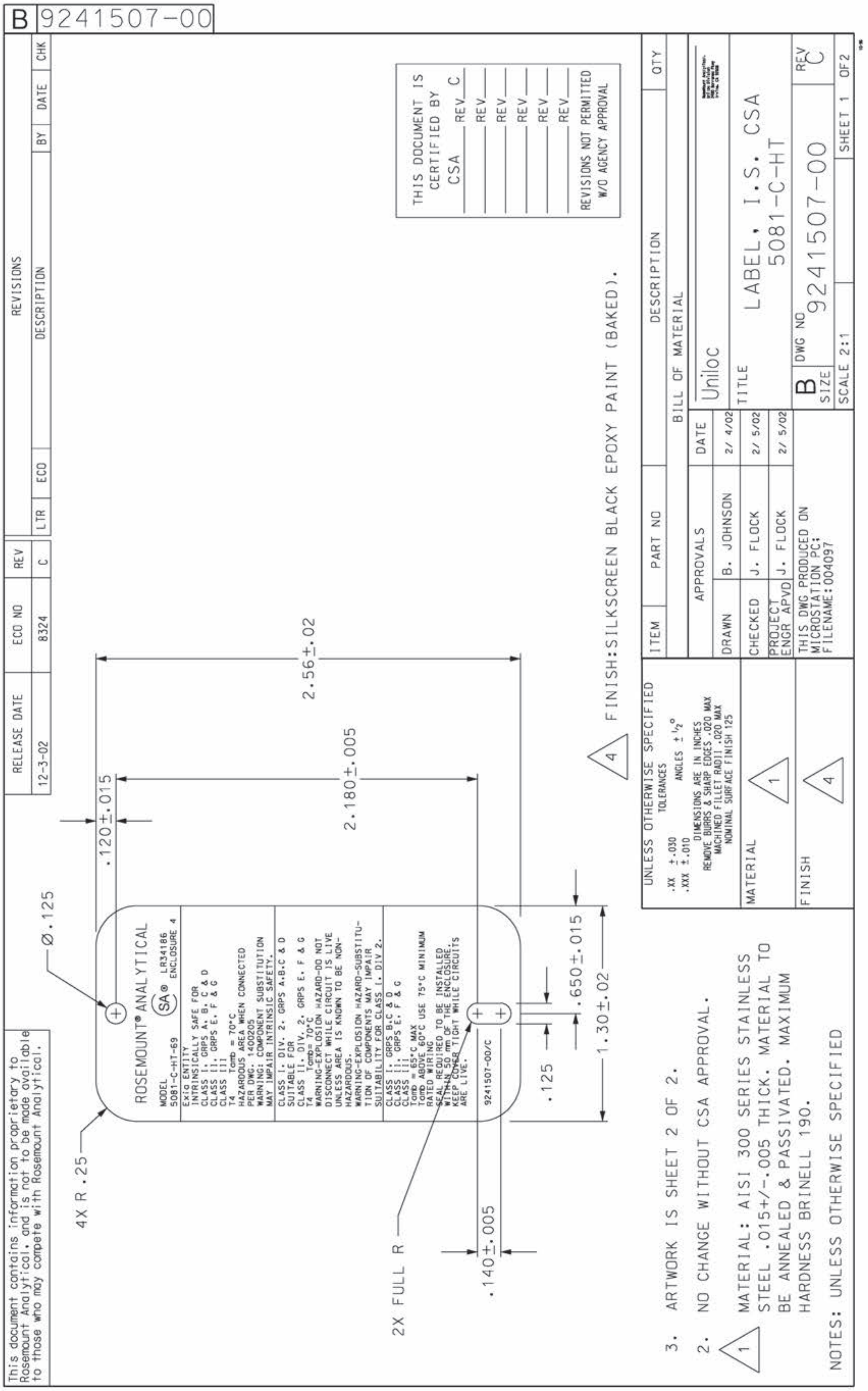



**FIGURE 4-6. CSA Intrinsically Safe Label for Model 5081-C-HT**

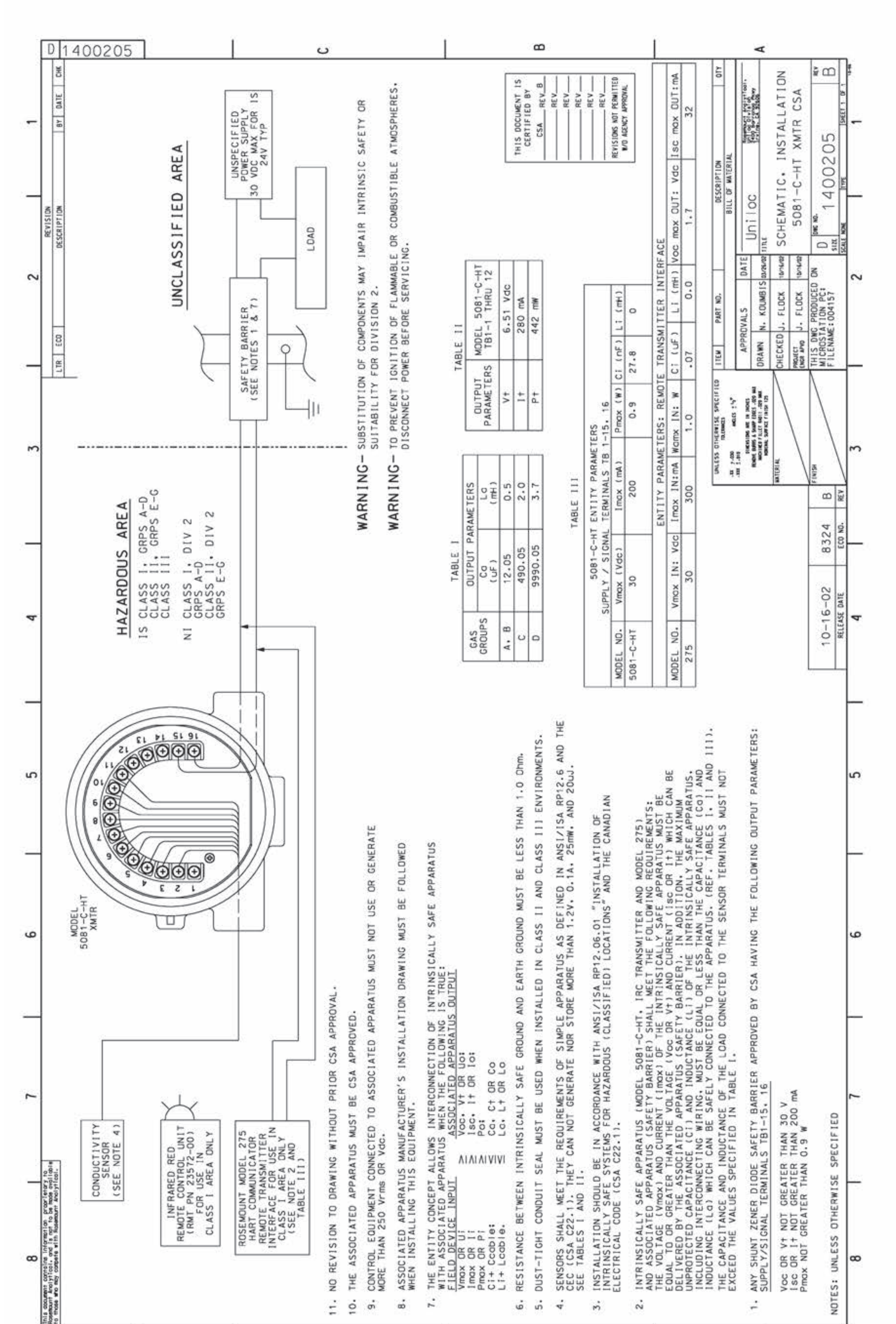



FIGURE 4-7. CSA Intrinsically Safe Installation for Model 5081-C-HT

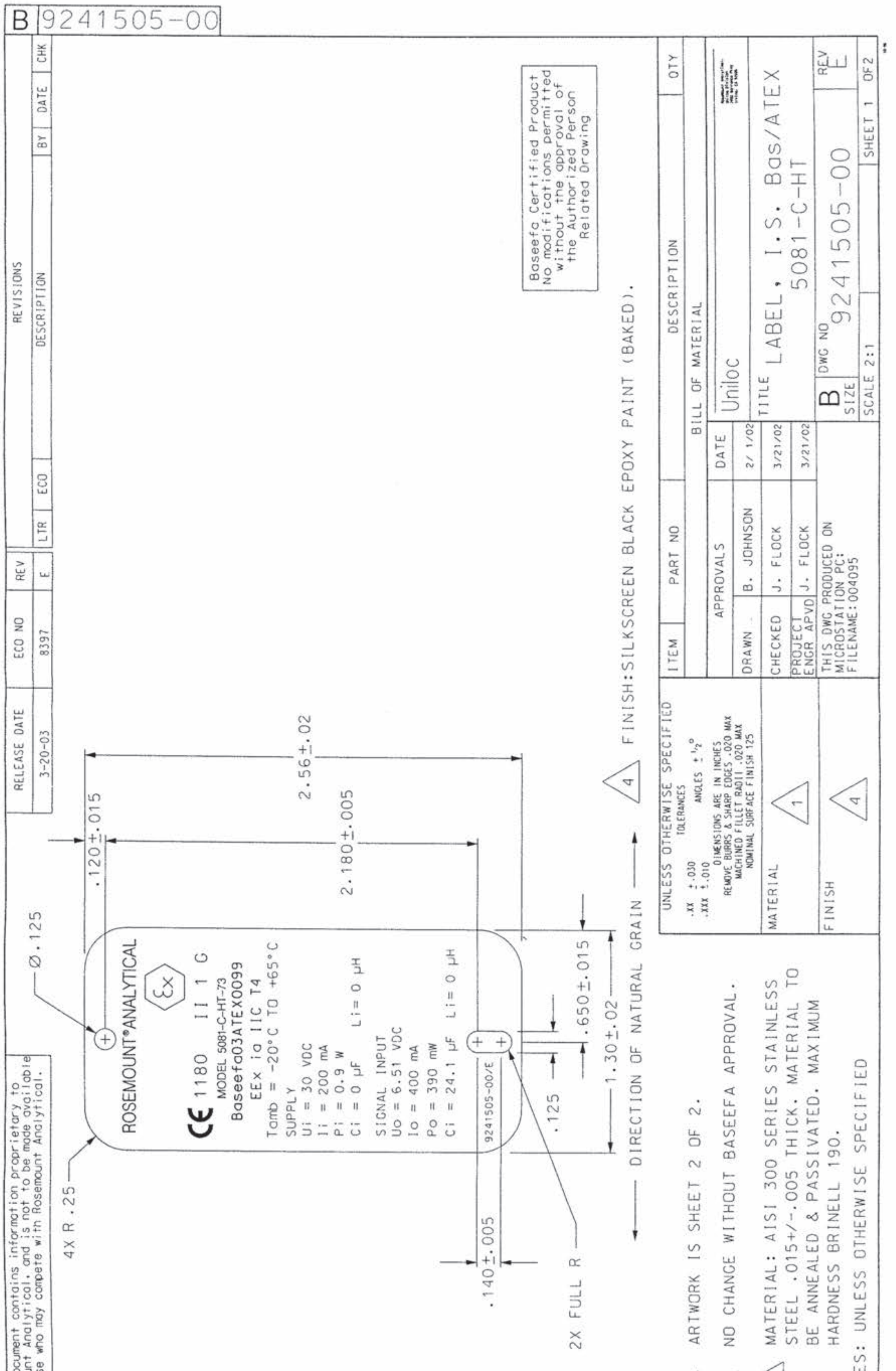



**FIGURE 4-8. ATEx Intrinsically Safe Label for Model 5081-C-HT**

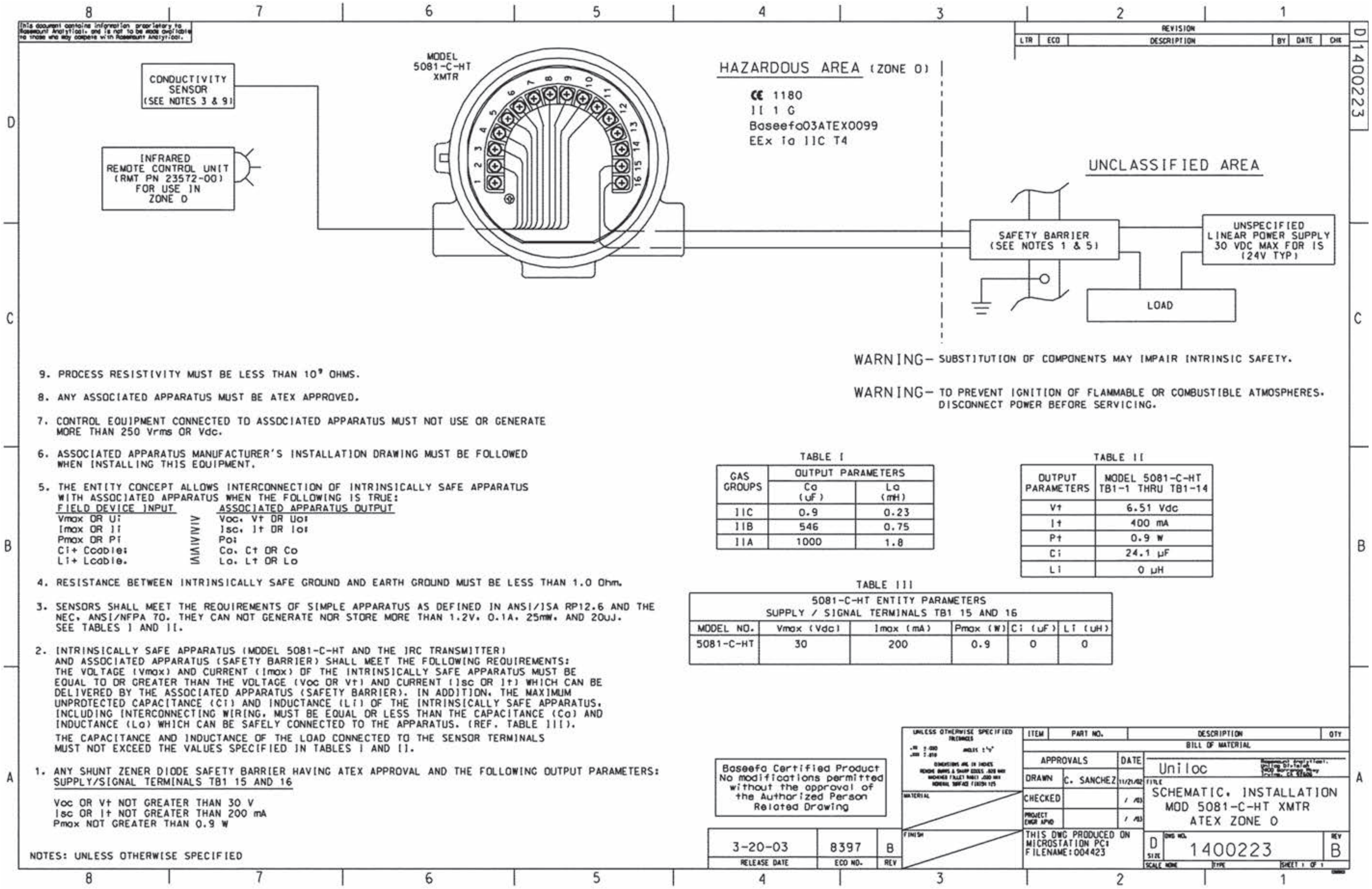



FIGURE 4-9. ATEx Intrinsically Safe Installation for Model 5081-C-HT

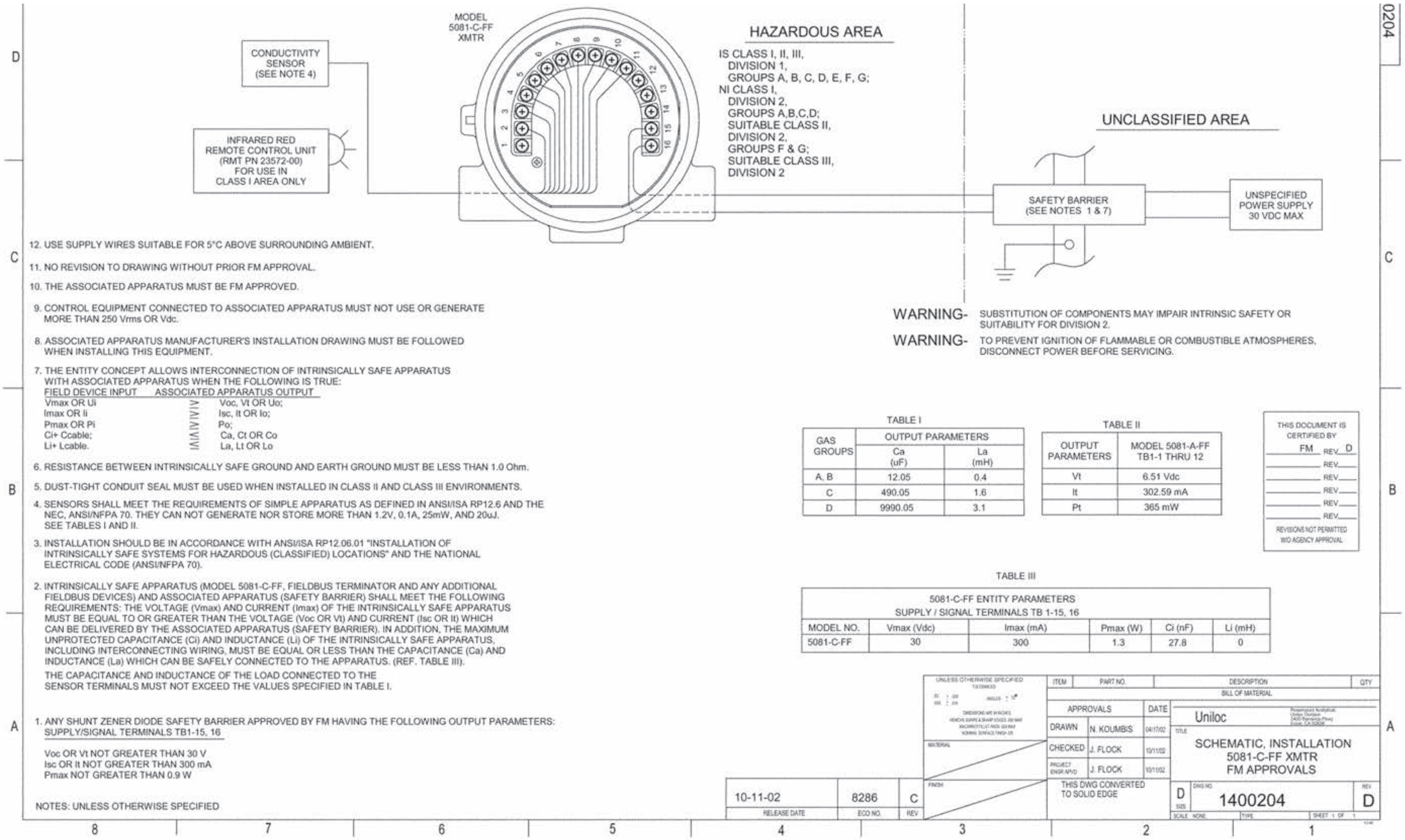



TABLE I

| GAS GROUPS | OUTPUT PARAMETERS Ca (uF) | La (mH) |
|---|---|---|
| A, B | 12.05 | 0.4 |
| C | 490.05 | 1.6 |
| D | 9990.05 | 3.1 |

TABLE II

| OUTPUT PARAMETERS | MODEL 5081-A-FF TB1-1 THRU 12 |
|---|---|
| Vt | 6.51 Vdc |
| It | 302.59 mA |
| Pt | 365 mW |

TABLE III

5081-C-FF ENTITY PARAMETERS SUPPLY / SIGNAL TERMINALS TB 1-15, 16

| MODEL NO. | Vmax (Vdc) | Imax (mA) | Pmax (W) | Ci (nF) | Li (mH) |
|---|---|---|---|---|---|
| 5081-C-FF | 30 | 300 | 1.3 | 27.8 | 0 |

FIGURE 4-10. FM Intrinsically Safe Installation for Model 5081-C-FF

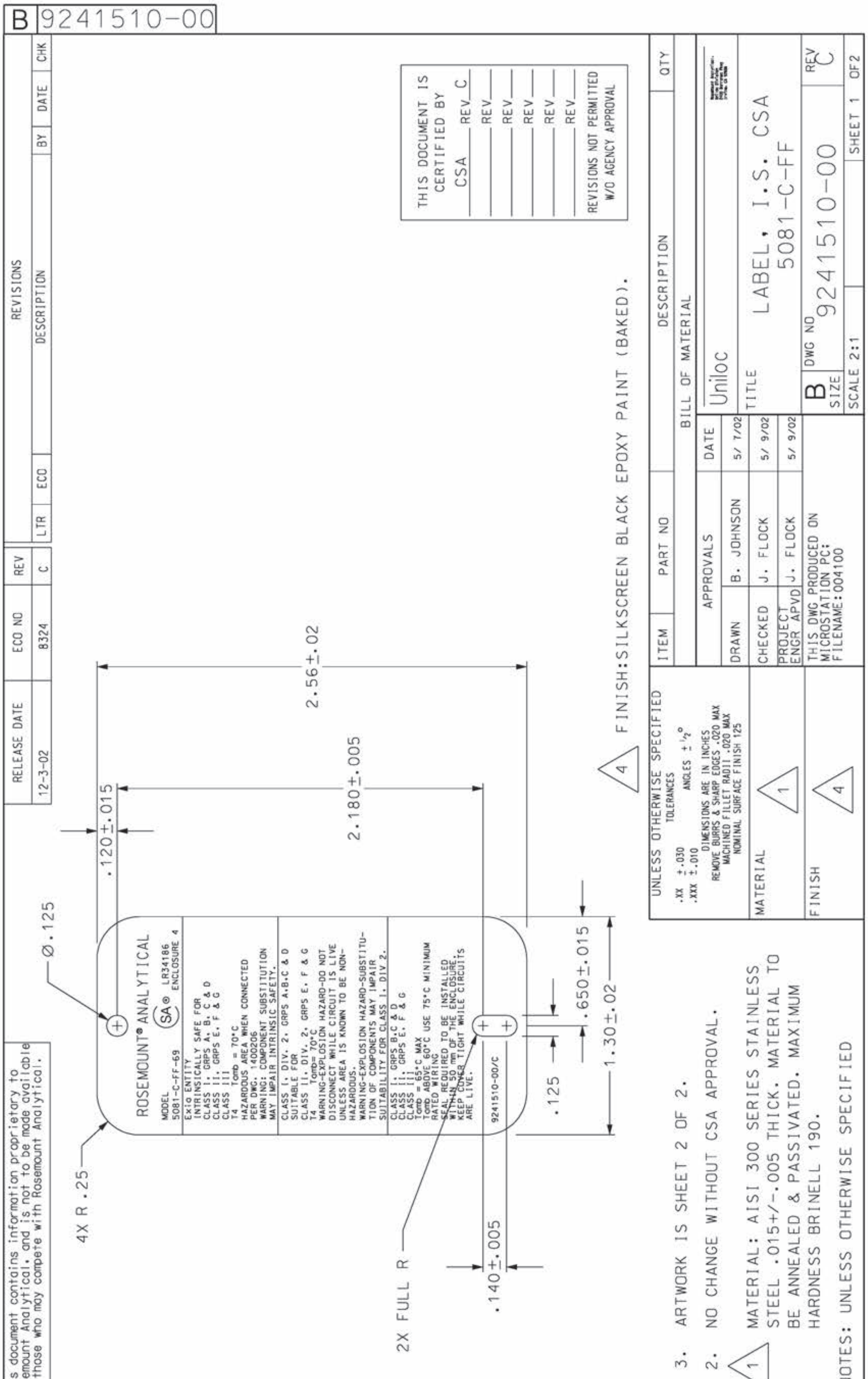



**FIGURE 4-11. CSA Intrinsically Safe Label for Model 5081-C-FF**

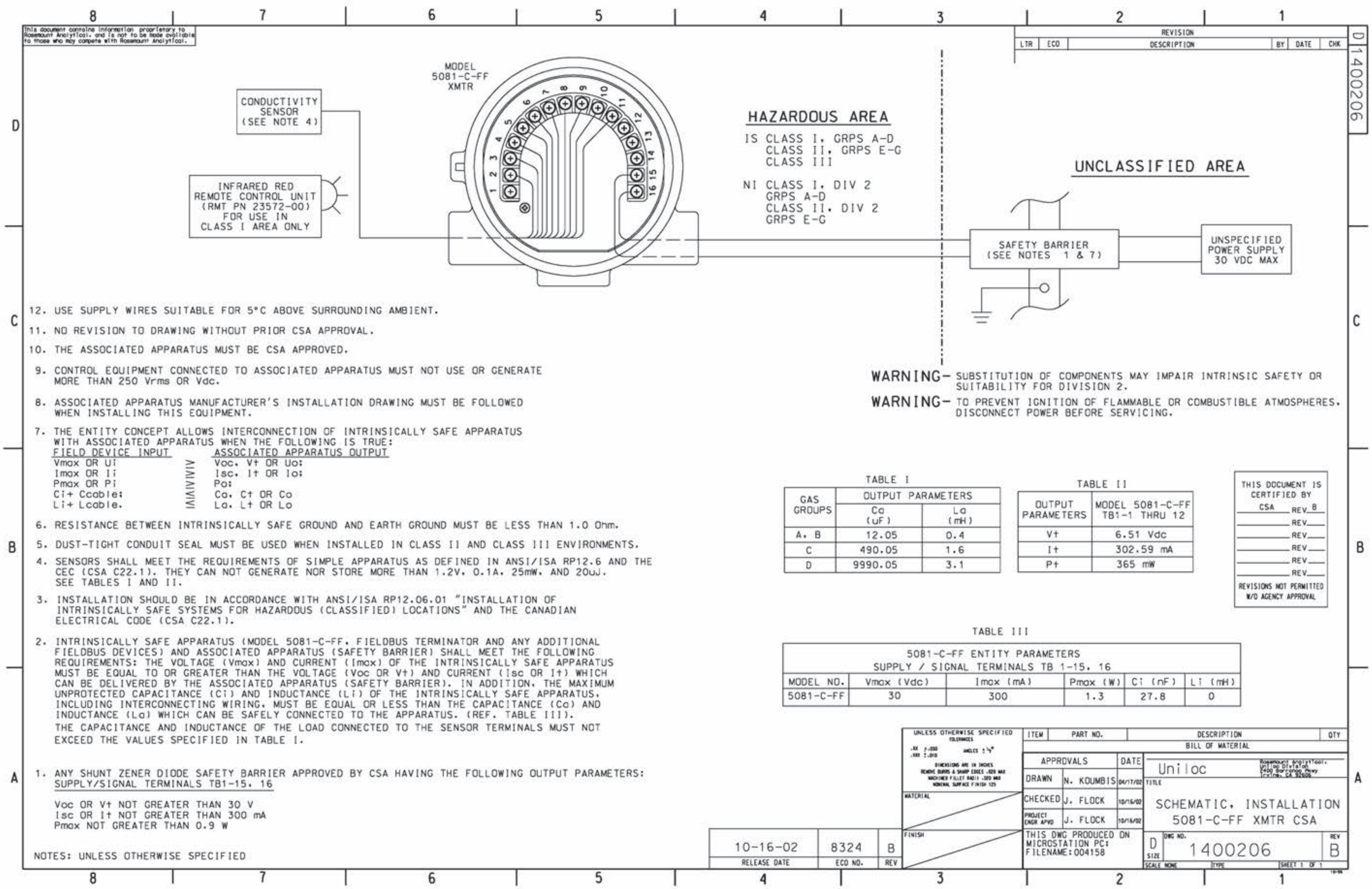



FIGURE 4-12. CSA Intrinsically Safe Installation for Model 5081-C-FF

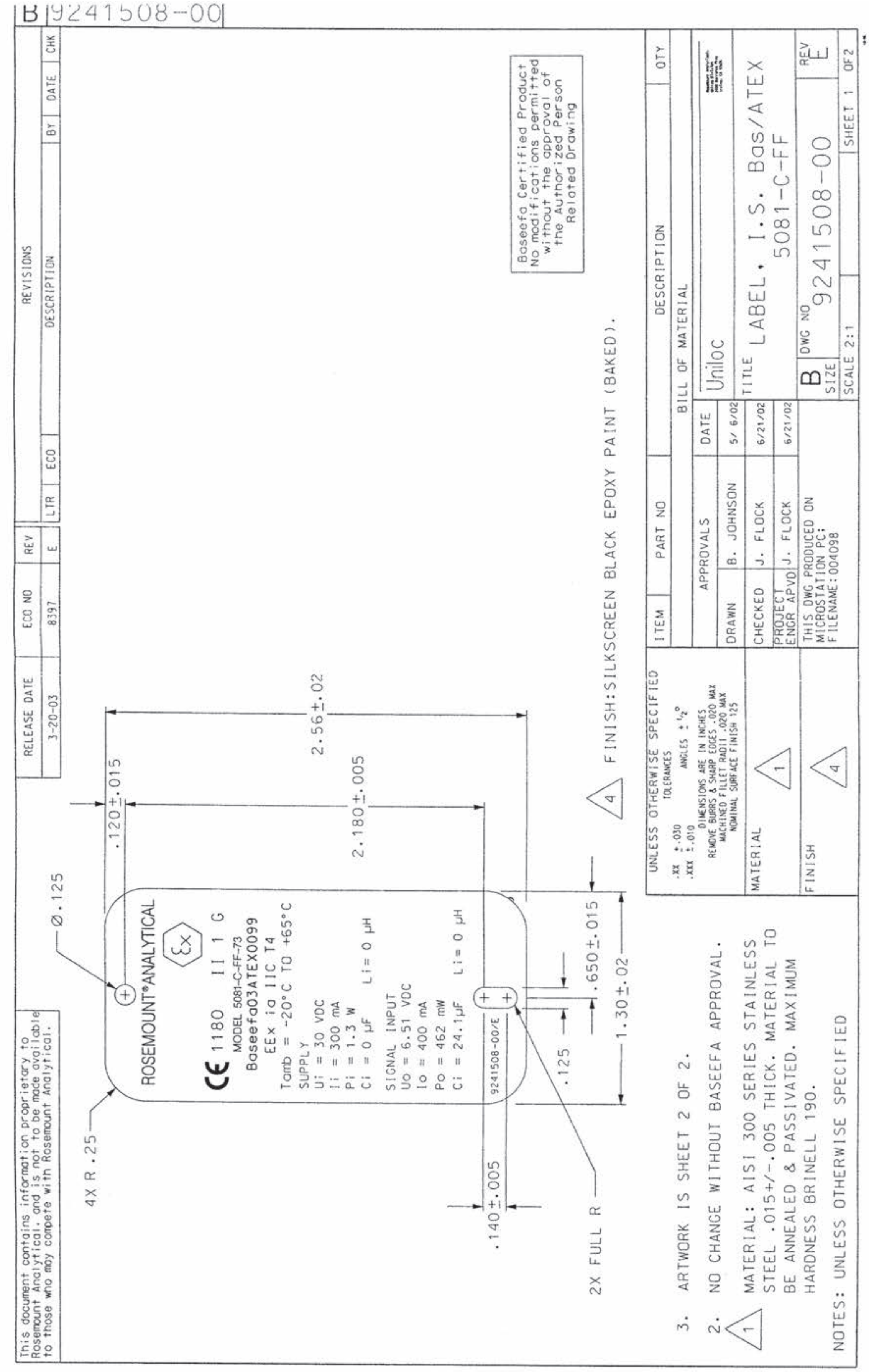



**FIGURE 4-13. ATEx Intrinsically Safe Label for Model 5081-C-FF**

# SECTION 5.0
# DISPLAy AND OPERATION



## 5.1 DISPLAyS

Figure 5-1 shows the process display screen, and Figure 5-2 shows the program display screen.

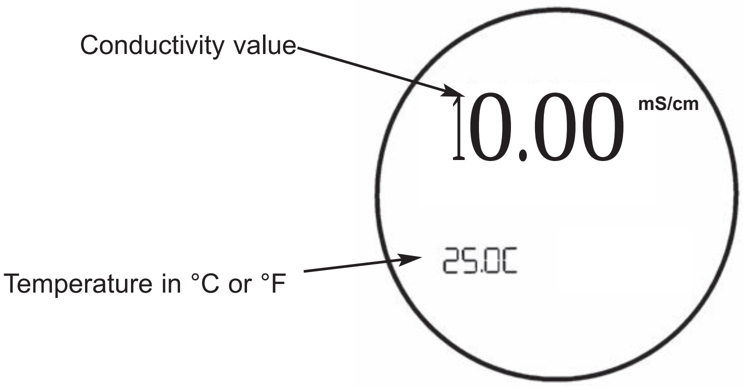



**FIGURE 5-1. Process Display Screen**
The process display screen appears during normal operation.

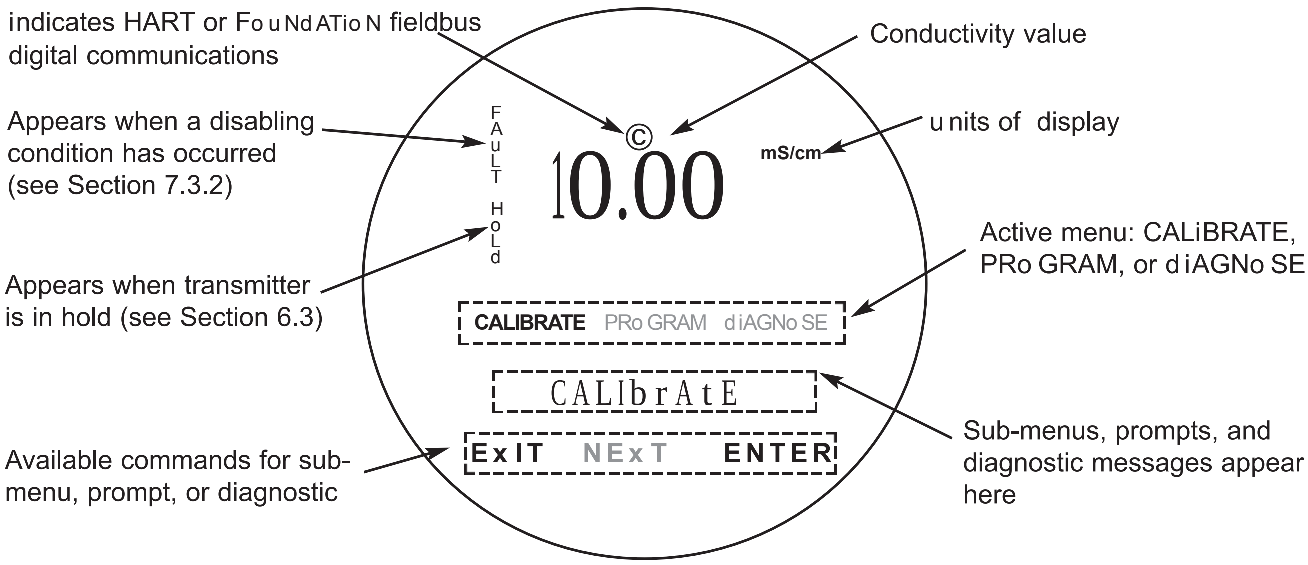



**FIGURE 5-2. Program Display Screen**
The program display screen appears when calibrating, programming, or reading diagnostic messages.

## 5.2 INFRARED REMOTE CONTROLLER (IRC) - KEy FUNCTIONS

The infrared remote controller is used to calibrate and program the transmitter and to read diagnostic messages. See Figure 5-3 for a description of the function of the keys.

**RESET -** Press to end the current operation and return to the process display. Changes will NoT be saved. RESET does not return the transmitter to factory default settings.

**Editing Keys -** use the editing keys to change the value of a flashing display. The left and right arrow keys move the cursor one digit at a time across a number. The up and down arrow keys increase or decrease the value of the selected digit. The up and down arrow keys also scroll the display through the items in a list.

**CAL -** Press to access the calibrate menu.*

**PROG -** Press to access the program menu.*

**DIAG -** Press to view diagnostic messages.*

** Pressing CAL, PROG, or DIAG causes the program screen to appear with the selected menu (CALIBRATE, PROGRAM, OR DIAGNOSE) showing. See Figure 5-2. The first sub-menu (or the first diagnostic message) also appears. Figure 5-4 shows the complete menu tree.*




**HOLD -** Press to access the prompt that turns on or off the Hold function. HoLd puts the transmitter in hold mode and sets the output to a pre-programmed value. Press RESET to exit hold mode.

**ENTER -** Press to advance from a sub-menu to the first prompt under the sub-menu. Pressing ENTER also stores the selected item or value in memory and advances to the next prompt.

**NExT -** Press to advance to the next sub-menu.

**ExIT -** Press to end the current operation. The transmitter returns to the first prompt in the present sub-menu. Changes will NoT be saved.

**FIGURE 5-3. Infrared Remote Controller.**

Hold the iRC within 6 feet of the transmitter, and not more than 15 degrees from horizontal to the display window.

## 5.3 QUICK START FOR MODEL 5081-C-HT (HART)

1. o n the Remote, press PRo G, NEXT, NEXT, ENTER.
2. u se the arrow buttons to select **COnduc** (conductivity), **rStvty** (resistivity), or **CuSt** (custom curve) mode. Press ENTER. if you chose **ConduC** or **rStvty**, go to step 4.
3. if you selected **CuST**, you will see the Setup Custom screen. To move to the custom curve configuration menu, press ENTER. You will automatically return to this same Setup Custom screen after configuration is complete. To continue transmitter display programming, press NEXT in the Setup Custom screen.
4. u se the arrow keys to toggle temperature units between Celsius and Farenheit.
5. Press ENTER then RESET.
6. Press PRo G, NEXT, ENTER.
7. u se the arrow key to toggle **t AutO** to o n or o FF to select using either the process temperature (**tAutO** = o n) or a manual temperature (**tAutO** = o FF). Press ENTER. if you selected **t AutO** = o FF, you will be prompted to enter the manual temperature; use the arrow keys, then press ENTER.
8. if you selected **CondUC** or **rStvty** in step 2, you will see a **COMP** (Temperature Compensation type) screen. u se the arrow keys to select desired temperature compensation: **LinEAr** (linear), **n SALt** (neutral salt), **CatIOn** (cation conductivity), or **nOnE** (raw or uncompensated conductivity). Press ENTER. if you are in **LinEAR** mode, you can now enter a particular temperature slope (default is 2%/degC), then press ENTER to apply the slope.
9. Press RESET.
10. Press CAL, NEXT four times, then ENTER.
11. u se the arrow buttons to enter the cell constant of the sensor. Press ENTER.
12. if you are in **rStvty**, **n SALt**, **Cation**, or **nOne** (raw) mode, quick start is complete, proceed to step 20.
13. if you are in **LinEAR** mode, press EXiT, CAL, NEXT, ENTER.
14. Hold the sensor in air to zero. Press ENTER. **PrOCESSIng** will appear briefly. Press EXiT.
15. Place the sensor in a solution of known conductivity value. Press CAL, ENTER.
16. u se the arrow buttons to enter the current conductivity value of the solution. Press ENTER.
17. Press RESET.

**To reset transmiter to factory default settings:**

1. Press PRo GRAM, then NEXT five times. The screen should say "**dEFAULt**". Press ENTER.
2. u se the arrow keys to toggle between **nO** (retain your configuration and calibration settings) and **y ES** (restore factory default settings to all variables).
3. Press ENTER, then EXiT.

## 5.4 QUICK START FOR MODEL 5081-C-FF (FOUNDATION FIELDBUS)

1. o n the Remote, press PRo G, NEXT, ENTER.
2. u se the arrow buttons to select **COnduc** (conductivity), **rStvty** (resistivity), or **CuSt** (custom curve) mode. Press ENTER. if you chose **ConduC** or **rStvty**, go to step 4.
3. if you selected **CuST**, you will see the Setup Custom screen. To move to the custom curve configuration menu, press ENTER. You will automatically return to this same Setup Custom screen after configuration is complete. To continue transmitter display programming, press NEXT in the Setup Custom screen.
4. u se the arrow keys to toggle temperature units between Celsius and Farenheit.
5. Press ENTER then RESET.
6. Press PRo G, ENTER.
7. u se the arrow key to toggle **t AutO** to o n or o FF to select using either the process temperature (**tAutO** = o n) or a manual temperature (**tAutO** = o FF). Press ENTER. if you selected **t AutO** = o FF, you will be prompted to enter the manual temperature; use the arrow keys, then press ENTER.
8. if you selected **CondUC** or **rStvty** in step 2, you will see a **COMP** (Temperature Compensation type) screen. u se the arrow keys to select desired temperature compensation: **LinEAr** (linear), **n SALt** (neutral salt), **CatIOn** (cation conductivity), or **nOnE** (raw or uncompensated conductivity). Press ENTER. if you are in **LinEAR** mode, you can now enter a particular temperature slope (default is 2%/degC), then press ENTER to apply the slope.
9. Press RESET.
10. Press CAL, NEXT, NEXT, NEXT, NEXT, ENTER.
11. u se the arrow buttons to enter the cell constant of the sensor. Press ENTER.
12. if you are in **rStvty**, **n SALt**, **Cation**, or **nOne** (raw) mode, quick start is complete, proceed to step 20.
13. if you are in **LinEAR** mode, press EXiT, CAL, NEXT, ENTER.
14. Hold the sensor in air to zero. Press ENTER. **PrOCESSIng** will appear briefly. Press EXiT.
15. Place the sensor in a solution of known conductivity value. Press CAL, ENTER.
16. u se the arrow buttons to enter the current conductivity value of the solution. Press ENTER.
17. Press RESET.

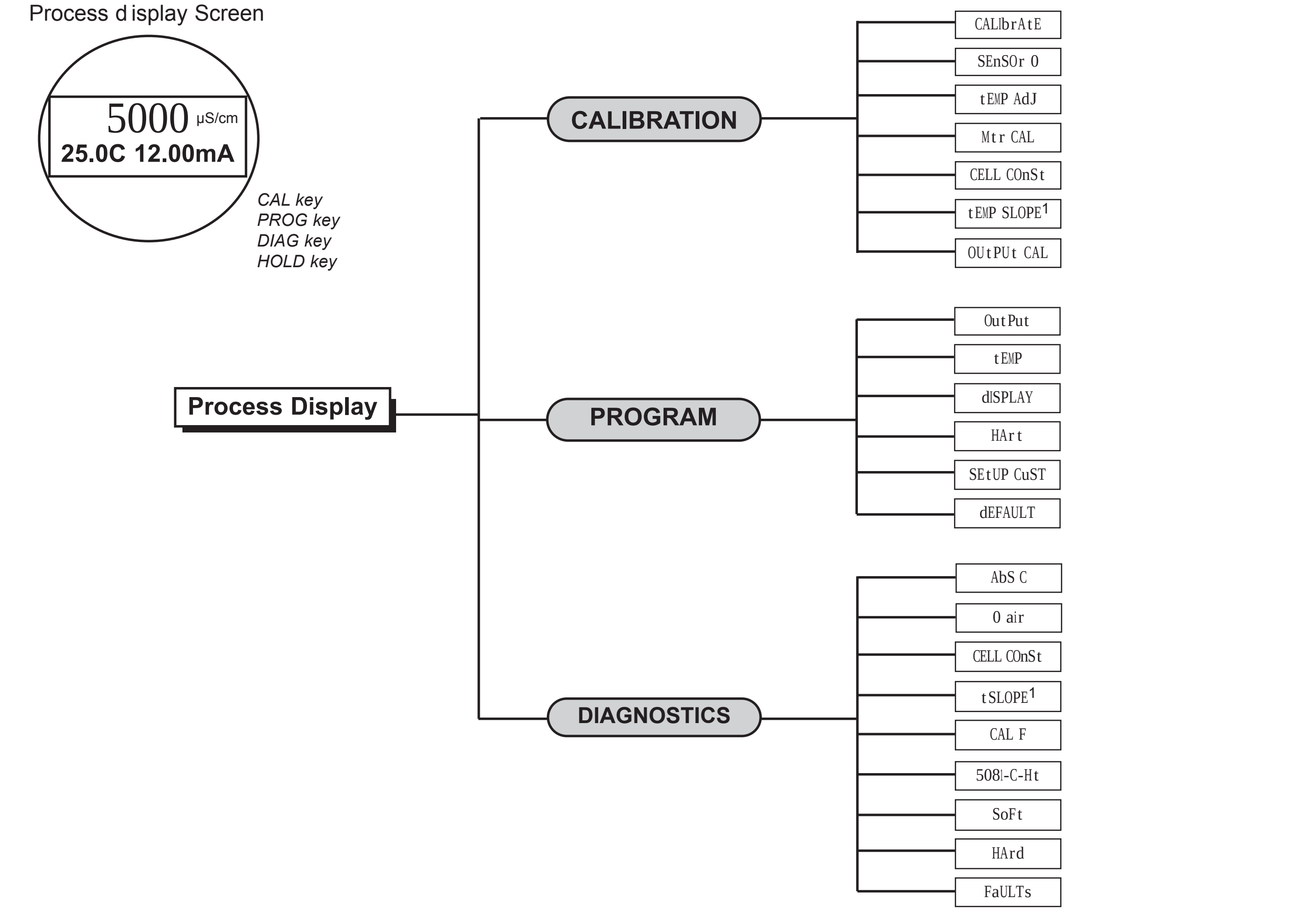
**To reset transmiter to factory default settings:**

1. Press PRo GRAM, NEXT, NEXT, NEXT. The screen should say "**dEFAULt**". Press ENTER.
2. u se the arrow keys to toggle between **nO** (retain your configuration and calibration settings) and **y ES** (restore factory default settings to all variables).
3. Press ENTER, then EXiT.

## 5.5 MENU TREE - Conductivity

The Model 5081-C pH transmitter has three menus: CALiBRATE, PRo GRAM, and d iAGNo SE. u nder the Calibrate and Program menus are several sub-menus. Figure 5-4 shows the complete menu tree for Model 5081-C-HT. Figure 5-5 shows the complete menu tree for Model 5081-C-FF.

**FIGURE 5-4. Menu Tree for Model 5081-C-HT**




**Program Menu Mnemonics**

| | |
|---|---|
| OUtPUt | Current output menu header |
| 4MA | 4mA current output (setpoint) |
| 20MA | 20mA current output (setpoint) |
| HoLd | Current output on hold |
| FAULt | Fault condition current output setting |
| dPn | Current output dampening time |
| tESt | Current output test value |
| tEMP | Temperature menu header |
| tAUtO | Automatic temperature compensation |
| tMAn | Manual temperature compensation input |
| dISPLAY | d isplay menu header |
| tYP | Conductivity measurement type |
| tEMP | °C / °F toggle selection |
| OUtPUt | Current (mA) or percent of full scale display |
| COdE | Security code |

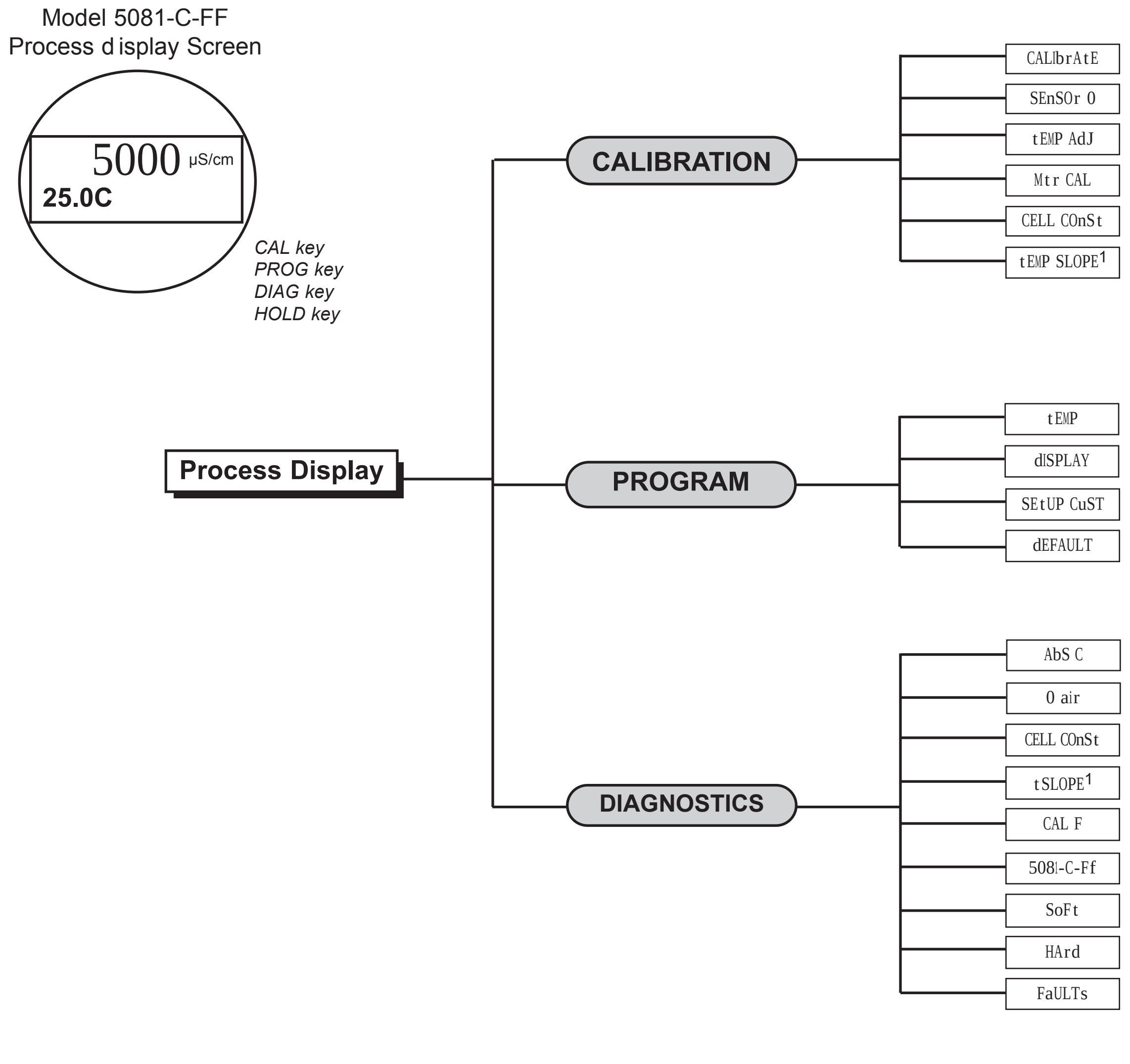



**FIGURE 5-5. Menu Tree for Model 5081-C-FF**

**Program Menu Mnemonics**

| | |
|---|---|
| HoLd | Transmitter on hold |
| FAULt | System disability fault condition |
| dPn | Current output dampening time |
| tEMP | Temperature menu header |
| tAUtO | Automatic temperature compensation |
| tMAn | Manual temperature compensation input |
| dISPLAY | d isplay menu header |
| tYP | Conductivity measurement type |
| tEMP | °C / °F toggle selection |
| COdE | Security code |

## 5.6 DIAGNOSTIC MESSAGES

Whenever a warning or fault limit has been exceeded, the transmitter displays diagnostic messages to aid in troubleshooting. d iagnostic messages appear in the same area as the temperature/output readings in the process display screen (see Figure 5-2). The display alternates between the regular display and the diagnostic message. Figure 5-4 shows the diagnostic fault messages for conductivity for Model 5081-C-HT. Figure 5-4 shows the diagnostic fault messages for conductivity for Model 5081-C-FF. if more than one warning or fault message has been generated, the messages appear alternately.

See Section 8.0, Troubleshooting, for the meanings of the fault and warning messages.

## 5.7 DEFAULT SETTINGS

Table 5-1 shows the diagnostic fault messages for pH for Model 5081-C-FF. Table 5-2 shows the diagnostic fault messages for pH for Model 5081-C-HT.

**TABLE 5-1. Default Settings for Model 5081-C-FF**

| vARIABLE NAME | MNEMONIC | FACTORy SETTINGS | CUSTOMER SETTINGS |
|---|---|---|---|
| **Program Menu** | | | |
| **Temperature** | **temp** | | |
| Auto temperature compensation | tauto | on | ________ |
| Manual temperature | tman | 25.0°C (overridden by auto) | ________ |
| Temperature compensation algorithm | COMP (Linear or n salt or Cation or nOnE) | LinEAr | ________ |
| **Display** | **display** | | |
| Measurement type | typ (ConduC or rstvty or Cust) | ConduC | ________ |
| Temperature (°C or °F) | temp | C | ________ |
| Security Code | code | 000 | ________ |
| **Custom Curve** | **SEtUP** | **CuSt** | ________ |
| Reference temperature | t ref | 25.0°C | ________ |
| **Calibrate Menu** | | | |
| Cell constant | CELL Const | 1.00 | ________ |
| Temperature slope | tEMP slOpe | 2.000 | ________ |
| **Diagnose Menu** | | | |
| **Diagnose** | | **SAMPLE READINGS** | |
| (Each segment displays the current value in the transmitter.) | | | |
| Absolute conductivity | Abs | 1000 µS | ________ |
| o ff Set | 0 Air | 0.0 µS | ________ |
| Cell constant (Linear mode) | CELL COnSt | 1.000 | ________ |
| Temperature slope | tslope | 2.000 | ________ |
| Calibration factor | CAL F | 1.000 | ________ |
| Software version | soft | A02.10 | ________ |
| Hardware version | HArd | 01 | ________ |
| Show fault warnings | FaULTS | none | ________ |

**TABLE 5-2. Default Settings for Model 5081-C-HT**

| vARIABLE NAME | MNEMONIC | FACTORy SETTINGS | CUSTOMER SETTINGS |
|---|---|---|---|
| **Program Menu** | | | |
| **Output** | **Output** | – | ________ |
| 4 mA | 4 mA | 0 µS | ________ |
| 20 mA | 20 mA | 20 mS | ________ |
| Hold | hold | 21 mA | ________ |
| Fault | fault | 22 mA | ________ |
| dampening | dpn | 0 samples/second | ________ |
| Test | test | 04.00 mA | ________ |
| **Temperature** | **temp** | | |
| Auto temperature compensation | tauto | on | ________ |
| Manual temperature | tman | 25.0°C (overridden by auto) | ________ |
| Temperature compensation algorithm | COMP (Linear or n salt or Cation or nOnE) | LinEAr | ________ |
| **Display** | **display** | | |
| Measurement type | typ (ConduC or rstvty or Cust) | ConduC | ________ |
| Temperature (°C or °F) | temp | C | ________ |
| output (mA or %) | output | Cur | ________ |
| Security Code | code | 000 | ________ |
| **Custom Curve** | **SEtUP** | **CuSt** | ________ |
| Reference temperature | t ref | 25.0°C | ________ |
| **Calibrate Menu** | | | |
| Cell constant | CELL Const | 1.00 | ________ |
| Temperature slope | tEMP slOpe | 2.000 | ________ |
| output Calibration | OUtPUt CAL | | ________ |
| **Diagnose Menu** | | | |
| **Diagnose** | | **SAMPLE READINGS** | |
| (Each segment displays the current value in the transmitter.) | | | |
| Absolute conductivity | Abs | 1000 µS | ________ |
| off Set | 0 Air | 0.0 µS | ________ |
| Cell constant (Linear mode) | CELL COnSt | 1.000 | ________ |
| Temperature slope | tslope | 2.000 | ________ |
| Calibration factor | CAL F | 1.000 | ________ |
| Software version | soft | A02.18 | ________ |
| Hardware version | HArd | 01 | ________ |
| Show fault warnings | FaULTS | none | ________ |

## 5.8 SECURITy

**5.8.1 General.** use the programmable security code to protect program and calibration settings from accidentally being changed. The transmitter is shipped with the security feature disabled. To program a security code, refer to Section 8.6, display units.




**5.8.2 Entering the Security Code.**

1. if calibration and program settings are protected with a security code, pressing PRoG or CAL on the infrared remote controller causes the **Id** screen to appear.
2. use the editing keys to enter the security code. Press ENTER .
3. if the security code is correct, the first sub-menu appears. if the security code is incorrect, the process display reappears.

**5.8.3 Retrieving a Lost Security Code.**

1. if the security code has been forgotten, enter 555 at the **Id** prompt and press ENTER . The transmitter will display the present code.
2. Press EXiT to return to the process display.
3. Press PRoG or CAL . The **Id** screen appears.
4. use the editing keys to enter the security code just shown; then press ENTER .
5. The first sub-menu under the selected menu will appear.

## 5.9 USING HOLD

during calibration, the sensor may be exposed to solutions having concentration outside the normal range of the process. To prevent false alarms and undesired operation of chemical dosing pumps, place the transmitter in hold during calibration. Activating hold keeps the transmitter output at the last value or sends the output to a previously determined value. See Section 7.3, output Ranging, for details.

After calibration, reinstall the sensor in the process stream. Wait until readings have stabilized before deactivating Hold.

To activate or deactivate Hold:

1. Press HoLd on the remote controller.
2. The **HoLd** prompt appears in the display. Press ↑ or ↓ to toggle Hold between **On** and **OFF**.
3. Press ENTER to save.

# SECTION 6.0
# START-UP AND CALIBRATION

## 6.1 ACCESSING THE CALIBRATE MENU

The “Calibrate” menu is used to calibrate the transmitter to known temperature and conductivity values. This menu also contains the temperature calibration operation to establish the temperature slope.

Figure 6-1 illustrates the relationship between the Calibrate Menu and its sub-menus. Each sub-menu leads to a series of prompts that are used for calibration.

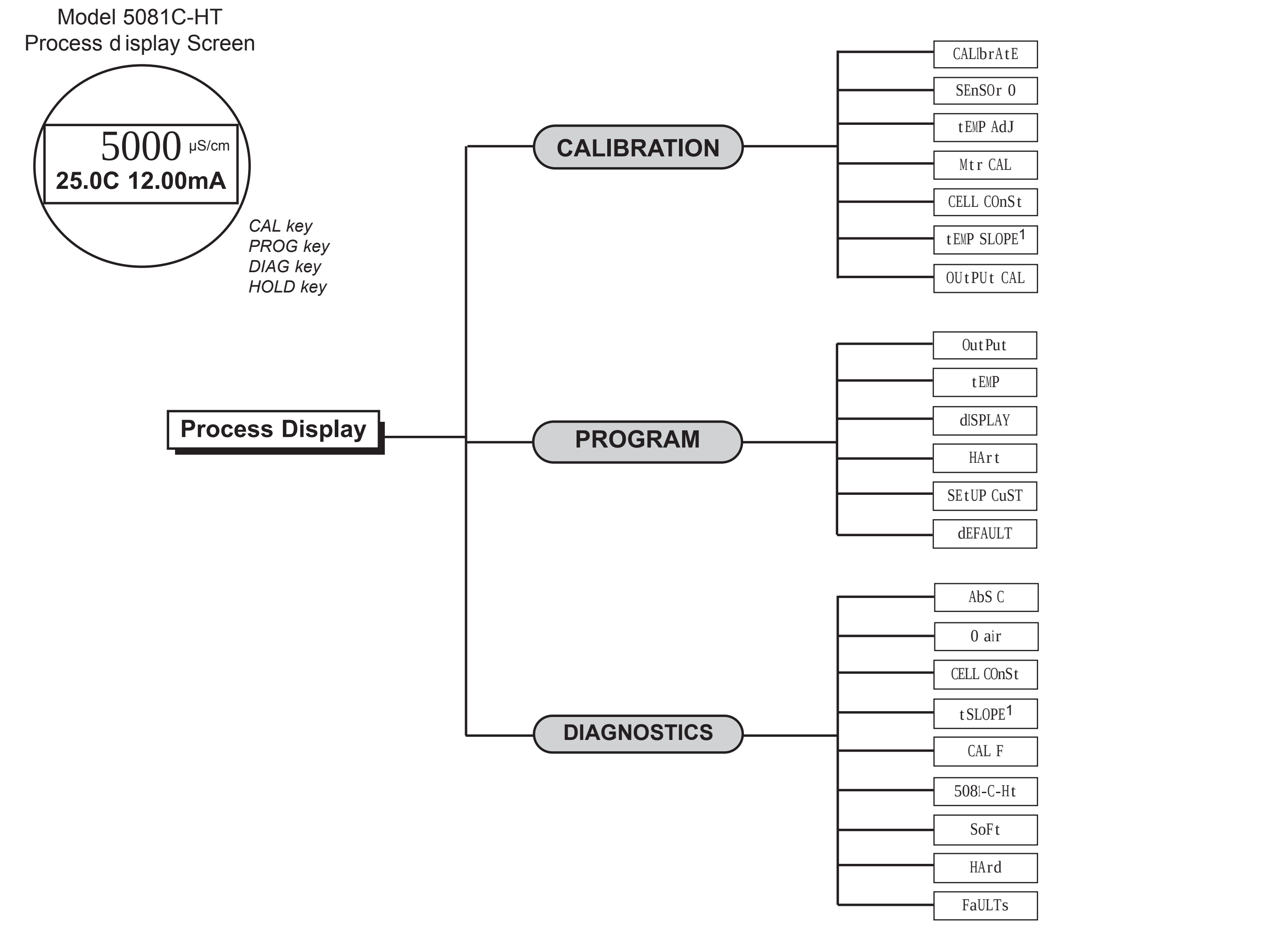


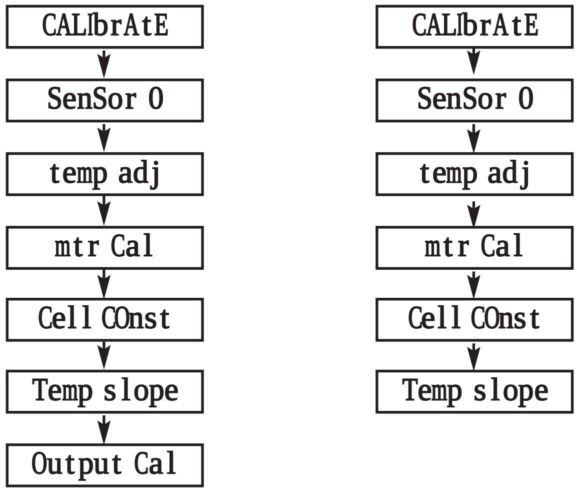

FIGURE 6-1. Menu Tree

## 6.2 CALIBRATE MENU

To access the “Calibrate” menu, press the CAL key on the infrared Remote Control. if security has been enabled, the secondary process display will be replaced with a prompt asking for the “id”. using the iRC editing keys, enter the “id”. if the correct “id” is entered, the **CALibrAtE** sub-menu will appear when ENTER is pressed.

if the **CALibrAtE** sub-menu does not appear when ENTER is pressed, see Section 4.4 (step 8) for procedure to find correct code.

**Model 5081-C-HT** **Model 5081-C-FF**




### 6.2.1 Calibrate

1. With the sensor in a standard solution of known conductivity value, allow the temperature of the sensor to stabilize (10 min).
2. To access the **CALIbrAtE** menu, press the CAL button on the iRC.
3. Press ENTER to access the **CAL** segment with flashing prompt.
4. use the iRC editing keys to indicate the conductivity values of the standard solution on the screen.
5. Press ENTER then EXiT to enter the standard solution value and return to the main screen.

### 6.2.2 Sensor 0

From the main screen, press CAL, then press NEXT to enter the **SEnSOr 0** menu. Press ENTER to access the **SEnSOr 0** sub-menu. With the sensor attached and in air, press ENTER again to zero the sensor. Press EXiT to return to the **SEnSOr 0** sub-menu.

### 6.2.3 Temp Adj

1. Press NEXT and then ENTER to access the **tEMP** sub-menu with flashing prompt. With the sensor in any solution of known temperature, allow the temperature of the sensor to stabilize. use the editing keys of the iRC to change the displayed value as needed.
2. Press ENTER to standardize the temperature reading and return to the **tEMP Adj** screen.

### 6.2.4 Mtr Cal

For maximum accuracy, calibrate the sensor in the process. This is labeled **Mtr CAL** on the 5081C and should be done after the initial transmitter calibration and periodically thereafter as required.

To access **Mtr CAL** from the main screen, press CAL, then NEXT three times. Refer to Section 6.4 for the procedure.

on-line calibration is well-suited for most conductivity measurements except ultra pure conductivity and resistivity measurements. These special applications require specialized tools to perform an accurate on-line comparison. A certified conductivity instrument with a certified flow-through conductivity cell, like the Rosemount Portable Validation instrument, can be used for this purpose.

### 6.2.5 Cell Constant

1. When the **CALibrAtE** sub-menu has been accessed, press NEXT four (4) times and then ENTER to access the **CELL COnSt** menu segment with the flashing cell constant prompt.
2. using the arrow keys on the iRC, enter your sensor’s cell constant as indicated on the sensor’s tag or specification sheet.
3. Press ENTER to save the cell constant into the transmitter memory and return to the **CELL COnSt** sub-menu.

### 6.2.6 Temp Slope

1. Press NEXT to enter the **tEMP SLOPE** menu.

   The correct temperature slope must be entered into the transmitter to ensure an acceptable process variable measurement under fluctuating process temperature conditions. Enter the slope in measured conductivity units per degree temperature change using the iRC's arrow keys. Press ENTER to enter the slope into memory; then press EXiT to return to the main screen.

2. if the temperature slope of the process is not known but you wish to approximate it, refer to the following guide and press ENTER to proceed on to **tSLOPE** sub-menu with flashing prompt. utilize the iRC editing keys to generate the desired slope value. Press ENTER then EXiT to return to the main screen.

   Acids: 1.0 to 1.6% per °C    Bases: 1.8 to 2.2% per °C

   Salts: 2.2 to 3.0% per °C    Water: 2.0% per °C

### 6.2.7 Output Cal

Although the transmitter outputs are calibrated at the factory, they can be trimmed in the field to match the reading from a standard current meter. Both the 4 mA and the 20 mA outputs can be trimmed. during output calibration the transmitter is in Hold. The output current will go to the value programmed in Section 6.3.

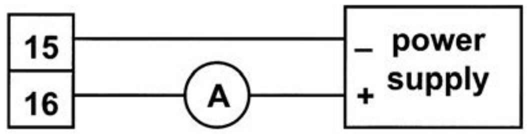



**FIGURE 6-2. Current Output Calibration**

**PROCEDURE**

CALiBRATE
OUtpUt CAL
EXiT NEXT ENTER

1. Wire an accurate milliammeter as shown in Figure 6-2.
2. Press CAL on the remote controller.
3. Press NEXT until the **OUtPUt CAL** submenu appears. Press ENTER.

CALiBRATE
Cur 4.000
EXiT NEXT ENTER

4. use the arrow keys to change the display to match the reading from the milliammeter. Press ENTER.

CALiBRATE
Cur 20.00
EXiT NEXT ENTER

5. use the arrow keys to change the display to match the reading from the milliammeter. Press ENTER. Press RESET to return to the main display.

**TABLE 6-1. CALIBRATE MENU MNEMONICS**

| | |
|---|---|
| CALIbrAtE | Calibrate menu header |
| CAL | Sensor calibration |
| tEMP SLOPE | Sub-menu header |
| Adj SLOPE | Sub-menu header |
| tSLOPE | Slope adjustment %/°C |
| CELL COnSt | Sub-menu header |
| SEnSOr | Sub-menu header |
| SEnSOr 0 | Sensor "0" (performed in air) |
| tEMP AdJ | Sub-menu header |
| tEMP | Temperature adjustment °C/°F |

# SECTION 7.0
# PROGRAMING

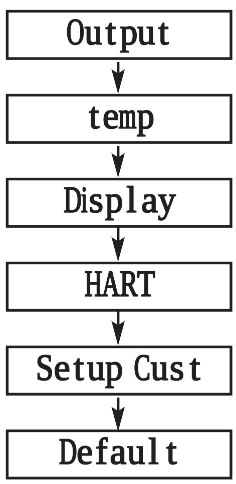


## 7.1 GENERAL

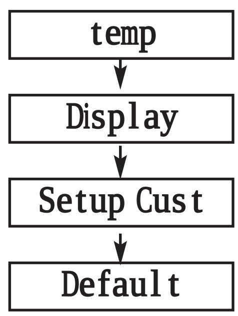
This section describes how to do the following:

1. assign values to the 4 and 20 mA outputs (for 5081-C-HT only)
2. set the current generated by the transmitter during hold (for 5081-C-HT only)
3. set the current generated by the transmitter when a fault is detected (for 5081-C-HT only)
4. change sensor diagnostic limits
5. enable and disable automatic temperature correction
6. program the type measurement
7. choose limits for diagnostic fault messages

**Model 5081-C-HT**




**Model 5081-C-FF**



## 7.2 OUTPUT

### 7.2.1 Purpose

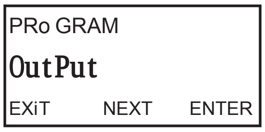
This section describes how to do the following:

1. assign values to the 4 and 20 mA outputs
2. set the output current generated during hold
3. set the output current generated when a fault is detected
4. control the amount of dampening on the output signal
5. generate a test current.

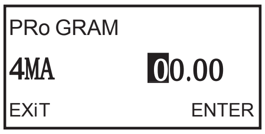
### 7.2.2 Definitions

1. Cu RRENT o u TPu TS. The transmitter provides a continuous 4 - 20 mA output directly proportional to the conductivity or resistivity.
2. Ho Ld . d uring calibration and maintenance the transmitter output may be outside the normal operating range. Placing the transmitter on hold prevents false alarms or the unwanted operation of chemical dosing pumps. The transmitter output can be programmed to remain at the last value or to generate any current between 3.80 and 22.00 mA. d uring hold, the transmitter displays the present concentration and temperature. The word Ho Ld appears in the display.
3. FAu LT. A fault is a system disabling condition. When the transmitter detects a fault, the following happens:
   a. The display flashes.
   b. The words FAu LT and Ho Ld appear in the main display.
   c. A fault or diagnostic message appears in the display.
   d. The output signal remains at the present value or goes to the programmed fault value. Permitted values are between 3.80 and 22.00 mA.
   e. if the transmitter is in Ho Ld when the fault occurs, the output remains at the programmed hold value. To alert the user that a fault exists, the word FAu LT appears in the main display, and the display flashes. A fault or diagnostic message also appears.
   f. if the transmitter is simulating an output current when the fault occurs, the transmitter continues to generate the simulated current. To alert the user that a fault exists, the word FAu LT appears in the display, and the display flashes.
4. d AMPEN. o utput dampening smooths out noisy readings. But it also increases the response time of the output. To estimate the time (in minutes) required for the output to reach 95% of the final reading following a step change, divide the setting by 20. Thus, a setting of 140 means that, following a step change, the output takes about seven minutes to reach 95% of final reading. The output dampen setting does not affect the response time of the process display. The maximum setting is 255.
5. TEST. The transmitter can be programmed to generate a test current.

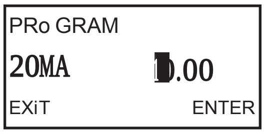
### 7.2.3 Procedure



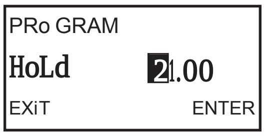

1. Press PRo G on the remote controller. The **OutPut** submenu appears.



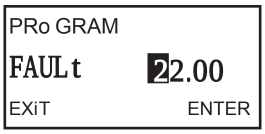

2. Press ENTER. The screen displays the **4 MA** prompt. u se the arrow keys to change the setting. Press ENTER to save.



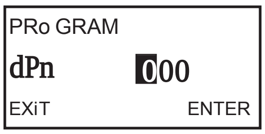

3. The screen displays the **20 MA** prompt. u se the arrow keys to change the setting. Press ENTER to save.



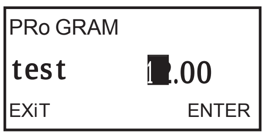

4. The screen displays the **HoLd** prompt. u se the arrow keys to change the setting to the output desired when the transmitter is in hold. The range is 3.80 to 22.00 mA. Entering 00.00 causes the transmitter to hold the output at the value it was when placed in hold. The hold setting overrides the fault setting. Press ENTER to save.




5. The screen displays the **FAULt** prompt. u se the arrow keys to change the setting to the output desired when the transmitter detects a fault. The range is 3.80 to 22.00 mA. Entering 00.00 causes the transmitter to hold the output at the value it was when the fault occurred. Press ENTER to save.




6. The screen displays the **dPn** prompt. u se the arrow keys to change the setting. The range is 0 to 255. Press ENTER to save.




7. The screen displays the **tESt** prompt. u se the arrow keys to enter the desired test current. Press ENTER to start the test. Press EXiT to end the test.

8. Press RESET to return to the process display.

## 7.3 TEMP

### 7.3.1 Purpose

This section describes how to do the following:

1. Enable and disable automatic temperature compensation
2. Set a manual temperature compensation value for conductivity measurements
3. Tell the transmitter the type of temperature element in the sensor

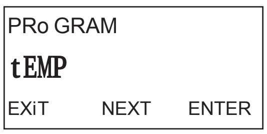
### 7.3.2 Definitions

1. Au To MATiC TEMPERATu RE Co MPENSATio N. Conductivity measurements are directly affected by temperature. A correction equation in the software automatically corrects for changes caused by temperature. in automatic temperature correction, the transmitter uses the temperature measured by the sensor for all calculations in which temperature is used.
2. MANu AL TEMPERATu RE Co MPENSATio N. in manual temperature compensation, the transmitter uses the temperature entered by the user as the reference temperature for corrections of conductivity readings. it does not use the actual process temperature.

**CAUTION**

Changing the reference temperature from the default 25°C (77°F) can have large effects on the conductivity readings and will require different temperature slopes.

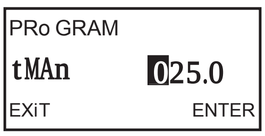
### 7.3.3 Procedure




1. Press PRo G on the remote controller.
2. Press NEXT until the **tEMP** submenu appears. Press ENTER.




3. The screen displays the **tAUtO** (automatic temperature compensation) prompt. Press ↑ or ↓ to toggle between **On** and **OFF**. Press ENTER to save.




4. if you disable tAuto, the **tMAN** prompt appears. u se the arrow keys to change the temperature to the desired value. To enter a negative number, press → or ← until no digit is flashing. Then press ↑ or ↓ to display the negative sign. **The temperature entered in this step will be used in all measurements, no matter what the process temperature is.** Press ENTER to save.

5. Press RESET to return to the process display.

## 7.4 DISPLAy

### 7.4.1 Purpose

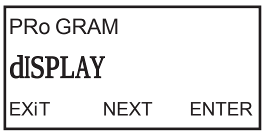
This section describes how to do the following:

1. Configure the transmitter to measure conductivity, resistivity, or set up a custom curve
2. Set the temperature units to °C or °F
3. Set the output to current or percent of full scale
4. Enter a security code.

### 7.4.2 Definitions

1. MEASu REMENT. The transmitter can be configured to measure conductivity in mS/cm or resistivity in Mego hms, or configured with a 3-5 point custom curve for special applications.
2. o u TPu T Cu RRENT. The transmitter generates a 4-20 mA output signal directly proportional to the conductivity or resistivity of the sample. The output signal can be displayed as current (in mA) or as percent of full scale.
5. SECu RiTY Co d E. The security code unlocks the transmitter and allows access to all menus.

### 7.4.3 Procedure







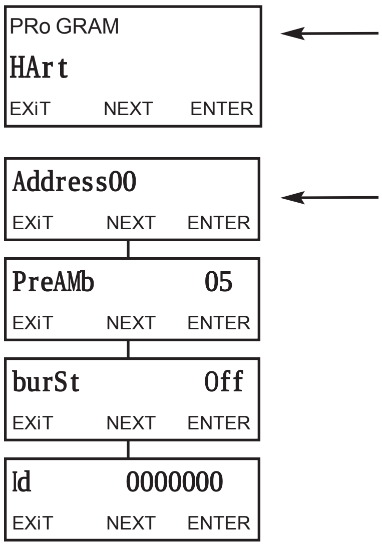
1. Press PRo G on the remote controller.
2. Press NEXT until the **diSPLAy** submenu appears. Press ENTER.
3. Press ↑ or ↓ to display the desired measurement. Press ENTER to save.

| | |
|---|---|
| **COnduc** | Conductivity |
| **rStvty** | Resistivity |
| **CuSt** | Custom Curve |

4. **tEMP** will appear. Press ↑ or ↓ to display the desired temperature reading, **C** or **F**. Press ENTER.
5. **OUtPUt** will appear. Press ↑ or ↓ to display the desired 4-20 output value, **Cur** or **%**. Press ENTER.
6. **COdE** will appear. u sing the arrow keys on the remote control, enter the desired 3-digit security code for accessing the Calibration, Program, and d iagnostic functions via the Remote Control handheld. Press ENTER. The **dISPLAy** mnemonic will appear.

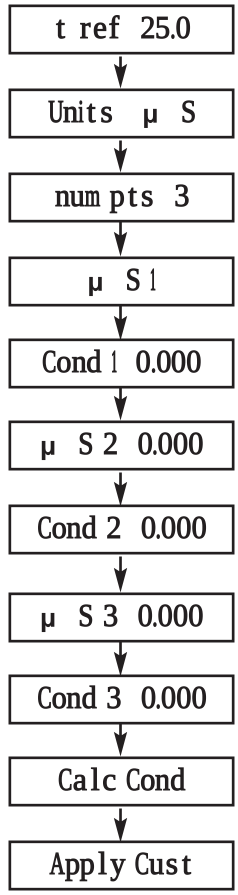
## 7.5 HART

in multi-drop operation, polling addresses can be more conveniently set and debugging more conveniently performed using the infrared remote controller.




1. Press PRo G on the infrared remote controller.
2. Press NEXT until the screen at left appears. Press ENTER.
3. The HART menu tree is shown at left. u se the arrow keys to change settings. Press ENTER to store. Press NEXT to move to the next item on the menu.

## 7.6 Setup Cust




The Model 5081-C contains a curve fitting program that can create a second order curve for 3 to 5 user supplied data points. if only two points are entered, a straight line will be used. These points are from numerical data previously collected that is entered via the keypad. All data point must be approximately the same reference temperature.

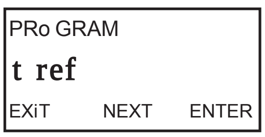
Best results will be obtained by selecting data points that are representative of the typical operating range and are at least 5% different conductivity values. Plotting the graph of conductivity vs. concentration for the data points of interest before using this procedure is highly recommended. This will insure that unsuitable points (i.e. two concentrations with the same conductivity) and critical points (that best describe the curve) can be determined. All data points should be either on the rising side of the conductivity versus concentration curve or the falling side, but not both (i.e. both side of the conductivity maximum or minimum). Following these guideline will simplify the data entry procedure and provide optimum results.

The first point entered "Co nd 1"should be at the normal operating condition. o ther points, both above and below "Co nd 1" can then be entered. Very nonlinear conductivity curves may need additional points to characterize these regions. d o not use the same data for more than one point and only use real data - do not interpolate.

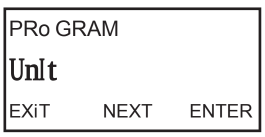
**NOTE**

The default values for the custom curve are three data points, reference temperature of 25°C and a linear temperature slope of 2%/°C. This combination will yield the best results in most applications. if normal operation is over 40°C or under 10°C, the reference temperature should be changed to the normal process temperature. if the temperature slope at the reference temperature is known, it can be used.

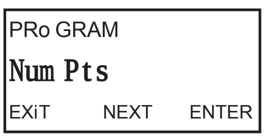
### 7.6.1 Procedure



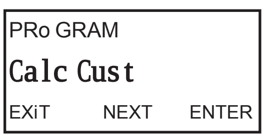

1. From the main menu, press PRo G; then press NEXT four times. **SetUP CuSt** will appear.
2. Press ENTER. **t rEF** will appear. if needed, change the reference temperature from the factory default 25°C (77°F) to a different reference temperature for the process. Press ENTER.




3. **UnIt** will appear. Press ↑ or ↓ to select the desired measurement units: µS (micro-Siemens), nS (milliSiemens), none (no units displayed), % (percent), or ppn (parts per million); then press ENTER.




4. **NUM PtS** will appear. Press ↑ or ↓ to select the desired number of data points for a custom conductivity curve. Selecting 2 will generate a linear relationship for conductivity and concentration at the given reference temperature.
   a. Enter the concentration for Pt. 1 (displayed as **µS 1**). Press ENTER.
   b. Enter the known conductivity for Pt. 1 in µS/cm. Press ENTER.
   c. Complete this process for additional known data points. Press ENTER.




5. **CALC Cust** will appear briefly. Press ENTER. **PrOCESSinG** will appear briefly; then **APPLy CUSt** will appear. Press ENTER to enter the custom curve into memory and return to the **SetUP CuSt** screen.

The Custom curve will now be used to display and output all conductivity (or resistivity) measurements if **Cust** is selected in the d isplay menu for measurement type.

## 7.7 DEFAULT

### 7.7.1 Purpose

This section describes how to erase ALL user-defined configuration settings and return the transmitter to factory default settings. All custom curve values and settings will be deleted.

### 7.7.2 Procedure

PRo GRAM
dISPLAY
EXiT NEXT ENTER

PRo GRAM
tYPE 02
EXiT ENTER

1. Press PRo G on the remote controller.
2. Press NEXT until the **dEFAULt** appears in the display. Press ENTER.
3. u se ↑ or ↓ to toggle between **nO** and **yES**. With **yES** showing, press ENTER to return to factory default settings.

# SECTION 8.0
# FOUNDATION FIELDBUS OPERATION

This section covers basic transmitter operation and software functionality. For detailed descriptions of the function blocks common to all Fieldbus devices, refer to Fisher-Rosemount Fieldbus FouNdATioN Function Blocks manual, publication number 00809-001-4783.

Figure 8-1 illustrates how the pH/oRP signal is channelled through the transmitter to the control room and the FouNdATioN Fieldbus configuration device.

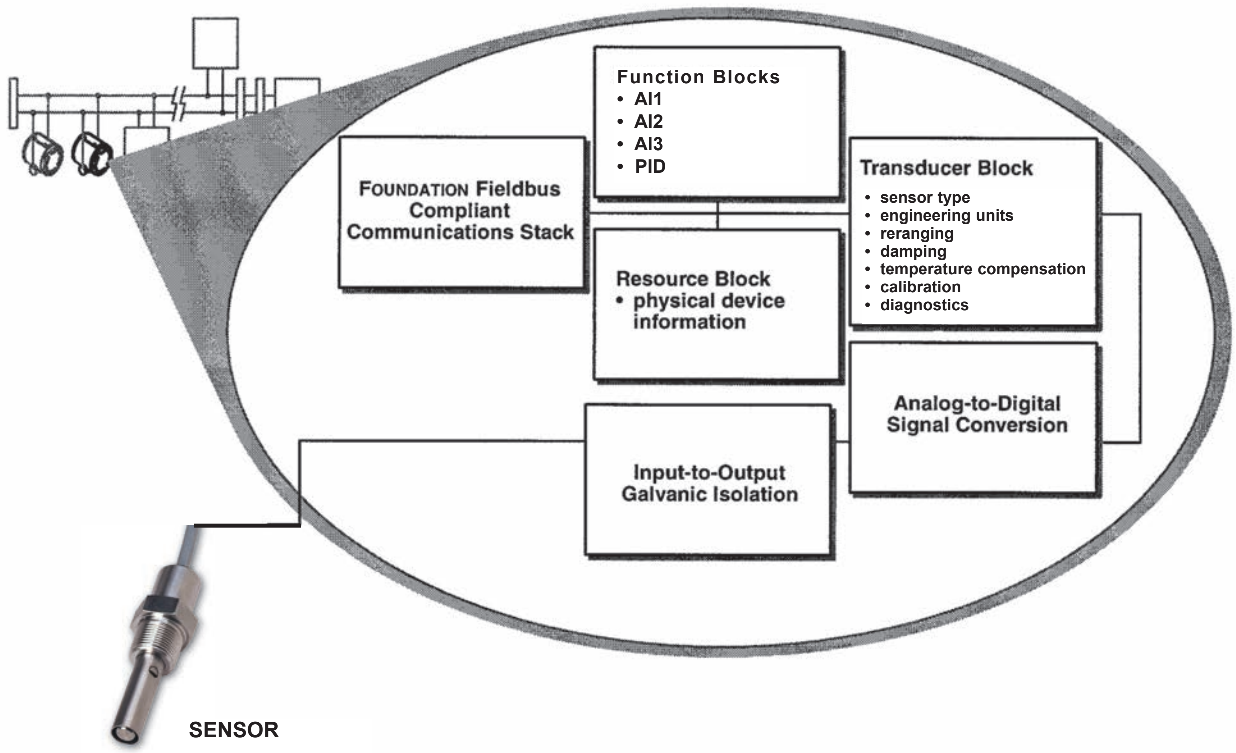



**FIGURE 8-1. Functional Block Diagram for the Model 5081-C-FF Conductivity Transmitter with FOUNDATION Fieldbus.**

**Software Functionality.** The Model 5081-C software is designed to permit remote testing and configuration of the transmitter using the Fisher-Rosemount deltaV Fieldbus Configuration Tool, or other FouNdATioN fieldbus compliant host.

**Transducer Block.** The transducer block contains the actual measurement data. it includes information about sensor type, engineering units, reranging, damping, temperature compensation, calibration, and diagnostics.

**Resource Block**. The resource Block contains physical device information, including available memory, manufacturer identification, type of device, and features.

**FOUNDATION fieldbus Function Blocks.** The Model 5081-C includes three Analog input (Ai) function blocks and one Pid function block as part of its standard offering.

**Analog Input.** The Analog input (Ai) block processes the measurement and makes it available to other function blocks. it also allows filtering, alarming, and engineering unit change.

**PID.** The Pid function block combines all of the necessary logic to perform proportional/integral/derivative (Pid) control. The block supports mode control, signal scaling and limiting, feedforward control, override tracking, alarm limit detection, and signal status propagation.

# SECTION 9.0
# OPERATION wITH MODEL 375

## 9.1 Note on Model 375 or 475 Communicator

The Model 375 or 475 Communicator is a product of Emerson Process Management, Rosemount inc. This section contains selected information on using the Model 375 or 475 with the Rosemount Analytical Model 5081-C-HT Transmitter. For complete information on the Model 375 or 475 Communicator, see the Model 375 or 475 instruction manual. For technical support on the Model 375 or 475 Communicator, call Emerson Process Management at (800) 999-9307 within the united States. Support is available worldwide on the internet at *http://rosemount.com*.

**Note:** Model 475 Communicator does not support FouNdATioN Fieldbus on Model 5081-C-FF.

## 9.2 Connecting the Communicator

Figure 9-1 shows how the Model 475 or 375 Communicator connects to the output lines from the Model 5081-C-HT Transmitter.

**CAUTION**

For intrinsically safe CSA and FM wiring connections, see the Model 375 instruction manual.

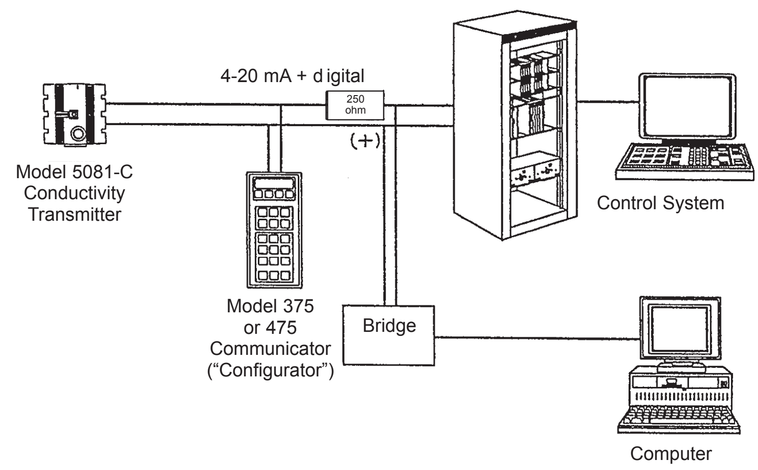



**FIGURE 9-1. Connecting the HART Communicator**

## 9.3 Operation

### 9.3.1 Off-line and On-line Operation

The Model 375 Communicator features off-line and on-line communications. On-line means the communicator is connected to the transmitter in the usual fashion. While the communicator is on line, the operator can view measurement data, change program settings, and read diagnostic messages. Off-line means the communicator is not connected to the transmitter. When the communicator is off line, the operator can still program settings into the communicator. Later, after the communicator has been connected to a transmitter, the operator can transfer the programmed settings to the transmitter. Off-line operation permits settings common to several transmitters to be easily stored in all of them.

### 9.3.2 Making HART related settings from the keypad

```
Calibrate          Hold
Program         Display
```

1. Press MENU. The main menu screen appears. Choose **Program**.

```
Output             Temp
Measurement          >>
```

2. Choose **>>**.

```
Security           HART
                     >>
```

3. Choose **HART**.

```
DevID         PollAddrs
Burst          Preamble
```

4. To display the device ID, choose **DevID**. To change the polling address, choose **PollAddrs**. To make burst mode settings, choose **Burst**. To change the preamble count, choose **Preamble**.

### 9.3.3 Menu Tree

The menu tree for the Model 375 HART communicator is on the following page. The menu tree for the Model 375 FOUNDATION Fieldbus communicator immediately follows.

**Note:** Model 375 Communicator fully supports FOUNDATION Fieldbus on Model 5081-C-FF.

```
--------------------------------------------------------------------------------
5081C 475, 375 Menu Tree for HART communications
--------------------------------------------------------------------------------
d evice setup
   Process variables
      Cond *
      Raw
      Conductance
      Temp
      Temp res
      View status
   d iag/Service
      Test device
         Loop test
         View status
         Master reset
         Fault history
      Hold mode
      Calibration
         Calibrate sensor
         Zero in air
         Zero in solution **
         Adjust temperature
         Calibrate input
         Cell constant
         Temp slope
      d /A trim
      d iagnostic vars
         Cond *
         Temp
         Cell constant
         Zero offset
         Soln offset **
         Temp slope ***
         input cal factor
   Basic setup
      Tag
      PV range values
         PV LRV
         PV u RV
         PV
         PV % rnge
```

**FIGURE 9-2. 5081-C-HT HART/Model 375 Menu Tree (1 of 4)**

- Basic setup (continued)
  - d evice information
    - d istributor
    - Model
    - d ev id
    - Tag
    - d ate
    - Physicl signl code
    - Write protect
    - Snsr text
    - d escriptor
    - Message
    - Revision #'s
      - u niversal rev
      - Fld dev rev
      - Software rev
      - Hardware rev
- d etailed setup
  - Sensors
    - Main sensor
      - PV Type [Conductivity, Resistivity, 0-12% Nao H, 0-15% HCl, 0-25% H2So 4, 96-99.7% H2So 4, Custom]
      - PV Snsr unit [uS/cm, mS/cm, mS/m, Mohm-cm, %, ppm, _]
      - Cond unit [uS/cm, mS/cm, mS/m] ****
      - d efine curve ****
      - View custom points ****
      - Cell constant
      - Temp comp type [Linear, Neutral salt, Cation, None/o ff] *..
      - Temp slope
      - Ref temp ***, ****, *.
      - PV sensor type
      - Sensor information
        - LSL
        - u SL
        - Min span
    - Temperature
      - ATC [o n, o ff]
      - Man temp
      - Temp unit [ºC, ºF]
      - Temp snsr [RTd PT100, RTd PT1000]
    - d iag override (continued)
      - o ffset error [o N, o FF]
      - Zero warning [o N, o FF]
      - o verrange [o N, o FF]
      - Sensor fail [o N, o FF]

**FIGURE 9-2. 5081-C-HT HART/Model 375 Menu Tree (2 of 4)**

d iag override (continued)
RTd fail [o N, o FF]
Sense line open [o N, o FF]
Temp high/low [o N, o FF]
Signal condition
LRV
u RV
Ao d amp
% rnge
Xfer fnctn
Ao 1 lo end point
Ao 1 hi end pt
o utput condition
Analog output
Ao 1
Ao Alrm typ
Fixed
Fault
Loop test
d /A trim
HART output
PV is Cond
SV is Temp
TV is Raw
Poll addr
Burst option [PV, %range/current, Process vars/crnt]
Burst mode [o ff, o n]
Num req preams
Num resp preams
d evice information
d istributor
Model
d ev id
Tag
d ate
Write protect
Snsr text
d escriptor
Message
Revision #'s
u niversal rev
Fld dev rev
Software rev
Hardware rev

**FIGURE 9-2. 5081-C-HT HART/Model 375 Menu Tree (3 of 4)**

Local display
Ao Lo i units [mA, %]
Xmtr id
Load default Conf.
Review
PV
PV Ao
PV LRV
PV uRV
--------------------------------------------------------------------------------

Notes:
* Can be Cond, Res, NaoH, HCl, H2So4, or Custom
** Valid only when PV Type = NaoH, HCl, 0-25% H2So4, or Custom
*** Valid only when Temp comp type = Linear
**** Valid only when PV Type = Custom
*. Valid only when PV Sensor Type = Toroidal
*.. Valid only when PV Type = Conductivity or Resistivity

**FIGURE 9-2. 5081-C-HT HART/Model 375 Menu Tree (4 of 4)**

5081CT-FF 375 Menu Tree

-----------------------

- RESo u RCE
  - identification
    - MANu FACT_id
    - d EV_TYPE
    - d EV_REV
    - d d _REV
    - Characteristics Block Tag
    - TAG_d ESC
    - Hardware Revision
    - Software Revision String
    - Private Label d istributor
    - Final Assembly Number
    - o utput Board Serial Number
    - iTK_VER
  - Status
    - BLo CK_ERR
    - RS_STATE
    - FAu LT_STATE
    - Summary Status
    - Mo d E_BLK: Actual
    - Mo d E_BLK: Target
    - ALARM_Su M: Current
    - ALARM_Su M: u nacknowledged
    - ALARM_Su M: u nreported
    - d etailed Status
  - Process
    - Mo d E_BLK.Actual
    - Mo d E_BLK.Target
    - Mo d E_BLK.Permitted
    - STRATEGY
    - ALERT_KEY
    - SHEd _RCAS
    - SHEd _Ro u T
    - GRANT_d ENY: Grant
    - GRANT_d ENY: d eny
  - Alarms
    - WRiTE_PRi
    - Co NFiRM_TiME
    - LiM_No TiFY
    - MAX_No TiFY
    - FAu LT_STATE
    - SET_FSTATE [u ninitialized, o FF, SET]
    - CLR_FSTATE [u ninitialized, o ff, Clear]
    - ALARM_Su M: d isabled
    - ACK_o PTio N
  - Hardware
    - MEMo RY_SiZE
    - FREE_TiME
    - MiN_CYCLE_T
    - HARd _TYPES
    - NV_CYCLE_T
    - FREE_SPACE
  - o ptions
    - CYCLE_SEL
    - CYCLE_TYPE
    - FEATu RE_SEL
    - FEATu RES
    - d ownload Mode
    - WRiTE_Lo CK
    - Start With d efaults
    - Write Lock d efinition
  - Plantweb Alerts
    - Health index
    - Recommended Action
    - Fail Active
    - Fail Mask
    - Maintenance Active
    - Maintenance Mask
    - Advisory Active
    - Advisory Mask
  - Methods
    - Master reset
    - Self test
    - d d Version info
- TRANSd u CER
  - Status
    - Mo d E_BLK: Actual

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (1 of 10)**

    - Transducer Error
    - ST_REV
    - BLo CK_ERR
    - Additional transmitter status
    - Fault history 0
    - Fault history 1
    - Fault history 2
  - Block Mode
    - Mo d E_BLK: Actual
    - Mo d E_BLK: Target
    - Mo d E_BLK: Permitted
    - STRATEGY
    - ALERT_KEY
    - Characteristics Block Tag
    - TAG_d ESC
  - Measurements
    - Prim Val Type
    - Primary Val: Primary Val
    - Primary Val: Status
    - Primary Value Range: Eu at 100%
    - Primary Value Range: Eu at 0%
    - Secondary variable: Value
    - Secondary variable: Status
    - Raw RTd o hms
    - Raw PV: Raw PV
    - Raw PV: Status
    - Conductance
  - Calibration
    - PV Cal
    - Sensor Zero
    - SV Cal
    - Calibrate Meter
  - Configuration
    - Change PV Type
    - Sensor type conductivity
    - Prim Val Type
    - Conductivity unit
    - d iagnostic override
    - Calibration Parameters
      - Cell constant
      - Conductance offset
      - Solution/Conductivity offset
      - input cal factor
      - Temperature calibration offset
      - Snsr Cal Meth
      - Snsr Cal d ate
    - Temperature Compensation
      - Secondary value units
      - Sensor temperature compensation
      - Sensor temp manual value
      - Temp comp type
      - Temperature slope
      - Raw RTd ohms
      - Sensor type temp
    - Custom Curve
    - Reset transducer/Load factory defaults
  - identification
    - Software revision level
    - Hardware revision level
    - Lo i security code
    - Sensor S/N
    - Final assembly number
  - Ai blocks simulation
- Ai1
- Ai2
- Ai3
  - Quick Config
    - Ai Channel
    - L_TYPE
    - Xd _SCALE: Eu at 100%
    - Xd _SCALE: Eu at 0%
    - Xd _SCALE: u nits index
    - Xd _SCALE: d ecimal
    - o u T_SCALE: Eu at 100%
    - o u T_SCALE: Eu at 0%
    - o u T_SCALE: u nits index
    - o u T_SCALE: d ecimal
  - Common Config
    - ACK_o PTio N
    - ALARM_HYS

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (2 of 10)**

- ALERT_KEY
  - Hi_Hi_LiM
  - Hi_Hi_PRi
  - Hi_LiM
  - Hi_PRi
  - io _o PTS
  - L_TYPE
  - Lo _Lo _LiM
  - Lo _Lo _PRi
  - Lo _LiM
  - Lo _PRi
  - Mo d E_BLK: Target
  - Mo d E_BLK: Actual
  - Mo d E_BLK: Permitted
  - Mo d E_BLK: Normal
  - o u T_SCALE: Eu at 100%
  - o u T_SCALE: Eu at 0%
  - o u T_SCALE: u nits index
  - o u T_SCALE: d ecimal
  - PV_FTiME
- Advanced Config
  - Lo W_Cu T
  - SiMu LATE: Simulate Status
  - SiMu LATE: Simulate Value
  - SiMu LATE: Transducer Status
  - SiMu LATE: Transducer Value
  - SiMu LATE: Simulate En/d isable
  - ST_REV
  - STATu S_o PTS
  - STRATEGY
  - Xd _SCALE: Eu at 100%
  - Xd _SCALE: Eu at 0%
  - Xd _SCALE: u nits index
  - Xd _SCALE: d ecimal
- i/o References
  - Ai Channel
- Connectors
  - o ut: Status
  - o ut: Value
- o nline
  - BLo CK_ERR
  - FiELd _VAL: Status
  - FiELd _VAL: Value
  - Mo d E_BLK: Target
  - Mo d E_BLK: Actual
  - Mo d E_BLK: Permitted
  - Mo d E_BLK: Normal
  - o ut: Status
  - o ut: Value
  - PV: Status
  - PV: Value
- Status
  - BLo CK_ERR
- o ther
  - TAG_d ESC
  - GRANT_d ENY: Grant
  - GRANT_d ENY: d eny
  - u Pd ATE_EVT: u nacknowledged
  - u Pd ATE_EVT: u pdate State
  - u Pd ATE_EVT: Time Stamp
  - u Pd ATE_EVT: Static Rev
  - BLo CK_ALM: u nacknowledged
  - BLo CK_ALM: Alarm State
- All
  - Characteristics: Block Tag
  - ST_REV
  - TAG_d ESC
  - STRATEGY
  - ALERT_KEY
  - Mo d E_BLK: Target
  - Mo d E_BLK: Actual
  - Mo d E_BLK: Permitted
  - Mo d E_BLK: Normal
  - BLo CK_ERR
  - PV: Status
  - PV: Value
  - o ut: Status
  - o ut: Value
  - SiMu LATE: Simulate Status
  - SiMu LATE: Simulate Value

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (3 of 10)**

SiMu LATE: Transducer Status
SiMu LATE: Transducer Value
SiMu LATE: Simulate En/d isable
Xd _SCALE: Eu at 100%
Xd _SCALE: Eu at 0%
Xd _SCALE: u nits index
Xd _SCALE: d ecimal
o u T_SCALE: Eu at 100%
o u T_SCALE: Eu at 0%
o u T_SCALE: u nits index
o u T_SCALE: d ecimal
GRANT_d ENY: Grant
GRANT_d ENY: d eny
io _o PTS
STATu S_o PTS
Ai Channel
Lo W_Cu T
PV_FTiME
FiELd _VAL: Status
FiELd _VAL: Value
u Pd ATE_EVT: u nacknowledged
u Pd ATE_EVT: u pdate State
u Pd ATE_EVT: Time Stamp
u Pd ATE_EVT: Static Rev
u Pd ATE_EVT: Relative index
BLo CK_ALM: u nacknowledged
BLo CK_ALM: Alarm State
BLo CK_ALM: Time Stamp
BLo CK_ALM: Subcode
BLo CK_ALM: Value
ALARM_Su M: u nacknowledged
ALARM_Su M: u nreported
ALARM_Su M: d isabled
ACK_o PTio N
ALARM_HYS
Hi_Hi_PRi
Hi_Hi_LiM
Hi_PRi
Hi_LiM
Lo _PRi
Lo _LiM
Lo _Lo _PRi
Lo _Lo _LiM
Hi_Hi_ALM: u nacknowledged
Hi_Hi_ALM: Alarm State
Hi_Hi_ALM: Time Stamp
Hi_Hi_ALM: Subcode
Hi_Hi_ALM: Value
Hi_ALM: u nacknowledged
Hi_ALM: Alarm State
Hi_ALM: Time Stamp
Hi_ALM: Subcode
Hi_ALM: Float Value
Lo _ALM: u nacknowledged
Lo _ALM: Alarm State
Lo _ALM: Time Stamp
Lo _ALM: Subcode
Lo _ALM: Float Value
Lo _Lo _ALM: u nacknowledged
Lo _Lo _ALM: Alarm State
Lo _Lo _ALM: Time Stamp
Lo _Lo _ALM: Subcode
Lo _Lo _ALM: Float Value
Alarm output: Status
Alarm output: Value
Alarm select
Stdd ev
Cap Stdd ev

Pid 1
- Quick Config
  - ALERT_KEY
  - Co NTRo L_o P
  - d V_Hi_LiM
  - d V_Lo _LiM
  - GAiN
  - Hi_Hi_LiM
  - Hi_LiM
  - Lo _LiM
  - Lo _Lo _LiM
  - o u T_SCALE: Eu at 100%

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (4 of 10)**

- ouT_SCALE: Eu at 0%
- ouT_SCALE: units index
- ouT_SCALE: decimal
- PV_SCALE: Eu at 100%
- PV_SCALE: Eu at 0%
- PV_SCALE: units index
- PV_SCALE: decimal
- RESET
- SP: Status
- SP: Value
- SP_Hi_LiM
- SP_Lo_LiM

Common Config

- ALARM_HYS
- ALERT_KEY
- CoNTRoL_oPTS
- dV_Hi_LiM
- dV_Lo_LiM
- GAiN
- Hi_Hi_LiM
- Hi_LiM
- Lo_LiM
- Lo_Lo_LiM
- ModE_BLK: Target
- ModE_BLK: Actual
- ModE_BLK: Permitted
- ModE_BLK: Normal
- ouT_Hi_LiM
- ouT_Lo_LiM
- ouT_SCALE: Eu at 100%
- ouT_SCALE: Eu at 0%
- ouT_SCALE: units index
- ouT_SCALE: decimal
- PV_FTiME
- PV_SCALE: Eu at 100%
- PV_SCALE: Eu at 0%
- PV_SCALE: units index
- PV_SCALE: decimal
- RATE
- RESET
- SP: Status
- SP: Value
- SP_Hi_LiM
- SP_Lo_LiM

Advanced Config

- BK_CAL_HYS
- FF_GAiN
- FF_SCALE: Eu at 100%
- FF_SCALE: Eu at 0%
- FF_SCALE: units index
- FF_SCALE: decimal
- SHEd_oPT
- SP_RATE_dN
- SP_RATE_uP
- ST_REV
- STATuS_oPTS
- STRATEGY
- TRK_SCALE: Eu at 100%
- TRK_SCALE: Eu at 0%
- TRK_SCALE: units index
- TRK_SCALE: decimal
- TRK_VAL: Status
- TRK_VAL: Value

Connectors

- BK_CAL_iN: Status
- BK_CAL_iN: Value
- BK_CAL_ouT: Status
- BK_CAL_ouT: Value
- CAS_iN: Status
- CAS_iN: Value
- FF_VAL: Status
- FF_VAL: Value
- iN: Status
- iN: Value
- ouT: Status
- ouT: Value
- TRK_iN_d: Status
- TRK_iN_d: Value
- TRK_VAL: Status
- TRK_VAL: Value

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (5 of 10)**

- o nline
  - BK_CAL_iN: Status
  - BK_CAL_iN: Value
  - BK_CAL_o u T: Status
  - BK_CAL_o u T: Value
  - BLo CK_ERR
  - BYPASS
  - CAS_iN: Status
  - CAS_iN: Value
  - FF_VAL: Status
  - FF_VAL: Value
  - GAiN
  - iN: Status
  - iN: Value
  - Mo d E_BLK: Target
  - Mo d E_BLK: Actual
  - Mo d E_BLK: Permitted
  - Mo d E_BLK: Normal
  - o u T: Status
  - o u T: Value
  - PV: Status
  - PV: Value
  - RCAS_iN: Status
  - RCAS_iN: Value
  - RCAS_o u T: Status
  - RCAS_o u T: Value
  - Ro u T_iN: Status
  - Ro u T_iN: Value
  - Ro u T_o u T: Status
  - Ro u T_o u T: Value
  - SP: Status
  - SP: Value
  - TRK_iN_d : Status
  - TRK_iN_d : Value
  - TRK_VAL: Status
  - TRK_VAL: Value
- Status
  - BLo CK_ERR
- o ther
  - TAG_d ESC
  - BAL_TiME
  - GRANT_d ENY: Grant
  - GRANT_d ENY: d eny
  - u Pd ATE_EVT: u nacknowledged
  - u Pd ATE_EVT: u pdate State
  - u Pd ATE_EVT: Time Stamp
  - u Pd ATE_EVT: Static Rev
  - u Pd ATE_EVT: Relative index
  - BLo CK_ALM: u nacknowledged
  - BLo CK_ALM: Alarm State
  - BLo CK_ALM: Time Stamp
  - BLo CK_ALM: Subcode
  - BLo CK_ALM: Value
  - ALARM_Su M: Current
  - ALARM_Su M: u nacknowledged
  - ALARM_Su M: u nreported
  - ALARM_Su M: d isabled
  - ACK_o PTio N
  - Hi_Hi_ALM: u nacknowledged
  - Hi_Hi_ALM: Alarm State
  - Hi_Hi_ALM: Time Stamp
  - Hi_Hi_ALM: Subcode
  - Hi_Hi_ALM: Float Value
  - Hi_ALM: u nacknowledged
  - Hi_ALM: Alarm State
  - Hi_ALM: Time Stamp
  - Hi_ALM: Subcode
  - Hi_ALM: Float Value
  - Lo _ALM: u nacknowledged
  - Lo _ALM: Alarm State
  - Lo _ALM: Time Stamp
  - Lo _ALM: Subcode
  - Lo _ALM: Float Value
  - Lo _Lo _ALM: u nacknowledged
  - Lo _Lo _ALM: Alarm State
  - Lo _Lo _ALM: Time Stamp
  - Lo _Lo _ALM: Subcode
  - Lo _Lo _ALM: Float Value
  - d V_Hi_ALM: u nacknowledged
  - d V_Hi_ALM: Alarm State

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (6 of 10)**

dV_Hi_ALM: Time Stamp
dV_Hi_ALM: Subcode
dV_Hi_ALM: Float Value
dV_Lo_ALM: unacknowledged
dV_Lo_ALM: Alarm State
dV_Lo_ALM: Time Stamp
dV_Lo_ALM: Subcode
dV_Lo_ALM: Float Value
Bias
Error
SP Work
SP FTime
mathform
structreconfig
uGamma
uBeta
ideadBand
Stddev
Cap Stddev

All

Characteristics: Block Tag
ST_REV
TAG_dESC
STRATEGY
ALERT_KEY
ModE_BLK: Target
ModE_BLK: Actual
ModE_BLK: Permitted
ModE_BLK: Normal
BLoCK_ERR
PV: Status
PV: Value
SP: Status
SP: Value
ouT: Status
ouT: Value
PV_SCALE: Eu at 100%
PV_SCALE: Eu at 0%
PV_SCALE: units index
PV_SCALE: decimal
ouT_SCALE: Eu at 100%
ouT_SCALE: Eu at 0%
ouT_SCALE: units index
ouT_SCALE: decimal
GRANT_dENY: Grant
GRANT_dENY: deny
CoNTRoL_oPTS
STATuS_oPTS
iN: Status
iN: Value
PV_FTiME
BYPASS
CAS_iN: Status
CAS_iN: Value
SP_RATE_dN
SP_RATE_uP
SP_Hi_LiM
SP_Lo_LiM
GAiN
RESET
BAL_TiME
RATE
BK_CAL_iN: Status
BK_CAL_iN: Value
ouT_Hi_LiM
ouT_Lo_LiM
BKCAL_HYS
BK_CAL_ouT: Status
BK_CAL_ouT: Value
RCAS_iN: Status
RCAS_iN: Value
RouT_iN: Status
RouT_iN: Value
SHEd_oPT
RCAS_ouT: Status
RCAS_ouT: Value
RouT_ouT: Status
RouT_ouT: Value
TRK_SCALE: Eu at 100%
TRK_SCALE: Eu at 0%

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (7 of 10)**

TRK_SCALE: u nits index
TRK_SCALE: d ecimal
TRK_iN_d : Status
TRK_iN_d : Value
TRK_VAL: Status
TRK_VAL: Value
FF_VAL: Status
FF_VAL: Value
FF_SCALE: Eu at 100%
FF_SCALE: Eu at 0%
FF_SCALE: u nits index
FF_SCALE: d ecimal
FF_GAiN
u Pd ATE_EVT: u nacknowledged
u Pd ATE_EVT: u pdate State
u Pd ATE_EVT: Time Stamp
u Pd ATE_EVT: Static Rev
u Pd ATE_EVT: Relative index
BLo CK_ALM: u nacknowledged
BLo CK_ALM: Alarm State
BLo CK_ALM: Time Stamp
BLo CK_ALM: Sub Code
BLo CK_ALM: Value
ALARM_Su M: Current
ALARM_Su M: u nacknowledged
ALARM_Su M: u nreported
ALARM_Su M: d isabled
ACK_o PTio N
ALARM_HYS
Hi_Hi_PRi
Hi_Hi_LiM
Hi_PRi
Hi_LiM
Lo _PRi
Lo _LiM
Lo _Lo _PRi
Lo _Lo _LiM
d V_Hi_PRi
d V_Hi_LiM
d V_Lo _PRi
d V_Lo _LiM
Hi_Hi_ALM: u nacknowledged
Hi_Hi_ALM: Alarm State
Hi_Hi_ALM: Time Stamp
Hi_Hi_ALM: Subcode
Hi_Hi_ALM: Float Value
Hi_ALM: u nacknowledged
Hi_ALM: Alarm State
Hi_ALM: Time Stamp
Hi_ALM: Subcode
Hi_ALM: Float Value
Lo _ALM: u nacknowledged
Lo _ALM: Alarm State
Lo _ALM: Time Stamp
Lo _ALM: Subcode
Lo _ALM: Float Value
Lo _Lo _ALM: u nacknowledged
Lo _Lo _ALM: Alarm State
Lo _Lo _ALM: Time Stamp
Lo _Lo _ALM: Subcode
Lo _Lo _ALM: Float Value
d V_Hi_ALM: u nacknowledged
d V_Hi_ALM: Alarm State
d V_Hi_ALM: Time Stamp
d V_Hi_ALM: Subcode
d V_Hi_ALM: Float Value
d V_Lo _ALM: u nacknowledged
d V_Lo _ALM: Alarm State
d V_Lo _ALM: Time Stamp
d V_Lo _ALM: Subcode
d V_Lo _ALM: Float Value
Bias
Error
SP Work
SP FTime
mathform
structreconfig
u Gamma
u Beta
id eadBand

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (8 of 10)**

Stdd ev
Cap Stdd ev
Scheduling
d etail
Physical d evice Tag
Address
d evice id
d evice Revision
Advanced
Stack Capabilities
FasArTypeAndRoleSupported
Maxd isapAddressesSupported
Maxd icepAddressesSupported
d icepd eliveryFeaturesSupported
Versiono fNmSpecSupported
AgentFunctionsSupported
FmsFeaturesSupported
Basic Characteristics
Version
BasicStatisticsSupportedFlag
d io peratFunctionalClass
d id eviceConformance
Basic info
SlotTime
Perd ipduPhio verhead
MaxResponsed elay
ThisNode
ThisLink
MininterPdud elay
TimeSyncClass
PreambleExtension
PostTransGapExtension
MaxinterChanSignalSkew
Basic Statistics
Not Supported!
Finch Statistics 1
Last Crash d escription
Last RestartReason
Finch Rec Errors
Finch FCS Errors
Finch Rec Ready Errors
Finch Rec FiFo o verrun Errors
Finch Rec FiFo u nderrun Errors
Finch Trans FiFo o verrun Errors
Finch Trans FiFo u nderrun Errors
Finch Count Errors
Finch Cd Errors
Cold Start Counts
Software Crash Counts
Spurious Vector Counts
Bus/Address Error Counts
Program Exit Counts
Finch Statistics 2
Scheduled Events
Missed Events
Max Time Error
Mid Violations
Schedule Resync
Token d elegation Violations
Sum o f All Time Adjustments
Time Adjustments
Time u pdates o utside of K
d iscontinuous Time u pdates
Queue o verflow Statistics 1
Time Available
Normal
u rgent
Time Available Rcv
Normal Rcv
u rgent Rcv
Time Available SAP EC d C
Normal SAP EC d C
u rgent SAP EC d C
Time Available Rcv SAP EC d C
Normal Rcv SAP EC d C
u rgent Rcv SAP EC d C
Queue o verflow Statistics 2
Time Available SAP SM
Time Available Rcv SAP SM
Normal SAP Las

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (9 of 10)**

Normal Rcv SAP Las
Time Available SAP Src Sink
Normal SAP Src Sink
u rgent SAP Src Sink
Time Available Rcv SAP Src Sink
Normal Rcv SAP Src Sink
u rgent Rcv SAP Src Sink
Sys Q
Link Master Parameters
d imeLinkMasterCapabilitiesVariable
PrimaryLinkMasterFlagVariable
Booto peratFunctionalClass

NumLasRoled eleg/Claim/d elegTokenHoldTimeout
Link Master info
MaxSchedulingo verhead
d efMinTokend elegTime
d efTokenHoldTime
TargetTokenRotTime
LinkMaintTokHoldTime
Timed istributionPeriod
MaximuminactivityToClaimLasd elay
Lasd atabaseStatusSpdud istributionPeriod
Current Link Settings
SlotTime
Perd ipduPhio verhead
MaxResponsed elay
Firstu npolledNodeid
ThisLink
MininterPdud elay
NumConsecu npolledNodeid
PreambleExtension
PostTransGapExtension
MaxinterChanSignalSkew
TimeSyncClass
Configured Link Settings
SlotTime
Perd ipduPhio verhead
MaxResponsed elay
Firstu npolledNodeid
ThisLink
MininterPdud elay
NumConsecu npolledNodeid
PreambleExtension
PostTransGapExtension
MaxinterChanSignalSkew
TimeSyncClass

**FIGURE 9-3. 5081-C-FF Model 375 Menu Tree (10 of 10)**

# SECTION 10.0
# DIAGNOSIS AND TROUBLESHOOTING

## 10.1 OvERvIEw

The Model 5081-C transmitters automatically monitor for fault conditions. The diagnose Menu allows the current variable settings to be reviewed and shows fault messages indicating problems detected. Figure 10-1 illustrates the relationship between the diagnose Menu and its sub-menus. The mnemonics are defined in Table 10-1.

### 10.1.1 TROUBLESHOOTING

**Step 1** Look for a diagnostic fault message on the display to help pinpoint the problem. Refer to Table 10-2 for an explanation of the message and a list of the possible problems that triggered it.

**Step 2** Refer to the Quick Troubleshooting Guide, Table 10-3, for common loop problems and the recommended actions to resolve them.

**Step 3** Follow the step-by-step troubleshooting flow chart, offered in Figure 10-5, to diagnose less common or more complex problems.

### 10.1.2 DISPLAyING DIAGNOSTIC vALUES

The diAG key on the iRC is used to access the diagnosis Menu. The menu flow is shown in Figure 10-2 and the mnemonics are defined in Table 10-1.

The **FAuLtS** sub-menu can be entered to show the last three faults/warnings. The most recent is displayed first; NEXT scrolls through the remaining faults. Pressing EXiT clears all fault/warnings and returns the **FAuLtS** segment. disconnecting the transmitter removes all fault messages from memory. The **nonE** message is displayed when no faults/warnings have occurred.

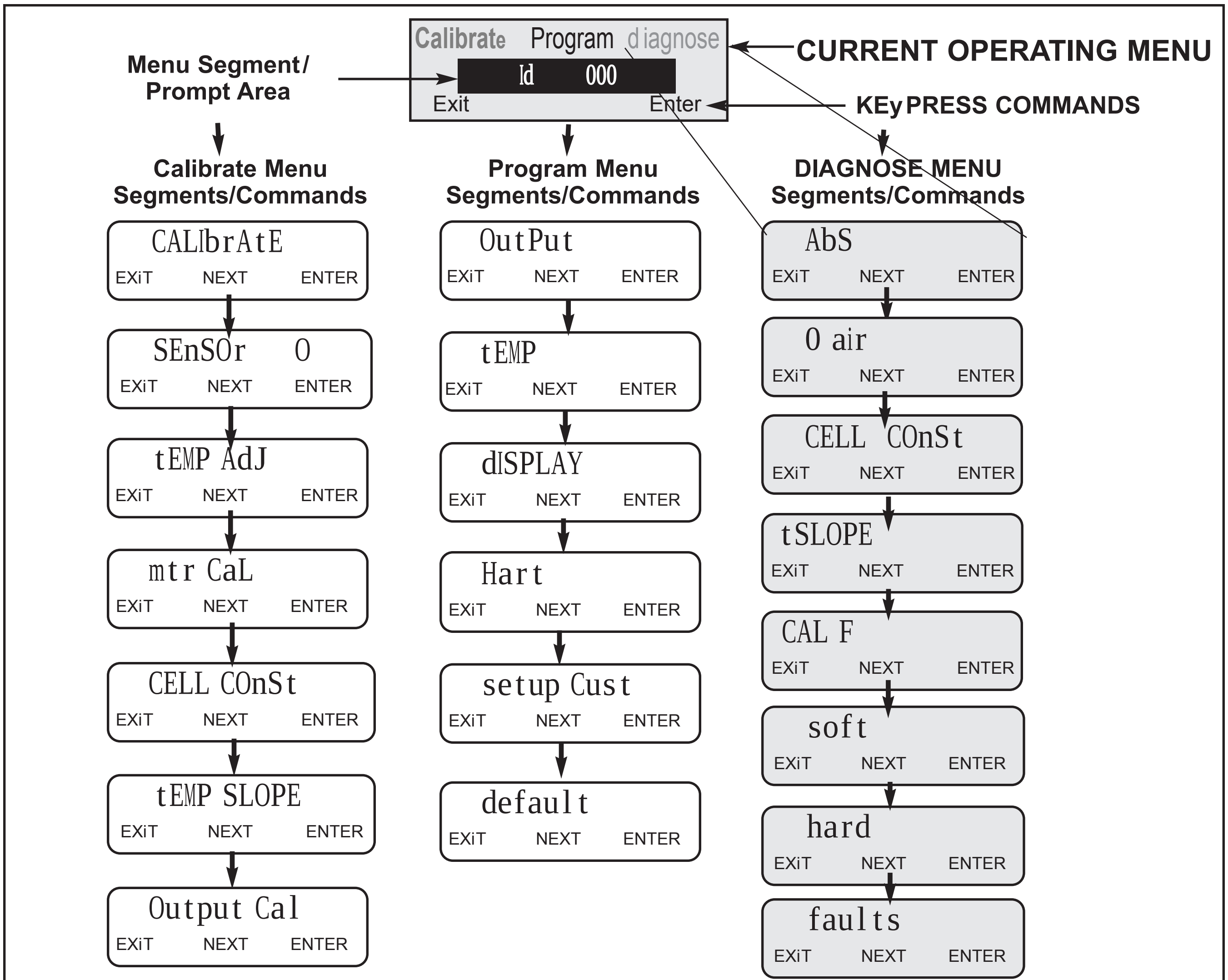



**FIGURE 10-1. Diagnose Menu Segments**

**TABLE 10-1. Diagnostic variables Mnemonics**

| | |
|---|---|
| AbS | Absolute conductivity (μS/cm or mS/cm) |
| 0 air | Sensor zero in air |
| CELL Const | Sensor cell constant (used in C mode) |
| tSLOPE | Temperature slope in %/ °C |
| CAL f | Calibration factor |
| soft | Software version |
| Hard | Hardware version |
| faults | Show fault messages |
| nonE | No fault messages in memory |

## 10.2 FAULT CONDITIONS

Three classes of error conditions/problems are detected and differentiated between by the diagnostic program. System disabling problems are faults caused by failures in the loop or significant variations in the process. System non-disabling problems are warnings and deal with input or A to d conversion settings. The third class of detected problems are error messages and occur when the calibration limits are exceeded.

### 10.2.1 DISABLING FAULTS

1. Both FAu LT and Ho Ld annunciation fields will become active (see Figure 10-3).
2. The process variable will flash at the rate of 1 second o N and 1 second o FF.
3. The appropriate fault message alternates with the normal Temperature/Current output display (see Figure 10-2).
4. The output current loop will be forced to the non-zero fault value entered in Step 7 of Section 4.2 or held at last value if fault value=0, if the transmitter is not in the TEST, Ho Ld , or Multidrop operational modes.
5. A 0-1 mA output signal is available for external use when system disability conditions are active. These conditions drive this output to 1 mA. Please contact factory for specific application information.

### 10.2.2 NON- DISABLING wARNINGS

When a **non-system-disabling** condition occurs, a warning message is displayed. The process variable does not flash. The appropriate message alternates with the Temperature/Current output display (see Figure 10-3).

if more than one fault exists, the display will sequence through each diagnostic message. This will continue until the cause of the fault has been corrected.




FIGURE 10-2. Disabling Fault Annunciation




FIGURE 10-3. warning Annunciation

## 10.3 DIAGNOSTIC MESSAGES

The Model 5081-C transmitters' diagnostics constantly monitor the conductivity loop for possible problems. if an operational problem is encountered, check the display for a fault or error message. These are displayed in the Temperature/Current output segment of the display. Note the message and refer to Table 10-2 for a description of possible problems that may have triggered the diagnostic message.

**TABLE 10-2. Diagnostic Fault Messages.**

| Message | Description | Action |
|---|---|---|
| **Faults** | | |
| tEMP LO | Temperature is too low. | Check wiring or sensor/process temp. Check RTd . |
| tEMP HI | Temperature is too high. | Check wiring or sensor/process temp. Check RTd . |
| Rtd FAIL | The RTd sense line fault limits have been exceeded for the sensor. | Check wiring or Check Program/Temp menu setting to verify the 100-3 or 100-4 sensor type connected. |
| CPU FAIL | The CPu has failed during RAM or EEPRo M verification. | Recycle. if persistent contact the factory. |
| FACt FAIL | The transmitter has not been accurately factory calibrated. | Contact factory. |
| rOM FAIL | The PRo M failed the check-sum test. | Contact factory. |
| CYCLE PWJr | A wrong value was detected during power-up. | Recycle the power. |
| **warnings** | | |
| InPut WJArn | The compensated conductivity limit of 9999 ms/cm is exceeded. | Verify the conductivity range setting. |
| Over rAngE | The current range setting has been exceeded. | Verify the 4 and 20 mA settings in the Program/output menu. |
| AdC error | An analog to digital conversion error has occurred. (This may come up normally while readings are changing quickly) | Recycle the power. |
| **Errors** | | |
| CAL Err or Offset Err | A calibration error has occurred between the standard and process. | Press RESET and repeat. Check calibration standards and unit configuration. |
| tSLOPE Err | The limit for T-2 in a two point calibration has been exceeded. | Press RESET and repeat the calibrate/temp. slope menu setting. |
| -0- Err | Sensor Zero limit has been exceeded | Press RESET and repeat the calibrate/sensor menu setting. |
| WjRITE Err | An attempt to the write on the EEPRo M has failed. | The jumper JP-1 on the CPu board has been removed. |

## 10.4 QUICK TROUBLESHOOTING GUIDE

Table 10-3 identifies some of the more common symptoms and suggests actions to help resolve a problem. in general, wiring is the most common cause.

**TABLE 10-3. Quick Troubleshooting Guide.**

| SyMPTOM | ACTION |
|---|---|
| Wrong temperature reading.<br>Suspected temp. compensation problem. | Perform a temperature standardization. Verify sensor's RTd.<br>Resistance vs. temp.; see Section 8.6 Temperature is out of range of sensor.<br>Check wiring. |
| display segments missing. display inoperable. | Replace display board. |
| Analyzer locks up; won't respond. | Replace PCB stack<br>Press Reset.<br>Check batteries in iRC. |
| Erratic displays. | Check sensors in process. |
| Transmitter won't respond to iRC key presses. | Verify and clean ribbon cable connection on CPu board. Check batteries in iRC. |
| Key press gives wrong selection. | Replace iRC. Check ribbon cable connection on CPu board. |
| Wrong or no current output. | Verify that output is not being overloaded; remove load; replace PCB stack. |
| No display or indicators. | Replace PCB stack. |
| ”Excess input”<br>“Reverse input” | Check sensor wiring.<br>Perform sensor zero. |
| “Check sensor zero” | Analyzer will not zero. Place sensor in air and access zero routine. |

### 10.4.1 FIELD TROUBLESHOOTING

When it is apparent by grab sample analysis that the transmitter is giving inaccurate readings, the following procedure should be followed.

A. The sensor surfaces need to be totally wetted by the process and air bubbles must no be trapped in the vicinity of the electrodes. if air bubbles are found, the installation technique should be altered to eliminate this source of error.

B. A quick visual inspection of the installation may identify the problem. Check to be sure that the transmitter is mounted securely and that its internal parts are properly connected. Next check all input and output wiring.

C. if the previous two steps did not indicate the source of the problem, the next step is to isolate the problem to either the sensor or the transmitter.

d. The first step in troubleshooting the sensor is to disconnect it from the transmitter, remove the sensor from the process and thoroughly dry the sensor electrodes. Refer to sensor manual for additional troubleshooting checks.

E. To troubleshoot the transmitter independently of the sensor, use an appropriate resistor across the temperature input connectors and connect the conductivity inputs to resistance decade box. Refer to Figure 10-7 to reference the conductivity simulation values.

## 10.5 SySTEMATIC TROUBLESHOOTING

if the Quick Troubleshooting Guide does not resolve the error, try the step-by-step approach offered in Figure 10-4.

**Step 1** Follow the troubleshooting flow chart.

**Step 2** Refer to the tests and instructions indicated by the flow chart to diagnose the problem.

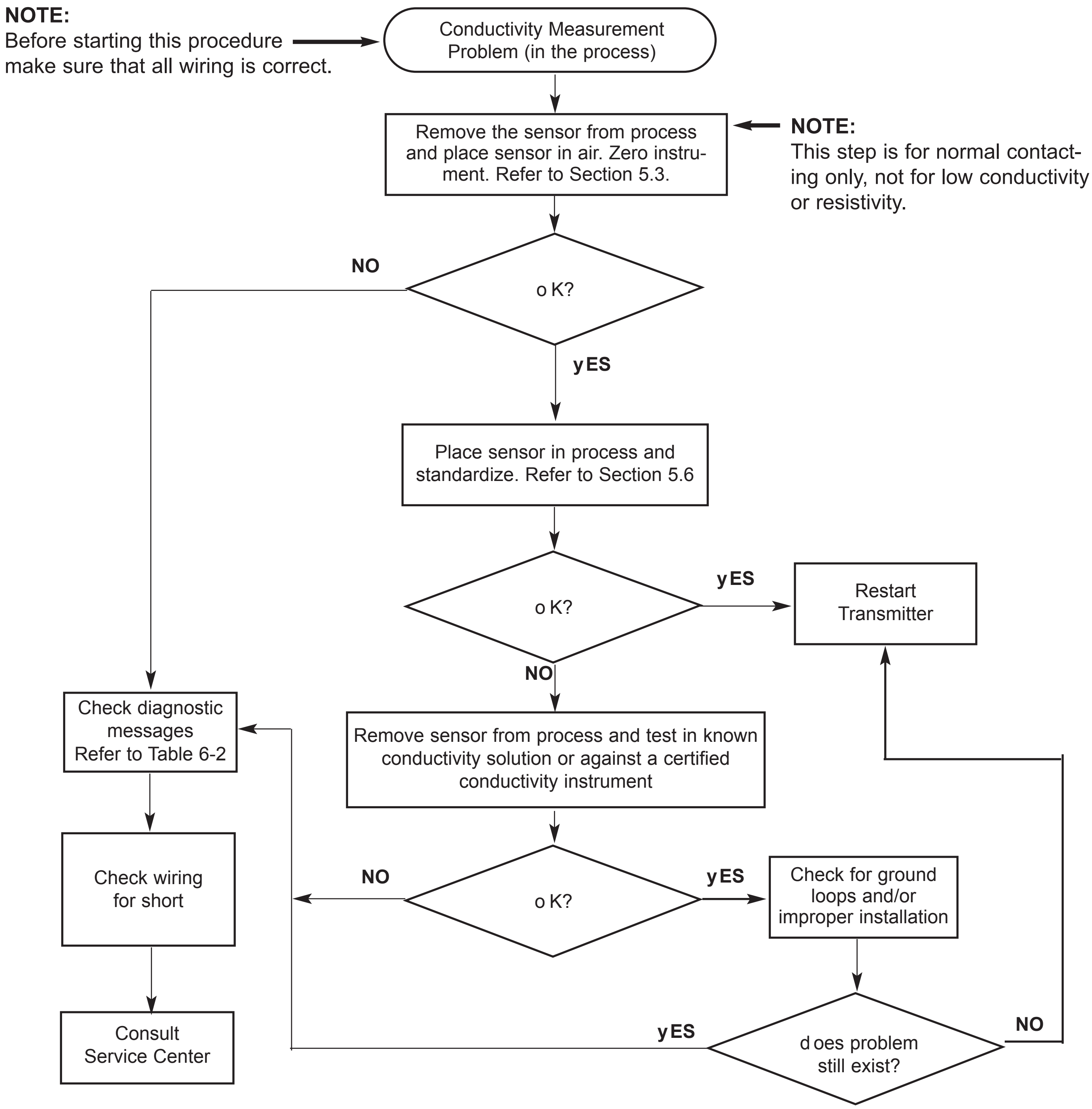



**FIGURE 10-4. Troubleshooting Flow Chart**

## 10.6 RTD RESISTANCE vALUES

Table 10-4 is a ready reference of RTd resistance values at various temperatures. These are used for test and evaluation of the sensor.

**NOTE**

Resistance values are read across the RTd element and are based on the manufacturer's stated values (±1%). Allow enough time for the RTd element in the sensor to stabilize to the surrounding temperature (10 min).

**Table 10-4. RTD Resistance values.**

| Temperature (°C) | Pt-100 Resistance (ohms) | Pt-1000 Resistance (ohms) |
|---|---|---|
| 0 | 100.00 | 1000 |
| 10 | 103.90 | 1039 |
| 20 | 107.79 | 1078 |
| 25 | 109.62 | 1096 |
| 30 | 111.67 | 1117 |
| 40 | 115.54 | 1155 |
| 50 | 119.40 | 1194 |
| 60 | 123.24 | 1232 |
| 70 | 127.07 | 1271 |
| 80 | 130.89 | 1309 |
| 90 | 134.70 | 1347 |
| 100 | 138.50 | 1385 |

use the following formula to determine the appropriate resistance value to use to simulate a conductivity value:

**FORMULA:**

$$\frac{\text{cell constant value x 1,000,000}}{\text{desired simulated conductivity in } \mu\text{s/cm}} = \text{resistance in ohms}$$

**ExAMPLE:**

$$\frac{.01 \text{ x } 1{,}000{,}000}{10\ \mu\text{s/cm}} = \text{use 1,000 ohm resistance}$$

**FIGURE 10-5. Conductivity Determination.**

## 10.7 wARNING AND FAULT MESSAGES

The Model 5081-A transmitter continuously monitors the sensor and transmitter for conditions that cause erroneous measurements. When a problem occurs, the transmitter displays either a warning or fault message. A warning alerts the user that a potentially disabling condition exists. There is a high probability that the measurement is in error. A fault alerts the user that a disabling condition exists. if a fault message is showing, all measurements should be regarded as erroneous.

**w hen a wARNING condition exists:**

1. The main display remains stable; it does not flash.
2. A warning message appears alternately with the temperature and output readings in the second line of the display. See Section 10.3 for an explanation of the warning messages and suggested ways of correcting the problem.

**w hen a FAULT exists:**

1. The main display flashes.
2. The words FAu LT and Ho Ld appear in the main display.
3. A fault message appears alternately with the temperature and output readings in the second line of the display. See Section 10.3 for an explanation of the fault messages and suggested ways of correcting the problem.
4. The output current will remain at the present value or go to the programmed fault value. See Section 7.2 for details on how to program the current generated during a fault condition.
5. if the transmitter is in Ho Ld when the fault occurs, the output remains at the programmed hold value. To alert the user that a fault exists, the word FAu LT appears in the main display, and the display flashes. A fault or diagnostic message also appears.
6. if the transmitter is simulating an output current when the fault occurs, the transmitter continues to generate the simulated current. To alert the user that a fault exists, the word FAu LT appears in the display, and the display flashes.

## 10.8 TROUBLESHOOTING wHEN A FAULT OR wARNING MESSAGE IS SHOwING

| Message | Explanation | See Section |
|---|---|---|
| **OuEr rAnGE** | over range, measurement exceeds display limit | 10.8.1 |
| **SEnSor FAIL** | Bad sensor, sensor current is a large negative number | 10.8.2 |
| **CAL Error** | Calibration error, sensitivity (nA/ppm) is too high or too low | 10.8.3 |
| **nEEd 0 CAL** | Sensor needs re-zeroing, reading is too negative | 10.8.4 |
| **rtd FAIL** | Bad temperature reading | 10.8.5 |
| **TEMP HI** | Temperature reading exceeds 275°C when auto temp is selected | 10.8.5 |
| **TEMP LO** | Temperature reading is less than -25°C when auto temp is selected | 10.8.5 |
| **SenSE OPEn** | Sense line is not connected | 10.8.6 |
| **OFFSEt Err** | Zero offset during standardization exceeds programmed limit | 10.8.7 |
| **FACt FAIL** | unit has not been factory-calibrated | 10.8.8 |
| **CPU FAIL** | internal CPu tests have failed | 10.8.9 |
| **ROM FAIL** | internal memory has failed | 10.8.9 |
| **AdC Error** | Analog to digital conversion failed | 10.8.10 |

### 10.8.1 OuEr rAnGE and AMP FAIL.

These error messages appear if the sensor current is too high. Normally, excessive sensor current implies that the sensor is miswired or the sensor has failed.

1. Verify that wiring is correct and connections are tight. Be sure to check connections at the junction box if one is being used. See Section 3.0.
2. Replace the sensor membrane and electrolyte solution and clean the cathode if necessary. See the sensor instruction sheet for details.
3. Replace the sensor.

### 10.8.2 SEnSor FAIL.

Bad sensor means that the sensor current is a large negative number.

1. **SEnSor FAIL** may appear for a while when the sensor is first placed in service. observe the sensor current (go to **SEnSor Cur** under the diagnostic menu). if the sensor current is moving in the positive direction, there is probably nothing wrong and the error message should soon disappear.
2. Verify that wiring is correct. Pay particular attention the anode and cathode connections.
3. Verify that the transmitter is configured for the correct measurement. Configuring the measurement sets (among other things) the polarizing voltage. Applying the wrong polarizing voltage to the sensor can cause a negative current.
4. Replace the sensor membrane and electrolyte solution and clean the cathode if necessary. See the sensor instruction sheet for details.
5. Replace the sensor.

### 10.8.3 CAL Error

At the end of the calibration step, the transmitter calculates the sensitivity in nA/ppm. if the sensitivity is outside the range normally expected, the transmitter displays the **CAL Error** message and the transmitter does not update the calibration. For assistance, refer to the troubleshooting section specific for the sensor.

### 10.8.4 nEEd 0 CAL

**nEEd 0 CAL** means that the concentration of the analyte is too negative.

1. Check the zero current (go to **0 CurrEnt** under the diagnostic menu). if the zero current is appreciably greater than the measurement current, the **nEEd 0 CAL** warning will appear.
2. Verify that the zero current is close to the value given in the calibration section for the analyte being determined.
3. Rezero the sensor. Refer to the calibration and troubleshooting sections for the sensor for more information.

### 10.8.5 rtd FAIL, TEMP HI, and TEMP LO

These messages usually mean that the RTd is open or shorted or there is an open or short in the connecting wiring.

1. Verify all wiring connections, including wiring in a junction box if one is being used.
2. disconnect the RTd iN, RTd SENSE, and RTd RETuRN leads or the thermistor leads at the transmitter. Be sure to note the color of the wire and where it was attached. Measure the resistance between the RTd iN and RETuRN leads. For a thermistor, measure the resistance between the two leads. The resistance should be close to the value in the table in Section 16.12. if the temperature element is open or shorted, replace the sensor. in the meantime, use manual temperature compensation.

### 10.8.6 SenSE OPEn

Most Rosemount Analytical sensors use a Pt100 or Pt1000 in a three-wire configuration. The in and return leads connect the RTd to the measuring circuit in the analyzer. A third wire, called the sense line, is connected to the return lead. The sense line allows the analyzer to correct for the resistance of the in and return leads and to correct for changes in lead wire resistance with changes in ambient temperature.

1. Verify all wiring connections, including wiring in a junction box if one is being used.
2. disconnect the RTd SENSE and RTd RETuRN wires. Measure the resistance between the leads. it should be less than 5 Ω. if the sense line is open, replace the sensor as soon as possible.
3. The transmitter can be operated with the sense line open. The measurement will be less accurate because the transmitter can no longer compensate for lead wire resistance. However, if the sensor is to be used at approximately constant ambient temperature, the lead wire resistance error can be eliminated by calibrating the sensor at the measurement temperature. Errors caused by changes in ambient temperature cannot be eliminated. To make the error message disappear, connect the RTd SENSE and RETuRN terminals with a jumper.

### 10.8.7 OFFSEt Err

The **OFFSEt Err** message appears if the zero offset (in mV) exceeds the programmed limit. Before increasing the limit to make the **OFFSEt Err** message disappear, check the following:

1. Verify that the reference meter is working properly and is properly calibrated.
2. Verify that the process sensor is working. Check its response in a solution of known conductivity.
3. if the transmitter is standardized against the conductivity determined in a grab sample, be sure to measure the conductivity before the temperature of the grab sample changes more than a few degrees.
4. Verify that the process sensor is fully immersed in the liquid. if the sensor is not completely submerged, it may not properly measure the conductivity of the process liquid.
5. Check the sensor for cleanliness. if the sensor looks fouled or dirty, clean it. Refer to the sensor instruction manual for cleaning procedures.

### 10.8.8 FACt FAIL

**FACt FAIL** means the unit has not been factory calibrated. Call the factory. The transmitter will probably need to be returned to the factory for calibration.

### 10.8.9 CPU FAIL and ROM FAIL

**CPU FAIL** means that the processing unit has failed internal tests. **ROM FAIL** means that the internal memory has failed.

1. Cycle the power. Leave the transmitter without power for at least 30 seconds before returning power to it.
2. if cycling the power fails to clear the error message, the CPu board probably needs replacing. Call the factory for assistance.

### 10.8.10 AdC Error

**AdC Error** means the analog to digital converter has failed.

1. Verify that sensor wiring is correct and connections are tight. Be sure to check connections at the junction box if one is being used. See Section 3.0.
2. d isconnect sensor(s) and simulate temperature and sensor input.
3. if the transmitter does not respond to simulated signals, the analog PCB has probably failed. Call the factory for assistance.

# SECTION 11.0
# MAINTENANCE

## 11.1 OvERvIEw

Maintenance consists of "Preventative" and "Corrective" measures.

## 11.2 PREvENTATIvE MAINTENANCE

**11.2.1 Transmitter Maintenance.** Transmitter maintenance consists of periodic calibration. A monthly calibration is a good starting maintenance schedule. This schedule can then be fine tuned to the site process.

**11.2.2 Sensor Maintenance.** Sensor maintenance consists of periodic cleaning of the electrode.

A weekly cleaning is a good starting maintenance schedule. This schedule can then be fine tuned to the site process.

**11.2.3 Initiating HOLD Function For Maintenance.** To place the transmitter into the Hold operational mode prior to servicing the sensor, press the **HOLD** key on the iRC (infrared remote control). The message field will respond with a message concerning the present hold condition. Press the iRC editing key to toggle to the **On** condition. Press ENTER to activate **HOLD** output.

Hold Mode will maintain the operating current output at the programmed value regardless of process changes. Refer to Section 4.2, step 4, for instructions on how to set this value.

Temperature/Current output segments change to indicate the current output level. See Figure 10-1.

The section of the LCd reserved for hold annunciation (Refer to Figure 11-1) will display **HOLD** when the transmitter is in the Hold Mode.

To return transmitter to normal operation, press **HOLD** on the iRC again to access the hold toggling function.

Always calibrate after cleaning or replacing the sensor.

Press the iRC editing key to toggle to the **OFF** condition. Press ENTER to disengage the **HOLD** output function.

## 11.3 CORRECTIvE MAINTENANCE

Refer to Figure 11-2 and Figure 11-3 for an exploded view of the 5081-C Transmitters.

Tables 11-1 and 11-2 list suggested spare parts along with part numbers. Sales and service locations are located on the back pages of this manual.

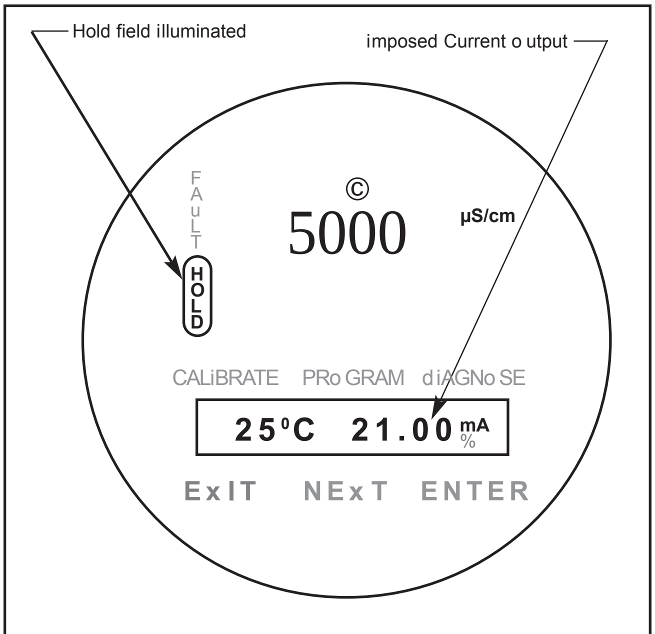



**FIGURE 11-1. Hold Annunciation**

### TABLE 11-1. Model 5081C Replacement Parts and Accessories

| Part # | d escription |
|---|---|
| 2002577 | Pipe Mounting Bracket |
| 23572-00 | infrared Remote Control |
| 23593-01 | Enclosure (Circuit End Cap) |
| 23652-01 | PCB (d isplay board) |
| 23992-04 | PCB Stack, 5081-C-HT (Fact Cal ) w/o d isplay (CPu and Analog boards) |
| 23992-05 | PCB Stack, 5081-C-FF (Fact Cal ) w/o d isplay (CPu and Analog boards) |
| 33360-00 | Enclosure (Body), Housing With Glass |
| 33337-02 | Terminal Block |
| 33362-00 | Enclosure Cover (Terminal End Cap) |
| 9550187 | o -Ring, Front / Rear Cover |
| 33342-00 | Lock, Cover, Front (o rder P/N 33343-00 also) |
| 33343-00 | Locking Bracket Nut (o rder P/N 33342-00 also) |

# SECTION 12.0
# THEORy OF OPERATION

## 12.1 OvERvIEw

This section is a general description of how the Model 5081-C Transmitter operates. This section is for those users who desire a greater understanding of the transmitter's operation.

## 12.2 CONDUCTIvITy

The conductivity sensor produces a "conductance signal" that is proportional to the conductivity of the process solution. The transmitter subtracts a baseline zero conductivity signal from the sensor signal and multiplies the result by the cell constant and the cell factor. This absolute conductivity is then corrected to the reference temperature (usually 25°C) using the process temperature measured by a RTd located in the conductivity sensor. in the "n SALt", "CAtion" and "rStvty" modes, the Model 5081-C automatically calculates the amount of correction needed.

in conductivity mode "LinEAr", the microprocessor also adjusts the amount of correction required for temperature compensation by means of a temperature slope adjustment. This slope may be adjusted between 0 to 5%/°C either manually via the infrared Remote Control Keypad or automatically during bench or process calibration. This slope controls the amount of correction required in the temperature compensation circuit, and is specific to the process, giving you the most accurate conductivity reading possible.

## 12.3 HART COMMUNICATION

A Mo d AC (An application specific integrated Circuit) is connected across the current loop to read and transmit the superimposed HART communications. The transmitter communicates via the HART protocol which uses an industry standard BELL 202 frequency shift keying (FSK) technique. This FSK signal is an AC signal, whose frequency is shifted higher or lower, depending upon the condition of the digital signal (High or Low). This communication conforms to the Rosemount HART® specification and is used to configure and interrogate the transmitter.

## 12.4 OUTPUT LOGIC

Normal transmitter operation specifies that the output tracks the process. However, the transmitter can be put into other modes of operation.

These modes are:

**Fault Mode (in the event of a fault).** Sets the transmitter output to the value set during configuration. (Between 3.80 and 22.00mA). This mode is over-ridden by the **HOLD** or **TEST** modes.

**Hold Mode (manually placed in hold).** Holds the output current to the value set during configuration. This value may be between 3.80 and 22.00 mA.

Hold mode supersedes the fault mode value. The current output measurement is "Frozen" while the transmitter is in the Hold Mode.

**Test Mode (manually placed to test output).** Can only be accessed through the Program menu, and is only active during the time the prompt is visible.

o utput is set to the entered value and supersedes the Hold and Fault modes, if such exist.

Test mode also disables the normal timeout feature (2 minutes after the last keystroke is made) for 20 minutes.

**Timeout.** The display will normally timeout and default to the Main d isplay two (2) minutes after the last keystroke is made.

While the output is being tested, or if a 2-point calibration is being performed, the timeout is adjusted to 20 minutes.

if a custom curve is being programmed, no timeout will be applied.

# SECTION 13.0
# RETURN OF MATERIAL

### 13.1 GENERAL.

To expedite the repair and return of instruments, proper communication between the customer and the factory is important. Call 1-949-757-8500 for a Return Materials Authorization (RMA) number.

### 13.2 wARRANTy REPAIR.

The following is the procedure for returning instruments still under warranty:

1. Call Rosemount Analytical for authorization.
2. To verify warranty, supply the factory sales order number or the original purchase order number. in the case of individual parts or sub-assemblies, the serial number on the unit must be supplied.
3. Carefully package the materials and enclose your "Letter of Transmittal" (see Warranty). if possible, pack the materials in the same manner as they were received.
4. Send the package prepaid to:

   Emerson Process Management
   Rosemount Analytical
   2400 Barranca Parkway
   irvine, CA 92606

   Attn: Factory Repair

   RMA No. ____________

   Mark the package: Returned for Repair

   Model No. ____

### 13.1 NON-wARRANTy REPAIR.

The following is the procedure for returning for repair instruments that are no longer under warranty:

1. Call Rosemount Analytical for authorization.
2. Supply the purchase order number, and make sure to provide the name and telephone number of the individual to be contacted should additional information be needed.
3. d o Steps 3 and 4 of Section 13.2.

**NOTE**

Consult the factory for additional information regarding service or repair.

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# EC Declaration of Conformity

We, **Emerson Process Management, Blegistrasse 21, Barr, Switzerland CH 6341** declare under our sole responsibility that the product,

**Model 5081-C-HT-60 Contacting Conductivity Transmitter, HART;**
**Model 5081-C-FF-60 Contacting Conductivity Transmitter, Fieldbus;**
**Model 5081-C-FI-60 Contacting Conductivity Transmitter, FISCO**

manufactured by, **Emerson Process Management, Rosemount Analytical**
**2400 Barranca Parkway, Irvine, California 92606 USA**

to which this declaration relates, is in conformity with the provisions of the European Community directives, including the latest amendments, as shown below.

Assumption of conformity is based on the application of the harmonized standards.

(signature)

Vice President Analytical Europe
(function name printed)

Andy Kemish
(name printed)

October 1, 2012
(date of issue)

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## EMC Directive (2004/108/EC)

**Model 5081-C-HT-60 Contacting Conductivity Transmitter, HART;**
**Model 5081-C-FF-60 Contacting Conductivity Transmitter, Fieldbus;**
**Model 5081-C-FI-60 Contacting Conductivity Transmitter, FISCO**
**Harmonized standard used: EN 61326-1: 2006**

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Analytical

# EC Declaration of Conformity

We, **Emerson Process Management, Blegistrasse 21, Barr, Switzerland CH 6341** declare under our sole responsibility that the product,

**Model 5081-C-HT-73 Contacting Conductivity Transmitter, HART;**
**Model 5081-C-FF-73 Contacting Conductivity Transmitter, Fieldbus;**
**Model 5081-C-FI-73 Contacting Conductivity Transmitter, FISCO**

manufactured by, **Emerson Process Management, Rosemount Analytical**
**2400 Barranca Parkway, Irvine, California 92606 USA**

to which this declaration relates, is in conformity with the provisions of the European Community directives, including the latest amendments, as listed below.

Assumption of conformity is based on the application of the harmonized standards and, when applicable or required, a European Community notified body certification, as shown below.

(signature)

Vice President Analytical Europe
(function name printed)

Andy Kemish
(name printed)

October 2, 2012
(date of issue)

## EMC Directive (2004/108/EC)

**Model 5081-C-HT Contacting Conductivity Transmitter, HART;**
**Model 5081-C-FF Contacting Conductivity Transmitter, Fieldbus;**
**Model 5081-C-FI Contacting Conductivity Transmitter, FISCO**

**Harmonized standard used: EN 61326-1: 2006**

## ATEX Directive (94/9/EC)

**Provisions of the directive fulfilled by the equipment:**

**Equipment Group II, Category 1 G Ex ia IIC T4 Ga** ($-20^{\circ}C \leq Ta \leq +65^{\circ}C$)

**Model 5081-C-HT Contacting Conductivity Transmitter, HART;**
**Model 5081-C-FF Contacting Conductivity Transmitter, Fieldbus;**
**Model 5081-C-FI Contacting Conductivity Transmitter, FISCO**

**Baseefa03ATEX0099X -- Intrinsically Safe Certificate**
**Harmonized standards used: EN 60079-0:2009 EN 60079-11:2007**

**Special condition for safe use:**
**The apparatus enclosure may contain light metals. The apparatus must be installed in such a manner as to minimize the risk of impact or friction with other metal surfaces.**

**ATEX Notified Body for EC Type Examination Certificate & Quality Assurance:**
**Baseefa [Notified Body Number: 1180], Rockhead Business Park, Staden Lane Buxton, Derbyshire SK17 9RZ, United Kingdom**

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## wARRANTy

Goods and part(s) (excluding consumables) manufactured by Seller are warranted to be free from defects in workmanship and material under normal use and service for a period of twelve (12) months from the date of shipment by Seller. Consumables, pH electrodes, membranes, liquid junctions, electrolyte, o -rings, etc. are warranted to be free from defects in workmanship and material under normal use and service for a period of ninety (90) days from date of shipment by Seller. Goods, part(s) and consumables proven by Seller to be defective in workmanship and / or material shall be replaced or repaired, free of charge, F.o .B. Seller's factory provided that the goods, parts(s), or consumables are returned to Seller's designated factory, transportation charges prepaid, within the twelve (12) month period of warranty in the case of goods and part(s), and in the case of consumables, within the ninety (90) day period of warranty. This warranty shall be in effect for replacement or repaired goods, part(s) and consumables for the remaining portion of the period of the twelve (12) month warranty in the case of goods and part(s) and the remaining portion of the ninety (90) day warranty in the case of consumables. A defect in goods, part(s) and consumables of the commercial unit shall not operate to condemn such commercial unit when such goods, parts(s) or consumables are capable of being renewed, repaired or replaced.

The Seller shall not be liable to the Buyer, or to any other person, for the loss or damage, directly or indirectly, arising from the use of the equipment or goods, from breach of any warranty or from any other cause. All other warranties, expressed or implied are hereby excluded.

iN CoNSidERATioN oF THE STATEd PuRCHASE PRiCE oF THE GoodS, SELLER GRANTS oNLY THE ABoVE STATEd EXPRESS WARRANTY. No oTHER WARRANTiES ARE GRANTEd iNCLudiNG, BuT NoT LiMiTEd To, EXPRESS ANd iMPLiEd WARRANTiES oF MERCHANTABiLiTY ANd FiTNESS FoR A PARTiCuLAR PuRPoSE.

## RETURN OF MATERIAL

Material returned for repair, whether in or out of warranty, should be shipped prepaid to:

**Emerson Process Management**
**Rosemount Analytical**
**2400 Barranca Parkway**
**Irvine, CA 92606**

The shipping container should be marked:

Return for Repair
Model ________________________________

The returned material should be accompanied by a letter of transmittal which should include the following information (make a copy of the "Return of Materials Request" found on the last page of the Manual and provide the following thereon):

1. Location type of service, and length of time of service of the device.
2. description of the faulty operation of the device and the circumstances of the failure.
3. Name and telephone number of the person to contact if there are questions about the returned material.
4. Statement as to whether warranty or non-warranty service is requested.
5. Complete shipping instructions for return of the material.

Adherence to these procedures will expedite handling of the returned material and will prevent unnecessary additional charges for inspection and testing to determine the problem with the device.

if the material is returned for out-of-warranty repairs, a purchase order for repairs should be enclosed.

*The right people,*
*the right answers,*
*right now.*

ROSEMOUNT ANALYTICAL
CUSTOMER SUPPORT CENTER
**1-800-854-8257**

*ON-LINE ORDERING NOW AVAILABLE ON OUR WEB SITE*
http://www.raihome.com

*Specifications subject to change without notice.*

Credit Cards for u.S. Purchases only.


**Emerson Process Management**

2400 Barranca Parkway
irvine, CA 92606 uSA
Tel: (949) 757-8500
Fax: (949) 474-7250

http://www.raihome.com




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